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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 1 of 49

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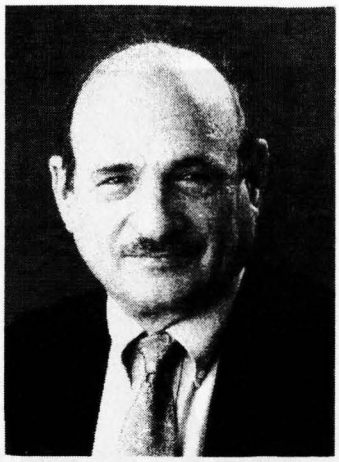
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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 2 of 49



General Chairman's Message

Welcome to the IEEE 53rd Vehicular Technology Conference. This conference has been organized by the VTS Israeli Chapter. Unfortunately, we could not host you in Israel, as we had originally planned. However, we trust that the facilities at Rodos Palace in the Island of Rhodes will prove to be an excellent replacement, adding the promise that we will invite you to a meeting in Israel for one of the near future VTCs.

As usual we are publishing both a CD-ROM and a hard copy book as conference proceedings. However, we have thought that time is ripe to deviate a little from the normal form. In the past the book was designed to follow the conference. As a result it was organized by the chronological order of the presentations. However, as the number of papers grew, the book became multi-volumes and heavy, with diminishing value as a companion to the flow of the conference. Also, as the book became optional, not every participant purchased the book. The conclusion from these observations is that the book makes more sense as a post-conference tool. This led to a new ordering of our book and CD-ROM. i.e., rather than by sessions, they are organized by topics.

In order to help the participant in the course of the conference we have extended the program by including short abstracts of the presentations. Naturally, these are organized by sessions. We hope you find these arrangements more beneficial.

I would like to take this opportunity and to thank all our volunteers, members of the Organizing committee, members of the Technical Program Committee and all others for their help and dedication. Without them there would be no conference.

As a plenary talk we have thought you might be interested in a new and novel idea, with interesting features, which is being considered for local wireless applications, with all its promises and perils. I am referring to UWB, which stands for Ultra Wide Band.

Reuven Meidan, Fellow, IEEE

General Chair, VTC 2001- Spring

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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 3 of 49

Table of Contens

1 Antennas and Propagation 1

11 Adaptive Antennas and Arrays 2

Comparison of Multiple Antenna Techniques for UMTS Downlink Capacity Enhancement 3
A. Alexiou
Lucent Technologies Optimus, UK

Novel Radiation Pattern by Genetic Algorithms in Wireless Communication 8
C. Chien-Ching, C. Chien-Hung
Tamkang University, China

The Performance of Multi-Element Antenna Systems in Freuency Selective Fading Environments 13
F. Choy 1, M. Cherniakov 2
1 Queensland University of Tecgnology, Australia
2 University of Birmingham, UK

Experimental Study of Adaptive Antennas for Handheld Terminal Applications 18
F. Choy 1, M. Cherniakov 2, J. Homer 3
1 Queensland University of Technology, Australia
2 The University of Birmingham, UK
3 University of Queensland, Australia

On Nonlinear Beamforming for Interference Cancellation 23
C. Xu, C. Law, S. Yoshida
Nanyang Technological University, Singapore

Joint Spatiotemporal Parameter Estimation for DS-CDMA System in Fast Fading Multipath Channel 28
Z. Gu, E. Gunawan, Z. Yu
Nanyang Technological University, Singapore

Distributed Versus Centralized Antenna Arrays in Broadband Wireless Neteworks 33
M. Clark, T. Willis, L. Greenstein, A. Rustako, V. Erceg, R. Roman
AT&T Labs-Research, USA

Adaptiva Antenna Arrays for Co-Channel Interference Cancellation in Space-time coded Systems 38
J. Li 1, K. Letaief 2, R. Cheng 2, Z. Cao 1
1 Tsinghua University, P.R. China
2 Hong Kong Univesity, Hong Kong

Beamforming Capacity and SNR Maximization for Multiple Antenna Systems 43
S. Jafar, A. Goldsmith
Stanford University, USA

Joint Angle of Arrival and Angle-Spread Estimation of Multiple Users Using an Antenna Array and a Modified MUSIC Algorithm 48
I. Jami, R. Ormondroyd
Royal Military College of Science, UK

Directional Power Based Admission Control for WCDMA Systems using Antenna Arrays 53
J. Ramiro-Moreno 1, K. Pedersen 2, P. Mogensen 2
1 Aalborg University, Denmark
2 Nokia Networks, Denmark

A Simple Downlink Antenna Array Algorithm Based on a Hybrid Scheme of Transmit Diversity and Conventional Beamforming 58
K. Pedersen, P. Mogensen
Nokia Networks, Denmark

Adaptive Low Profile Array Antennas for Smart Car Antenna Systems 63
R. Kronberger 1, H. Lindenmeier 2, L. Reiter 2, J. Hopf 2
1 Fuba Automotive, Germany
2 University of Bundeswehr Munich, Germany

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 4 of 49

A New Channel Estimation Method for RF Beamforming Implementable in Mobile Terminals 68
Y. Liang 1, F. Chin 1, A. Kot 2
1 Center for Wireless Communications, Singapore
2 School of EEE, Singapore
Asymptotically Optimal Open-Loop Space-Time Architecture Adaptive to Scattering Conditions 73
A. Lozano, F. Farrokhi, R. Valenzuela
Lucent Technologies Optimus, USA
Adaptive-Rank Receiver for Space-Time DS CDMA Systems 78
M. Nicoli, U. Spagnolini
D.E.I. Politecnico di Milano, Italy
Shift Invariance Algorithms for the Delay/Angle Estimation of Multipath 83
J. Picheral, U. Spagnolini
D.E.I. Politecnico di Milano, Italy
Impact of Adaptive Array Architectures on S-Aloha Protocol Performance 88
R. de Araujo 1, F. Cavalcanti 2, J. Mota 2
1 Institut National des Telecommunications, France
2 Federal University of Ceara DEE, Brazil
Wideband Dual-Polarized Base Station Antenna for GSM1800 and WCDMA UMTS 93
V. Voipio
Nokia Networks, Finland
Uniform Spherical Distributions for Adaptive Array Applications 98
J. Verhaevert, E. Van Lil, A. Van de Capelle
Adaptive Space-time Coding in Fading Channels 103
W. Tao, R. Cheng, K. Letaief
Hong Kong Univesity, Hong Kong
Adaptive MIMO Techniques for UTRA-TDD Mode 108
C. Degen, C. Walke, A. Lecomte, B. Rembold
RWTH Aachen University of Technology, Germany
Hybrid-Selection/Optimum Combining 113
J. Winters, M. Win
AT&T Labs-Research, USA
The EM Algorithm for DOA Estimation in IS-95 Reverse Link 118
R. Zelenovsky 1, M. Grivet 2
1 Institute Militar de Engenharia, Brasil
2 PUC/Rio, Brazil
Application of Music for Spatial Reference Beamforming for SDMA in a Smart Antenna for GSM and DECT 123
A. Margarita, S. Flores, L. Rubio, V. Almenar, J. Corral
Universidad Politecnica de Valencia, Spain
Convolutionally Coded Multi-Antenna Transmission in WCDMA Over Frequency-Selective Rayleigh Fading Channel 127
E. Kunnari, D. Tujkovic
Center for Wireless Communications, Finland
A Fast Tracking Method for Time-variant DOA of Signals 132
X. Su, X. Xu, Y. Yao
Tsinghua University, P.R. China
Multi-Input Multi-Output Maximum Likelihood Detection for a Wireless System 137
X. Zhu, R. Murch
Hong Kong University, Hong Kong
Performance Analysis of MIMO-MMSE-DFE Multiuser Receiver for TDMA Mobile Systems with Spatial Diversity 142
J. Hwang, C. Chen
Yuan-Ze University, Taiwan
Smart Antennas Performance Evaluation and Capacity Increase for WCDMA UMTS 147
R. Martinez, D. Trosa, L. Haro, M. Calvo
Universidad Politecnica de Madrid, Spain

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 5 of 49

Hopped Delay Diversity for EDGE 152
K. Kuchi 1, R. Pirhonen 1, R. Srinivasan 2
1 Nokia Research Center, USA
2 Lincom Wireless Communications, USA
A New Adaptive Downlink Beamforming Method for WCDMA System 157
D. Shim 1, F. Alam 2, B. Woerner 2
1 LG Eelectronics Inc., Korea
2 Virginia University, USA
Direction of Arrival Estimation Using Genetic Algorithms 162
P. Karamalis, A. Marousis, A. Kanatas, P. Constantinou
National Technical University of Athens, Greece
A Radio System with Multi-Element Antennas 167
V. Jungnickel, V. Pohl, U. Kruger, C. von Helmolt, T. Haustein, S. Stanczak
Heinrich-Hertz-Institut, Germany
Performance Analysis of Work-length Effect on the Hardware Design in MMSE/DD Space-Time Array Receiver 171
J. Lee, H. Oh, M. Kyeong
ETRI, Korea
RF Gain/Phase and I/Q Imbalance Error Correction Technique for Multi-channel Array Antenna Systems 175
H. Park, C. Park, H. Oh, M. Kyeong
ETRI, Korea
Real-Time Implementation of MMSE Adaptive Beamformer using Modified Systolic Array 180
J. Park, H. Oh, M. Kyeong
ETRI, Korea
A Novel Space-Time Pre-Multiuser Downlink Transmission Scheme Suitable for TDD-CDMA Systems 185
W. Wang, X. Wu, Q. Yin
Xi'an Jiaotong University, P.R. China
Block Based RLS Re-Spread Re-Spread Multitarget Array: Algorithm and Performance 190
Z. Du, P. Gong, W. Wu
Beijing University of Posts & Telecomm, P.R. China
Measurement of the Array- Antenna Directional Pattern and Bit Error Rate of Space-Time Equalizer 194
T. Toda, Y. Aihara, Y. Kamio
YRP Mobile Telecommunications, Japan
Exploiting the Data-Rate Potential of MIMO Channels: Multi-Stratum Space-Time Coding 199
U. Wachsmann, J. Thielecke, H. Schotten
Ericsson Eurolab, Germany
Measurement of the Capacity of MIMO Systems in Frequency-Selective Channels 204
A. Molisch 1, M. Steinbauer 2, M. Toeltsch 2, E. Bonek 2, R. Thoma 3
1 AT&T Labs-Research, USA
2 INTHF, Austria
3 IKM, Germany
Combined Channel-Modified Adaptive Array MMSE Canceller and Viterbi Equalizer 209
R. Friedman, Y. Bar-Ness
New Jersey Inst. Of Technology, USA
MIMO Measurement and Joint M-D Parameter Estimation of Mobile Radio Channels 214
A. Richter, D. Hampicke, G. Sommerkorn, R. Thoma
Ilmenau University of Technology, Germany
Adaptive Cell Sectorization for UMTS Third Generation CDMA Systems 219
R. Giuliano, F. Mazzenga, F. Vatalaro
Universita degli Studi di Roma 'Tor Vergata', Italy
Analysis of Surface Waves in Microstrip Array 224
M. Wnuk, W. Kolosowski, M. Amanowicz, R. Dufrene
Military University of Technology, Poland

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 6 of 49

New Antennas for Personal Communications 228
M. Wnuk, W. Kolosowski, M. Amanowicz
Military University of Technology, Poland
A Spatio-Temporal Channel Model for Position Location Techniques via AOA and TDOA 233
J. Kim, W. Chung
SungKyunKwan University, Korea
Feedback Schemes for FDD WCDMA Systems in Multipath Environments 238
J. Hamalainen 1, R. Wichman 2
1 Nokia Networks, Finland
2 Nokia Research Center, Finland
Soft Handoff Analysis of CDMA Systems using Novel Switched-Beam Smart Antennas with Polarization Diversity 243
W. Wang, I. Lu, S. Liu
Polytechnic University, USA
Effect of Mixer Phase Distortions on the DOA Tracking Algorithm for an Adaptive Antenna Array 248
W. Hou, H. Kwon
Wichita State University, USA
A Novel Polarization Smart Antenna 253
J. Shapira, S. Miller
Celletra Ltd., Israel
Transmission Considerations for Polarization-Smart Antennas 258
S. Miller, J. Shapira
Celletra Ltd., Israel
Interference Distributions in Mixed Service WCDMA Systems - Opportunities for Advanced Antenna Systems 263
J. Barta 1, M. Ericson 2, B. Goransson 2, B. Hagerman 2
1 Ericsson Research, Hungary
2 Ericsson Research, Sweden

12 Channel Measurement/Modeling/Prediction 268

On the Distribution of Relevant Radio Channel Figures in Different Propagation Environments for Performance Evaluation of WCDMA Systems 269
A. Alayon Glazunov, J. Berg
Ericsson Research, Sweden
Coupling at Cross, T and L Junctions in Tunnels and Urban Street Canyons 274
J. Lee, H. Bertoni
Polytechnic University, USA
A Statistical Approach to Bertoni-Walfisch Propagation Model for Mobile Radio Design in Urban Areas 279
I. Cavdar
Karadeniz Technical University, Turkey
Keyholes, Correlations and Capacities of Multi-element Transmit and Receive Antennas 284
D. Chizhik, G. Foschini, M. Gans, R. Valenzuela
Lucent Technologies, USA
BLAST Systems Capacity Measurments at 2.44 GHz in Suburban Outdoor Environment 288
M. Gans, N. Amitay, Y. Yeh, H. Xu, R. Valenzuela, T. Sizer, R. Storz, D. Taylor, W. MacDonald, C. Tran, A. Adamiecki
Lucent Technologies, USA
Effect of Channel Estimation on the Accuracy of the Capacity Estimation 293
P. Kyritsi 1, R. Valenzuela 2, D. Cox 1
1 Stanford University, USA
2 Lucent Technologies, USA
Propagation Study in Urban Environment at 25 and 40 GHz 298
N. Moraitis, P. Constantinou
National Technical University of Athens, Greece

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 7 of 49

On Modelling of Aggregated Teletraffic Using Generalized Fokker-Planck Equation 303
S. Primak 1, D. Makrakis 2, V. Lyandres 3
1 The University of Western Ontario, Canada
2 The University of Ottawa, Canada
3 Ben-Gurion University of The Negev, Israel
Shadow Fading Corelation Between Uplink and Downlink 309
E. Perahia 1, D. Cox 2
1 mDiversity Inc., USA
2 Stanford University, USA
Shadow Fading Cross Correlation Between Basestations 313
E. Perahia 1, D. Cox 2, S. Ho 1
1 mDiversity Inc., USA
2 Stanford University, USA
Correlation Control in the Multichannel Fading Simulators 318
T. Poutanen, J. Kolu
Electrobit Ltd., Finland
Outage Probabilities of Dual Selection Combiners in a Correlated Nakagami Fading with Cochannel Interference 323
J. Reig, N. Cardona, L. Rubio
Universidad Politecnica de Valencia, Spain
Radio Channel Measurements on an Eigth-Branch Indoor Office Distributed Antenena System 328
T. Sorensen 1, P. Mogensen 2
1 Aalborg University, Denmark
2 Nokia Networks, Denmark
Mobile Propagation Loss with a Low Base Station Antenna for NLOS Street Microcells in Urban Area 333
A. Tang, J. Sun, K. Gong
Tsinghua University, P.R. China
Measured Path Loss and Multipath Propagation Characteristics in UHF and Microwave Frequency Bands for Urban Mobile Communications 337
Y.Oda, R. Tsuchihashi, K. Tsunekawa, M. Hata
NTT Docomo Inc., Japan
Spatial Channel Model and Measurements for IMT-2000 Systems 342
M. Buehrer, S. Arunachalam, K. Wu, A. Tonello
Lucent Technologies Optimus, USA
Statistical Model of W-CDMA Signals Over Realistic Multipath Channel 347
D. Oh, G. Lee, D. Choi, C. Kim
Chonnam National University, Korea
Site-specific Simulation of Ship Safety/Surveillance Radars Operating in Harbour Environments 352
L. Valle, B. Cobo, I. Paez, R. Torres
Universidad de Cantabria, Spain
Impact of Shadowing Effect and its Countermeasure Methods for Wireless 1394 Home Network 357
T. Udagawa 1, H. Zhang 1, T. Arita 1, T. Nasu 2, M. Nakagawa 2
1 Telecommunications Advancement Organization, Japan
2 Keio Univtersity, Japan
The Verification of a Deterministic Spatio-Temporal Channel Modeling Approach by Applying a Deconvolution Technique in the Measurement 362
H. Zhu 1, J. Takada 2, T. Kobayashi 3
1 Nokia Research Center, Japan
2 Tokyo Institute of Technology, Japan
3 YRP Mobile Telecommunications, Japan
A Spatio-Temporal Ray Launching Propagation Model for UMTS Pico and Microcellular Environments 367
B. Lee, A. Nix, J. McGeehan
University of Bristol, UK

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 8 of 49

Analysis of the LS Estimation Error on a Rayleigh Fading Channel 372
T. Ekman
Uppsala University, Sweden
Intelligent Base Station Hand-Over Algorithms Based upon a Precise Power Drop Model 377
M. Dohler, A. Marbini, H. Aghvami
King's College London, UK
Design and Simulation of a Vector Channel Sounder for UMTS 382
A. Marousis, P. Karamalis, A. Kanatas, P. Constantinou
National Technical University of Athens, Greece
Neural Networks Applications for the Prediction of Propagation Path Loss in Urban Environments 387
I. Popescu 1, I. Nafornita 2, P. Constantinou 3, A. Kanatas 3, N. Moraitis 3
1 University of Oradea, Romania
2 Technical University of Timisoara, Romania
3 National Technical Univesity of Athens, Greece
Predicting Multi-Element Receive &Transmit Array Capacity Outdoors with Ray Tracing 392
J. Ling, D. Chizhik, R. Valenzuela
Lucent Technologies, USA
Microwave Path-loss Characteristics in Urban LOS and NLOS Environments 395
H. Masui 1, M. Ishii 1, K. Sakawa 1, H. Shimizu 1, T. Kobayashi 1, M. Akaike 2
1 YRP Mobile Telecommunications, Japan
2 Science University of Tokyo, Japan
Spatial Characterization of Urban Mobile Radio Channels 399
M. Toeltsch 1, J. Laurila 3, A. Molisch 1, K. Kalliola 2,3, P. Vainikainen 2, E. Bonek 1,4
1 Technische Universitat Wien, Austria
2 Helsinki University of Technology, Finland
3 NRC, Finland
4 FTW, Austria
Low Complexity Channel Estimation for the WB-CDMA Terminal 404
E. Batut, M. Arndt
FT R&D DIH/OCF, France
A Mixed-Cell Propagation Model for Interfernce Prediction in a UMTS Network 409
E. Tameh, A. Nix
University of Bristol, UK
A Novel Approach to the Modelling of Natural Surface Scattering for 3D Channel Prediction 414
M. Pettersen 1, G. Stette 1, J. Noll 2
1 Norwegian University, Norway
2 Telenor Resrarch and Development, Norway
Channel Estimation for EGPRS Modems 419
E. Yakhnich
Comsys Communication and Signal Processing Ltd., Israel
An Indoor IS-2000 Transmit Diversity Evaluation using Propagation Measurements 423
G. Messier, W. Krzymien
TRLabs, Canada
A Field Prediction Model for Urban Environment Based on Pattern Recognition and Statistical Ray Tracing 428
V. Degli-Esposti, A. De'Marsi, F. Fuschini
University of Bologna, Italy
Implementation Techniques of Broadband Radio Channel Simulators 433
T. Jamsa, T. Poutanen, J. Meinila
Electrobit Ltd., Finland

13 Indoor Propagation 438

Propagation of Millimetric Waves in Rough Sidewals Mining Environment 439
M. Ndoh, G. Delisle
Laval University, Canada

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 9 of 49

Effects of Human Shadowing, Traffic and Antenna Movements on 62.4GHz Indoor RLAN's Channels 444
A. Siamarou, M. Al-Nuaimi
University of Glamorgan, UK
Wideband Propagation Measurements for Indoor Rician Fading Radio Channels at 62.4GHz 449
A. Siamarou, M. Al-Nuaimi
University of Glamorgan, UK
Multipath Delay Spread and Signal Level Measurements for Indoor Wireless Radio Channels at 62.4GHz 454
A. Siamarou, M. Al-Nuaimi
University of Glamorgan, UK
Performance Improvement of Wireless 1394 Using Multiple-Element Antenna System 459
H. Zhang 1, T. Udagawa 1, T. Arita 1, K. Kobayashi 2, M. Nakagawa 1,2
1 Telecommunications Advancement Organization, Japan
2 Keio University, Japan
A Multi-Wall-and-Floor Model for Indoor Radio Propagation 464
M. Lott 1, I. Forkel 2
1 Siemens AG, Germany
2 RWTH Aachen, Germany
Accuracy Analysis of GO/UTD Radio Channel Modelling in Indoor Scenarios Including Cross-Polarization 469
S. Loredo, L. Valle, I. Paez, R. Torres
Universidad de Cantabria, Spain
Site-Specific BER Similation for Indoor Wireless Communications 474
R. Torres, B. Manteca, S. Loredo, L. Valle
Universidad de Cantabria, Spain
Feasibility Study for Wireless Data Transmission inside Space Platforms 479
M. Domingo, R. Torres
Universidad de Cantabria, Spain
Analysis and Measurement of EM Field Distribution in Area Where DECT System Works 484
W. Kolosowski, M. Wnuk, G. Rozanski
Military University of Technology, Poland

2 Wireless Access 489

21 Multiple Access Technology 490

Pre-Selection Based Reduced-Complexity MLMUD for DS-CDMA Systems 491
E. Al-Susa, D. Cruickshank
The University of Edinburgh, UK
Throughput Analysis of Strongly Interfering Slow Frequency-Hopping Wireless Networks 496
F. Floren 1, A. Stranne 1, O. Edfors 1, B. Molin 2
1 Lund University, Sweden
2 Axis Communications AB, Sweden
Performance of VSG-CDMA and MC-CDMA in Multirate Systems 501
Z. Guo, K. Letaief
Hong Kong University, Hong Kong
Admission Control and Adaptive CDMA for Interated Voice and Data Services 506
X. Tang 1, A. Goldsmith 2
1 U.C. Berkeley, USA
2 Stanford University, USA
An Enhanced Adaptive Time Slot Assignment using access statistics in TD/CDMA TDD system 511
S. Park, M. Kim, N. Kim
Ewha Women's University, Korea
A New Access Scheme for Common Packet Channel in W-CDMA System 517
J. So, D. Cho
KAIST, Korea

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 10 of 49

Influence of System Load on Channel Estimation in an MC-CDMA Mobile Radio Communication System 522
T. Salzer, D. Mottier, L. Brunel
Mitsubishi Electric ITE, France
Optimal Linear Multiuser Receiver in DS-CDMA System 527
W. Wang, Z. Xu, X. Wu, Q. Yin
Xi'an Jiaotong University, P.R. China
Performance Analysis of the Random Access Channel (RACH) in WCDMA 532
I. Vukovic, T. Brown
Motorola Inc., USA
Erlang Capacity of Multiclass CDMA Cellular System 537
J. Castaneda-Camacho, D. Lara-Rodriguez
CINVESTAV-IPN, Mexico
Non-Linear Multiuser Detection for Circuit-Switched and Packet-Switched Integrated CDMA Systems 541
S. Sfar, K. Letaief, R. Murch
Hong Kong University, Hong Kong
Adaptive Multicode CDMA for Uplink Throughput Maximization 546
S. Jafar, A. Goldsmith
Stanford University, USA
System Level Interference Mitigation Schemes in EGPRS: Mode-0 and Scheduling 551
*K. Balachandran 1, K. Chang 2, *W. Luo 1, S. Nanda 3*
1 Lucent Technologies, USA
2 Coree Networks, USA
3 Narad Networks, USA
Joint Control of Slot Assignments and Traffic Policing in Wireless Packet Switched Netwoks 556
D. Lee, C. Chou
National Tsing Hua University, Taiwan
Enhanced Channel Access Techniques for Wireless Multimedia Terminals 561
A. Iera 1, A. Modafferi 1, G. Aiello 1, A. Molinaro 2, S. Marano 3
1 D.I.M.E.T.-University of Reggio Calabria, Italy
2 university of Messina, Italy
3 University of Calabria, Italy
Broadband Packet Wireless Access Appropriate for High-speed and High-capacity Throughput 566
H. Atarashi, S. Abeta, M. Sawahashi
NTT Docomo Inc., Japan
ML Estimation and Correction of Frequency Offset for MC-CDMA Systems over Fading Channels 571
Q. Tian, K. Letaief
1 Purdue University, USA
2 Hong Kong University, Hong Kong
Performance Evalation of CDMA/PRMA Techniques for LEO Constellations 576
N. Batsios, I. Tsetsinas, F. Pavlidou
Aristotle University of Thessaloniki, Greece

22 Spread Spectrum Technology 581

A Frequency Domain Error Analysis for Channel Estimation with Variable Averaging Interval 582
D. Xiaojian, Y. Xiaohu
Southeast University, P.R. China
DS-CDMA and Adaptive Modulation Based TDMA Dual Mode Scheme for High Speed Data Transmission Service in Wireless Multimedia Communication Systems 585
T. Inoue, S. Sampei, N. Morinaga
Osaka University, Japan
A Simple Method to Calculate the Error Probability for 2d Rake Receivers 590
A. Poloni, U. Spagnolini
D.E.I. Politecnico di Milano, Italy

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 11 of 49

Impact of Reconstruction Error Using Canonical Channel Representation in Direct-Spread Systems 595
J. Hkegard
SINTEF Telecom and Information, Norway
Optimization of Spread Spectrum Characteristics from Channel Measurements 599
M. Lienard, V. Degardin, P. Degauque
University of Lille, France
Adaptive Multiuser Receiver Using a Support Vector Machine Technique 604
S. Chen, A. Samingan, L. Hanzo
University of Southampton, UK
VSB Wideband CDMA for Overlay System and its Implementation 609
D. Kim 1, D. Roh 2, Y. Choi 1, S. Kwon 1, M. Lee 1
1 Yonsei University, Korea
2 LG Information & Communications, LTD., Korea
Multiple Access Interference Cancellation in Fading Multipath Channels: Progress and Limitations 614
J. Andrews, T. Meng
Stanford University, USA
Blind Space-Time Rake Structure Based on Second Order Statistics for DS-CDMA 618
R. Piechocki, N. Canagarajah, J. McGeehan
University of Bristol, UK
Modified Leaky LMS Algorithm for Channel Estimation in DS-CDMA Systems 623
S. Jo 1, J. Choi 2, Y. Lee 2
1 Samsung Electronics Co. Ltd., Korea
2 KAIST, Korea
A 2 IR: An Asynchronous and Adaptive Hybrid ARQ scheme for 3G Evolution 628
A. Das, F. Khan, S. Nanda
Lucent Technologies, USA
Using Multi-Level QAM Modulation in CDMA System 632
Y. Wei, E. Tiedemann, F. Ling, S. Sarkar
QUALCOMM Inc., USA
Generation Verification and Assignment of Hopping Channels to VHF Combat Nets 637
J. Pawelec 1, T. Szymczyk 2, R. Piotrowski 2
1 Univresity of Technology, Poland
2 Defence Communication Inst., Poland

23 OFDM 642

Receiver Architectures for FMT Broadband Wireless Systems 643
N. Benvenuto, S. Tomasin, L. Tomba
University of Padova/DEI, Italy
A Constrained Approach to Pre-Equalization for TDD OFDM Systems 648
M. Butler, P. Fletcher, A. Nix, D. Bull
University of Bristol, UK
Channel Estimation Versus Equalization in an OFDM WLAN System 653
S. Boumard, A. Mammela
VTT Electronics, Finland
A New Class of Signal Processing Schemes for Bandwidth-eeficient OFDM Transmission with Low Envelope Fluctuation 658
R. Dinis, A. Gusmao
Instituto Superior Tecnico, Portugal
Performance Evaluation of a Signal Processing Scheme for Multicarrier Transmission with Quasi-constant Envelope 663
R. Dinis, A. Gusmao
Instituto Superior Tecnico, Portugal
A Study of the Performance of Hiperlan/2 and IEEE 802.11a Physical Layers 668
A. Doufexi, S. Armour, M. Butler, A. Nix, D. Bull
University of Bristol, UK

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 12 of 49

Impact of the Channel Estimation onto the BER-Performance of PSAM-OFDM Systems in Mobile Radio Channels 673
I. Gaspard
T-Nova Deutsche Telekom Inn., Germany
A Fine Frequency and Fine Sample Clock Estimation Technique for OFDM Systems 678
S. Duncan, R. Heaton, B. Hodson
Mitsubishi Electric VIL, UK
A Pilot-Signal Assisted Channel Estimation Scheme for Multi-Carrier Modulation 683
O. Muta, Y. Akaiwa
Kyushu University, Japan
Wavelet Based OFDM for Wireless Channels 688
B. Negash, H. Nikookar
Delf University, The Netherlands
Transmitter Impairments in OFDM-Based Wireless LAN 692
M. Pauli 1, U. Wachsmann 1, M. Sundelin 2, P. Schramm 1
1 Ericsson Eurolab, Germany
2 Ericsson Radio Systems AB, Germany
Performance of DMT Systems in Dispersive Channels with Correlated Impulsive Noise 697
G. Pay, M. Safak
Hacettepe University, Turkey
Blind Estimation of Time and Frequency Offset for PCC-OFDM 702
J. Shentu, J. Armstrong
La Trobe University, Australia
Improved Adaptive Downlink for OFDM/SDMA-Based Wireless Networks 707
S. Thoen, L. Van der Perre, M. Engels
IMEC, Belgium
A Joint Estimation Algorithm of Symbol Timing and Carrier Offset in OFDM Systems 712
J. Wu, Q. Zhou, K. Cheng
Hong Kong University, Hong Kong
Channel Estimator for OFDM Systems with 2-Dimensional Filtering in the Transform Domain 717
C. Wong, C. Law, Y. Guan
Nanyang Technological University, Singapore
Analysis of the Demodulation Techniques for OFDM Signals under Correlated Rayleigh Fading 722
L. Wan, V. Dubey
Nanyang Technological University, Singapore
High Bit Rate Transmission Scheme with a Multilevel Transmit Power Control for the OFDM Based Adaptive Modulation Systems 727
T. Yoshiki, S. Sampei, N. Morinaga
Osaka University, Japan
TCM, TTCM, BICM and Iterative BICM Assisted OFDM-based Digital Video Broadcasting to Mobile Receivers 732
C. Lee, S. Ng, L. Piazzo, L. Hanzo
Univ. of Southampton, UK
Analysis of Nonlinear Effects in OFDM Communications Systems 737
N. Ermolova
Helsinki Univrsity of Technology, Finland
A Novel Partial Sampling MMSE Receiver for Uplink Multi-Carrier CDMA 741
P. Zong, K. Wang, Y. Bar-Ness
New Jersey Inst. of Technology, USA
Joint Adaptive Power Control and Detection in OFDM/SDMA Wireless LANs 746
J. Li 2, K. Letaief 1, R. Cheng 1, Z. Cao 2
1 Hong Kong University, Hong Kong
2 Tsinghua University, P.R. China
Performance of a Modified ATDMA Protocol Carrying Mixed Traffic Over an Indoor Wireless System using OFDM 751
C. Lokuge, A. Coulson
Industrial Research Limited, New Zealand

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 13 of 49

New OFDM Peak-to-Average Power Reduction Scheme 756
J. Armstrong
La Trobe University, Australia
An Investigation of Peak to Average Power Ratio in MC-CDMA Combined with Partial Transmit Sequence 761
N. Ruangsurat 1, R. Rajatheva 2
1 Sonera Corporation, Finland
2 SAT/Asian Institute of Tech., Thailand
Throughput Performance of WLANs Operating at 5GHz Based on Link Simulations with Real and Statical Channels 766
A. Doufexi 1, S. Armour 1, P. Karlsson 2, A. Nix 1, D. Bull 1
1 University of Bristol, UK
2 Telia Research AB, Sweden
Software-Defined Radio Based Baseband Discrete Model for Orthogonal Frequency Division Multiplexing CDMA Systems 771
X. Wu, B. Jiang, Q. Yin
Xi'an Jiaotong University, P.R. China
Concatenated Space-Time Block Coded and Turbo Coded Symbol-by-Symbol Adaptive OFDM and Multi-Carrier CDMA Systems 776
B. Choi, T. Liew, L. Hanzo
Univrsity of Southampton, UK
Comparative Study of Concatenated Turbo Coded and Space-Time Block Coded as well as Space-Time Trellis Coded OFDM 781
T. Liew, B. Choi, L. Hanzo
Univrsity of Southampton, UK
Design of a Turbo Coded OFDM-CDMA Transmitter-Receiver with QPSK Signal Mapping 786
T. Ginige, N. Rajatheva, K. Ahmed
SAT/Asian Institute of Tech., Thailand
Blind Joint Channel and Data Estimation for OFDM Signals in Rayleigh Fading 791
M. Chang, Y. Su
National Chiao Tung University, Taiwan
Optimal Weighting for ML Decoding of Convolution Code in COFDM Systems 796
J. Cho, C. Yoon, N. Cho, H. Jun, D. Hong
Yonsei University, Korea
A Low Complexity Multi-carrier BLAST Architecture for Realizing High Data Rates Over Dispersive Fading Channels 800
N. Boubaker, K. Letaief, R. Murch
Hong Kong University, Hong Kong
Performance of an OFDM Transceiver for Radio Transmission in Idustrial Multipath Environments 805
A. Koukourgiannis, A. Miaoudakis, G. Kalivas
University of Patras, Greece
DFT-based Channel Estimation in 2D-Pilot-Symbol-Aided OFDM Wireless Systems 810
M. Fernandez-Getino Garcia, J. Paez-Borrallo, S. Zazo
Universidad Politecnica de Madrid, Spain
Joint Channel Estimation and Peak-to-Average Power Reduction in Coherent OFDM: A Novel Approach 815
M. Fernandez-Getino Garcia, O. Edfors, J. Paez-Borrallo
Universidad Politecnica de Madrid, Spain
Parameter Estimation for OFDM with Transmit Receive Diversity 820
A. Mody, G. Stuber
Georgia Institute of Technology, USA
Performance of Several OFDM Transceivers in the Indoor Radio Channels in 17GHz Band 825
Z. Dlugaszewski 1, K. Wesolowski 1, M. Lobeira 2
1 Poznan University of Technology, Poland
2 ACORDE, Spain

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 14 of 49

Programmable Multiuser Synchronization for OFDM-CDMA 830
S. Wu, K. Chen
National Taiwan University, Taiwan
Companding Transform for the Reduction of Peak-to-Average Power Ratio of OFDM Signals 835
X. Huang 1, J. Lu 1, J. Chuang 2, J. Zheng 1
1 Tsinghua University, P.R. China
2 AT&T Labs Research, USA

24 Access Protocol 840

Performance Evaluation of IEEE 802.11 841
C. Foh, M. Zukerman
The University of Melbourne, Australia
An LMDS Access Protocol for Advanced High-Speed Bandwidth Intensive Wireless Applications 846
G. De Obaldia, T. Tozer, D. Grace, D. Pearce
University of York, UK
Proposal of DQRAP./CDMA MAC Protocol Optimization 851
G. Giovannini, L. Alonso, R. Agusti
Politecnic University of Catalonia, Spain
Load Balancing in Mixed Services CDMA Systems with Delayed Information 856
J. Harris, D. Chen, P. Fleming
Motorola Inc., USA
A Random-Reservation Medium Access Protocol for Satellite Netwowrks to Accommodate Real-time Traffic 861
S. Lepaja
Technische Universitat Wien, Austria
Impact of Radio Resource Control Mechanisms on the Performance of Internet Applications 866
A. Talukdar, M. Cudak
Motorola Labs, USA

25 Channel Assignment 871

Cellular Radio Channel Assignment Using a Sequential Trellis Search Algorithm 872
X. Fernando 1, A. Fapojuwo 2
1 The University of Calgary, USA
2 Nortel Networks, USA
Time Slot Assignment for Cellular SDMA/TDMA Systems with Antenna Arrays 877
Y. Hara 1, T. Nabetani 2, S. Hara 2
1 YRP Mobile Telecommunications, Japan
2 Department of Electrics, Japan
A Novel Decentralised DCA Concept for a TDD Network Applicable for UMTS 881
H. Haas 1, S. McLaughlin 2
1 Siemens AG, Germany
2 The University of Edinburgh, UK
Admission Control of Multimedia Calls in CDMA Mobile Systems 886
W. Jeon 1, D. Jeong 2
1 Seoul National University, Korea
2 Hankuk University of FS, Korea
Maximum-likehood Subchannel Detection in Forward Links for Multicarrier DS CDMA System 891
J. Li, P. Fan, Z. Cao
Tsinghua University, P.R. China
A Near Optimal Subchannel Allocaiton Policy in Forward Links for Multicarrier CDMA Systems 896
P. Fan, J. Li, Z. Cao
Tsinghua University, P.R. China

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 15 of 49

An Analytical Modeling for a Class of Queueing Priority Handoff and Call Admission Control Schemes in Micro-Cellular PCN's 901
V. Phan-Van 1, S. Glisic 2
1 Nokia Networks, Finland
2 University of Oulu, Finland
Code Assignment for IMT-2000 on Forward Radio Link 906
F. Shueh, W. Chen
National Chung-Hsing University, P.R. China
Performance Analysis of Channel Assignment Schemes 911
Z. Tabakovic
Croatian Institute of Telecommunications, Croatia
Multi-User Detection with Dynamic Channel Assignment 916
M. Wu 1, W. Fang 1, J. Chen 2
1 National Taiwan Univrsity of Sci. and Tech., Taiwan
2 National Tsing Hua Univrsity, Taiwan
Aggressive Distributed Dynamic Channel Assignment Strategies for Multi-Rate Transmission Microcellular Networks 921
F. Cruz-Perez, D. Lara-Rodriguez, M. Lara
CINVESTAV-IPN, Mexico
An Approximate Analysis Method of Erlang Capacity for CDMA Systems with Multiple Sectors, and Multiple Frequency Allocation Bands 926
I. Koo 1, J. Yang 1, K. Kim 1, Y. Yang 2
1 KJIST, Korea
2 SK Telecom
Spectrally Efficient Cell Planning in Mobile Wireless Networks 931
S. Allen, S. Hurley, R. Whitaker
Cardiff University, UK
Call Placement Algorithm Evaluation for Integrated Networks that Overflow Speech or Data 936
S. Lincke-Salecker, C. Hood
Illinois Institute of Technology, USA
Uplink and Downlink Performance Evaluation of Interference Adaptive Distributed DCA Algorithms in F-TDMA Mobile Radio Networks 941
R. Verdone, A. Zanella
University of Bologna, Italy
Performance of Delay-Dependent Queuing of Hando_ Requests with 2 and 3 Priority Classes in PCS 946
A. Xhafa, O. Tonguz
Carnegie Mellon University, USA
Dynamic Priority Queuing, Channel Borrowing, and First in First Out Handoff Schemes: A Performance Comparison 951
A. Xhafa, O. Tonguz
Carnegie Mellon University, USA
The Vertexes Reduction Algorithm for the Channel Assignment Problem - Comparison Analysis 956
W. Koloswski, C. Ziolkowski
Military University of Technology, Poland

27 Resource Allocation 961

Modeling Methods for WCDMA Network Planning 962
D. Bem, M. Nawrocki, T. Wieckowski, R. Zielinski
Wroclaw Univ. of Technology, Poland
Evaluation of Packet-by-Packet Downlink Radio Resource Management Schemes 967
M. Eriksson
Royal Institute of Technology, Sweden
A Learning Approach for Call Admission Control with Prioritized Handoff in Mobile Multimedia Networks 972
E. El-Alfy, Y. Yao, H. Heffes
Stevens Inst. of Technology, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 16 of 49

Resource Allocation for the Broadcast Control Channel in UTRA-TDD 977
P. Guidotti 1, P. Skillermark 2
1 Erricsson Lab Italy SpA, Italy
2 Ericsson Radio Systems AB, Sweden
Channel Assignment in CDMA Systems with Walsh and PN Coding 982
P. Gajewski
Military University of Technology, Poland
Multi-Cell Admission Control for UMTS 987
J. Outes 1, L. Nielsen 2, K. Pedersen 2, P. Mogensen 2
1 Aalborg University, Denmark
2 Nokia Networks, Denmark
Adaptive Switching Point Simulations for Different Traffic Profiles for Utra-TDD 992
R. Schelb, T. Winter
Siemens AG, Germany
Performance Bounds for Cellular Mobile Communications Networks with Repeated Attempts 996
M. Zukerman, C. Lee
The University of Melbourne, Australia
Downlink Throughput and Fairness Analysis in Multi-rate CDMA Systems 1001
J. Cho, D. Hong
Sogang University, Korea
Performance Analysis of the Fractional Channel Reservation in TDMA and CDMA Integrated Services Networks 1007
F. Cruz-Perez, D. Lara-Rodriguez, M. Lara
CINVESTAV-IPN, Mexico
Radio Resource Management Strategies for Packet Data Services in UMTS 1012
C. Carciofi, P. Grazioso
Fondazione Ugo Bordoni, Italy
Comparative Evaluation of Fixed and Adaptive Soft Handoff Parameters Using Fuzzy Inference System in CDMA Mobile Communication Systems 1017
V. Kunsriruksakul, B. Homnan, W. Benjapolakul
Chulalongkorn University, Thailand
Network Assisted Power Control for Wireless Data 1022
D. Goodman 1, N. Mandayam 2
1 Politechnic University, USA
2 Rutgers University, USA
Improved TDD Resource Allocation through Inter-Mobile Interference Avoidance 1027
M. Lindstrom
Royal Institute of Technology (KTH), Sweden
Dynamic Channel Allocation in UMTS Terrestrial Radio Access TDD Systems 1032
I. Forkel 1, T. Kriengchaiyapruk 1, B. Wegmann 2, E. Schulz 2
1 RWTH Aachen University of Technology, Germany
2 Siemens AG, Germany
Resolving the CDMA Cell Breathing Effect and Near-Far Unfair Access Problem by Bandwidth-Space Partitioning 1037
S. Yang 1, A. Ephremides 2
1 Transilica Inc., USA
2 University of Marylang, USA
Efficient Resource Allocation Scheme for Reverse High Speed Operation in CDMA2000 System 1042
J. So, S. Choi, D. Cho
KAIST, Korea
Application of a Realistic Mobility Model to Call Admissions in DS-CDMA Cellular Systems 1047
T. Tugcu, C. Ersoy
Bogazici University, Turkey
An Agglomerating Radio Resource Control Method for Wireless Packet Access Systems 1052
T. Takao, T. Sato, N. Umeda
NTT Docomo Inc., Japan

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 17 of 49

Study of distributed Resource Allocation in Cellular Systems 1057
S. Anand, A. Sridharan, K. Sivarajan
Indian Institute of Science, India
Optimal Power and Rate Control for Fading Channels 1063
I. Bettesh, S. Shamai
Technion-Israel Institute of Technology, Israel
Uplink Admission Control for Conversational Services Using Information from Many Cells 1068
B. Timus, J. Pettersson
Ericsson Erisoft AB, Sweden
Congestion Based Pricing in a Dynamic Wireless Network 1073
T. Heikkinen
University of Lund, Sweden
Trunk-Resource-Efficiency-Controlling Soft Handoff Based on Fuzzy Logic and Gradient Descent Method 1077
B. Homnan, W. Benjapolakul
Chulalongkorn University, Thailand
A Scheduling Algorithm for Soft-QoS Guarantee in 3G Systems 1082
O. Sallent, J. Perez-Romero, R. Agusti, F. Casadevall
Univrsity Politechnica de Catalunya, Spain

29 Short range access (Bluetooth, UWB, home-RF) 1087

Ultra-Wide Band Radio: Introducing a New Technology 1088
K. Siwiak
Time Domain Corporation, USA
Gaussian Pulse Shaping of Coded OOK Formats in Wireless Infrared Links at High Bit Rates 1094
A. Garcia-Zambrana 1, P. Vera-Candeas 2, A. Puerta-Notario 1
1 Universidad de Malaga, Spain
2 Universidad de Jaen, Spain
CSMA Multiuser Bit Loading Algorithm for Multicarrier Wireless Local Area Networks 1099
A. Garcia-Armada
Universidad Carlos III de Madrid, Spain
Performance Enhancement of Wireless LANs Through Packet Combining 1104
M. Gidlund, S. Slimane
Radio Communication Systems Group, Sweden
Empirical Study for IEEE 802.11 and Bluetooth Interoperability 1109
I. Howitt 1, V. Mitter 1, J. Gutierrez 2
1 University of Wisconsin Milwaukee, USA
2 Eaton Corporation Innovation Center
IEEE 802.11 and Bluetooth Coexistence Analysis Methodology 1114
I. Howitt
University of Wisconsin Milwaukee, USA
Reliable Delivery of Broadcast Packet in Bluetooth 1118
K. Jang, J. Park, T. Lee, Y. Kim
Samsung Electronics Co. Ltd., Korea
Wireless 1394: A New Standard for Integrated Wireless Broadband Home Networking 1124
H. Zhang 1, T. Udagawa 1, T. Arita 1, J. Tsuji 1, K. Okada 1,2, I. Sasase 1,2, M. Nakagawa 1,2
1 Telecommunications Advancement Organization, Japan
2 Keio University, Japan
Optimum Performance of Link Adaptation in HIPERLAN/2 Networks 1129
S. Simoens, D. Bartolome
Motorola Labs, France
Bluetooth-Based Mobile AD HOC Networks: Opportunities and Challenges for a Telecommunications Operator 1134
D. Groten, J. Schmidt
KPN Research, The Netherlands

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 18 of 49

Radio Aspects of Hybrid Wireless AD-HOC Networks 1139
O. Mantel, N. Scully, A. Mawira
KPN Research, The Netherlands
Model and Performance Evaluation of a Piconet for Point-to-Multipoint Communications in Bluetooth 1144
T. Lee, K. Jang, H. Kang, J. Park
Samsung Electronics Co. Ltd., Korea
Relative Location in Wireless Networks 1149
N. Patwari 1, R. O'Dea 1, Y. Wang 2
1 Motorola Labs, USA
2 University of Florida, USA
Cell Based QOS Provisioning Scheme for Indoor Wireless Network 1154
C. Lee, K. Sung
KAIST, Korea
A Statistical Model for the UWB Indoor Channel 1159
D. Cassioli 1, M. Win 2, A. Molisch 3
1 Universita degli Studi di Roma 'Tor Vergata', Italy
2 AT&T Labs-Research, USA
3 Technische Universitat Wien, Austria
CDMA-based Carrier Sense Multiple Access Protocol for Wireless LAN 1164
G. Qiang 1, Z. Liu 1, S. Ishihara 2, T. Mizuno 2
1 Xidian University, P.R. China
2 Shizuoka University, Japan
Ultra-Wide Band Radio: The Emergence of an Important RF Technology 1169
K. Siwiak, P. Withington, S. Phelan
Time Domain Corporation, USA
A Path Link Model for Ultra Wide Band Pulse Transmissions 1173
K. Siwiak, A. Petroff
Time Domain Corporation, USA
The Effects of Multipath Interference on the Performance of UWB Systems in an Indoor Wireless Channel 1176
J. Foerster
Intel Architecture Labs, USA
Impact of Ultra-Wide Band Transmission on a generic receiver 1181
K. Siwiak
Time Domain Corporation, USA
Generating Near- White Ultra-Wideband Signals with Period Extended PN Sequences 1184
X. Huang, Y. Li
Motorola Australian Research Center, Australia
Measurement of UWB Antenna Efficiency 1189
H. Schantz
Time Domain Corporation, USA

3 Transmission Technology 1192
31 Modulation/Demodulation 1193

BER Calculation for MQAM-OFDM with ICI Caused by Carrier Frequency Fluctuations 1194
J. Hasson, B. Bobrovsky
Tel Aviv University, Israel
A Novel Selective Combining Demodulator for Unresolvable Multipath in DS-SpSp 1197
J. Hasson, B. Bobrovsky
Tel Aviv University, Israel
Measurement and Monitoring of Microwave Reflection Properties of Cement-Based Materials for Propagation Modeling 1202
S. Kharkovsky 1,2, U. Hasar 1, M. Akay 1, C. Atis 1
1 Cukurova University, Turkey
2 Institute of Ukraine, Ukraine

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 19 of 49

Signal Design for Multipath Fading Channels - Doppler and ISI Barriers 1206
A. Mammela
VTT Electronics, Finland
Adaptive Data Rate Using ARQ and Nonuniform Constellations 1210
R. Otnes 1, T. Maseng 2
1 UniK - Center for Tech. At Kjeller, Norway
2 Norwegian Defence Research Establishment, Norway
Improving the Adaptive Rate QAM-DFE Systems Performance by using Tomlinson-Harashima Precoding 1215
J. Paris, M. Aguayo-Torres, J. Entrambasaguas
University of Malaga, Spain
On Performance Evaluation of Trellis Coded PSK Modulation in Rician-Fading Mobile Radio Channel 1221
M. Pejanovic, Z. Veljovic
University of Montenegro, Yugoslavia
New Approach for QPSK Modulaiton 1225
L. Xiaoli 1, L. Look 1, S. Zhongxiang 1, S. Aditya 1, Q. Cheng 2, S. Zhongliang 2
1 Nanyang Technological University, Singapore
2 Southeast University, P.R. China
Concatenated TCM with Space-Time Block Codes and Diffrential M-PSK Modulation 1230
H. Xu, K. Kwak
Inha University, Korea
Novel Two-Level and Three-Level 8PSK Modulation Codes with More UEP Flexibility for Rayleigh Fading Channel 1235
D. Yuan 1, C. Gao 1, L. Zhang 2, Z. Cao 2
1 Shandong University, P.R. China
2 Tsinghua University, P.R. China
Linear Transformation of Multi-level Signal Set in Multi-Code CDMA 1239
T. Minn, K. Siu
Massachusetts Institute of Technology, USA
Maximizing Minimum Euclidean Distance of Spectrally Constrained Partial Response CPM 1244
T. Svensson, A. Svensson
Chalmers University of Technology, Sweden
Array Antenna Assisted Adaptive Modulation in a Fast Fading Channel 1249
M. Okada 1, T. Wada 2, H. Yamamoto 1
1 Nara Inst. of Science and Technology, Japan
2 Wakayama University, Japan
Dynamic Water-Filling for Wavelet Communications 1254
M. Chang 1, K. Lay 1, J. Chen 2
1 National Taiwan University, P.R. China
2 National Tsing Hua University, P.R. China
Joint Turbo-Equalization and TTCM for Frequency Selective Channels 1259
X. Li, W. Song, H. Luo
Shanghai Jiatong University, P.R. China
A Novel Demodulation Approach for Multi-Carrier Using Bandpass RAKE Receiver 1264
Yangxin, Y. Xiaohu
Southeast University, P.R. China
Degress of Freedom in Adaptive Modulation: A Unified View 1267
S. Chung, A. Goldsmith
Stanford University, USA
Turbo-Greedy Coding for High Data Rate Wireless Communications: Principles and Robustness 1272
A. Stefanov 1, A. AlRustamani 2, B. Vojcic 2
1 Arizona State University, USA
2 George Washington University, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 20 of 49

Decoding Performance and Complexity Analysis for Analog and Digital Channel Decoders 1277
S. Hong 1, W. Stark 2
1 State Univ. of New York, USA
2 University of Michigan, USA
Turbo-BLAST and its Performance 1282
A. van Zelst 1, R. van Nee 2, G. Awater 2
1 Wireless Systems Research, The Netherlands
2 Woodside Networks, The Netherlands
Performance of Iterative Successive Detection Algorithm for Space-Time Transmission 1287
A. Benjebbour, H. Murata, S. Yoshida
Kyoto University, Japan
Design of Space-Time Codes and Its Performance in CDMA Systems 1292
J. Yuan 1, B. Vucetic 2, B. Xu 3, Z. Chen 2
1 The University of New South Wales, Australia
2 The University of Sydney, Australia
3 Lucent Technologies, Australia

32 Source/Channel Coding 1297

Improved Techniques for 4 Transmit and 4 Receive Antenna MIMO-OFDM for Wireless Communications 1298
R. Blum 1, Q. Yau 1, Y. Li 2, J. Winters 3
1 Lehigh University, USA
2 Georgia Institute of Technology, USA
3 AT&T Labs-Research, USA
A Memory Efficient Scheme for Hardware Implementation of Long-Map Turbo Decoder 1303
C. Bai, J. Jiang, P. Zhang
Beijing University of Posts & Telecomm, P.R. China
A Novel Interleaving Technique Combining with STBC for Flat Fading Down-Link Convolutionally Coded CDMA System 1307
J. Cheng 1, H. Wang 2, S. Cheng 1
1 Southeast University, China
2 Nokia Mobile Phones, Finland
Space Time Codes of Multi-code Transmission for WCDMA 1311
M. Chen 1, G. Wu 1, H. Wang 2
1 Southeast University, China
2 Nokia Mobile Phones, Finland
Efficient Spectral Magnitude Quantisation for High-Quality Sinusoidal Speech Coders 1314
Y. Cho, S. Villette, A. Kondoz
CCSR, University of Surrey, UK
Upper Bounds on the Bit-Error Probability of Space-Time Trellis Codes using Generating Function Techniques 1318
R. Gozali, B. Woerner
Virginia Polytechnic Institute and State University, USA
A Pragmatic Coded Modulation Choice for Future Broadband Wireless Communications 1324
P. Montezuma, A. Gusmao
Instituto Superior Tecnico, Portugal
A Novel AUQ Scheme and Some Implementation Issues in WCDMA System 1329
G. Kang, Q. Quan, P. Zhang
Beijing University of Posts & Telecomm, P.R. China
The Integration of Power Control and Turbo Coding in Ka-band CDMA Based LEO Stellite System 1333
W. Li, C. Law, V. Dubey
Nanyang Technological University, Singapore

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 21 of 49

Application of Block Coded Modulation in Direct-Sequence Spread-Spectrum Communication 1338
Y. Luo, K. Kwak
Inha University, Korea
Joint Adaptive Rate Turbo Decoding and Synchronization on Rayleigh Fading Channels 1342
B. Mielczarek, A. Svensson
Chalmers University of Technology, Sweden
Comparison between Soft and Hard Decision Decoding Using Quaternary Convolutional Encoders and the Decomposed CPM Model 1347
M. Singh, I. Wassell
University of Cambridge, UK
Turbo Coded Space -Time Unitary Matrix Differential Modulation 1352
A. Steiner, M. Peleg, S. Shamai
Technion-Israel Institute of Technology, Israel
Performance of Space-Time Bit-Interleaved Codes in Fading Channels with Simplified Iterative Decoding 1357
A. Tonello
University of Padova/DEI, Italy
Blind Space-time Channel Estimation for DS-CDMA with Aperiodic Spreading Code 1362
B. Jiang, X. Wu, Q. Yin
Xi'an Jiaotong University, P.R. China
A New Adaptive Strategy for Turbo Decoder with Prior Statistical Knowledge of Extrinsic Information over AWGN and Fading Channels 1367
F. Yang 1, R. Tafazolli 2, B. Evans 2
1 Nanjing University
University of Surrey, UK
Research on the Application of UEP using Turbo Codes to Image Transmission 1372
D. Yuan, X. Shan
Shandong University, P.R. China
Research on the Viterbi and BCJR Decoding Schemes of Convolutional Codes under Different Sources 1377
D. Yuan, X. Shan
Shandong University, P.R. China
Syndrome-Based Hybrid ARQ with Reed-Solomon Codes and the Practice in Image Transmission over Rayleigh Fading Channel 1382
L. Zhang, Y. Wang, Z. Ma, Z. Cao
Shandong University, P.R. China
Low Bit Rate Video Transmission in a Rayleigh Fading Channel 1386
A. Akbulut, H. Zorba, M. Demir, S. Tugac, M. Yilmaz
Ankara University, Turkey
Turbo Coded Modulation for High-Throughput TDMA Systems 1390
P. Papadimitriou, P. Varshney
Nokia Mobile Phones, USA
Reduced Complexity In-phase/Quadrature-phase Turbo Equalisation using Radial Basis Functions 1395
M. Yee, B. Yeap, L. Hanzo
University of Southampton, UK
Data Link Control Scheme for Wireless ATM Transmission 1400
Z. Ilic, A. Bazant, M. Kos
University of Zagreb, Croatia
Performance of Space-time Trellis Coding Over Nakagami Fading Channels 1405
Y. Gong, K. Letaief
Hong Kong University, Hong Kong
Hybrid ARQ Using Serial Concatenated Convolutional Codes Over Fading Channels 1410
N. Chandran, M. Valenti
West Virginia University, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 22 of 49

The Application of Space-time Codes to CDMA System 1415
C. Xu 1,2, H. Xu 1, K. Kwak 1
1 Inha University, Korea
2 Nanjing University, China
A New Soft Handover Scheme Using Punctured Turbo Codes in the Wideband CDMA System 1420
B. Kim, S. Kwon
LG Eelectronics Inc., Korea
Errors-and-Erasures Decoding fo Block Codes in Hidden Markov Channels 1425
C. Lee, Y. Su
National Chiao Tung University, Taiwan
Improved Turbo Decoder Structures for Burst Error Channels 1430
B. Mielczarek, A. Svensson
Chalmers University of Technology, Sweden
Coded Transmit Macrodiversity: Block Space-Time Codes Over Distributed Antennas 1435
Y. Tang, M. Valenti
West Virginia University, USA
On the Complexity of Turbo Decoding Algorithms 1439
P. Wu
MIT Lincoln Laboratory, USA
Eneregy Efficient Coding and Transmission 1444
E. Erkip, Y. Wang, D. Goodman, Y. Wu, X. Lu
Polytechnic University, USA
Linear time and frequency domain Turbo equalization 1449
M. T¨uchler, J. Hagenauer
Lehrstuhl f¨ur Nachrichtentechnik, Germany
Search Strategies for Two-Dimensional Code Acquisition in Environments with- Non Uniform Spatial Distribution of Interference 1454
M. Katz, J. Iinatti, S. Glisic
University of Oulu, Finland
Optimised labeling maps for bit-interleaved transmission with turbo demodulation 1459
A. Gorokhov, M. van Dijk
Philips Research Nat. Labs, The Netherlands
Turbo Equalization of Serially Concatenated Systematic Convolutional Codes and Systematic Space Time Trellis Codes 1464
B. Yeap, T. Liew, L. Hanzo
University of Southampton, UK
Multiple Channel Turbo Detection 1469
B. Unal 1, A. Berthet 2
1 Middle East Technical University, Turkey
2 Alcatel Space Industries, France
A SINR Maximizing 2D Rake Receiver for Multi-Sensor WCDMA Mobile Terminals 1474
M. Lenardi, D. Slock, A. Medles
EURECOM Institute, France
A Randomization Technique for Non-Orthogonal Space-time Block Codes 1479
A. Hottinen, O. Tirkkonen
Nokia Research Center, Finland
Fixed-Point Performance of Low-Complexity Turbo Decoding Algorithms 1483
T. Blankenship, B. Classon
Motorola Labs, USA
Parity-Check-Bit Inserted Turbo Code 1488
H. Jung, G. Lee, S. Park
Information and Communication Univresity, Korea

33 Interference Rejection 1492

A Novel Multipath Interference Cancellation Scheme for Rake Channel Estimation 1493
J. Baltersee, G. Fock, P. Schulz-Rittich
Aachen University of Technology, Germany

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 23 of 49

Integrated Power Control and Beamforming in TDMA Cellular Systems with Mobility 1498
S. Cheng, D. Cox
Stanford University, USA
Space-Time-Frequency Multiuser Detection over Fast-Fading Multipath Channels for Syhnchronous DS-CDMA Systems 1503
O. Ertug, B. Baykal
Middle East Technical University, Turkey
Multipath Interference Cancellation and Modified RAKE Receiver 1508
R. Hu, A. Huang, H. Wang, W. Gu
Zhejiang University, P.R. China
On the Impact of Soft Decision Functions on the Performance of Multistage Parallel Interference Cancelers for CDMA Systems 1513
R. Irmer, A. Nahler, G. Fettweis
Dresden University of Technology, Germany
Iterative Multiuser Receiver for a Coded DS-CDMA System 1518
J. Luna Rivera, D. Cruickshank, J. Thompson
The University of Edinburgh, UK
A Hybrid Interference Canceller for CDMA Systems in Rayleigh Fading Channels 1523
R. Malik 1, V. Dubey 1, B. McGuffin 1,2
1 Nanyang Technological University, Singapore
2 Massachusetts Institute of Technology
Nonwhite Noise/Interference Rejection via Blind Adaptive Filtering 1528
R. Piotrowski 1, J. Pawelec 2
1 Defence Communication Inst., Poland
2 Radom University of Technology, Poland
Multistage Non-linear Paralll Interference Cancellation with Small Spread Factor 1533
T. Xiaofeng, L.Lihua, Z.Ping
Beijing University Of Posts & Telecomm., P.R. China
W-CDMA Adaptive Receiver with Space-Frequency Diversity for Multi-path Fading Channels 1538
A. Ciofini, L. Ronga
CNIT-University of Florence, Italy
Space Time Block Precoding Scheme for Time Division Duplex CDMA Communications 1543
Z. Bu 1, H. Wang 2, J. Lilleberg 2, S. Cheng 1
1 Southeast University, P.R. China
2 Nokia Mobile Phones, Finland
Estimation of Noise and Interfering Power for Transmissions over Rayleigh Fading Channels 1548
L. Husson, A. Wautier, J. Antoine, J. Dany
SUPELEC Service Radioelectricite et Electronique, France
Protection Against Cochannel Interference from Neighboring Cells using Down-Tilting of Antenna Beams 1553
H. Cho 1, Y. Kim 2, D.Sung 3
1 Hankuk Aviation University, Korea
2 ETRI, Korea
3 KAIST, Korea
Performance Analysis of a Blind Adaptive Linear Minimum Mean Squared Error Receiver for Use in UMTS TDD-CDMA Basestations 1558
Y. Bian, A. Nix, J. McGeehan
University of Bristol, UK
The Projection Matrix Method for Interference Cancellation 1563
S. Shim 1, S. Jung 2, C. Lee 1
1 Yonsei University, Korea
2 Samsung Thales Ltd., Korea
Intercell Interference Cancelation at a SCDMA Mobile Terminal by Exploiting Excess Codes 1568
M. Lenardi, A. Medles, D. Slock
EURECOM Institute, France

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 24 of 49

Interference Factor Evaluation for CDMA System Capacity Analysis 1573
S. Ammari, A. Wautier
SUPELEC Service Radioelectricite et Electronique, France
Derivation of a New Analysis Tool to Compute the Performance of Non-Linear Multistage Interference Cancellation Detectors 1578
A. Wellig
Morphics Technology Inc., USA
Interference Cancellation for Multirate Multiuser Systems 1584
D. Yoo, W. Stark
University of Michigan, USA
Implementation Issues on the Interference Cancellation over Asynchronous Multi-path Channels 1589
Y. Kim 1, S. Kim 1, I. Choi 1, S. Cho 2
1 ETRI, Korea
2 Hanyang University, Korea
CDMA Downlink Equalization with Imperfect Channel Estimation 1593
L. Mailaender
Lucent Technologies, USA
Iterative (Soft) Interference Cancellation and Decoding for the Uplink IS-95 CDMA System 1598
S. Waxman, S. Shamai
Technion-Israel Institute of Technology, Israel

34 Equalization 1603

Iterative Soft Cholesky Block Decision Feedback Equalizer - a Promising Approach to Combat Interference 1604
J. Egle, C. Sgraja, J. Lindner
University of Ulm, Germany
Adaptive Equalization for Mobile Communication Systems Based on Constant Modulus Algorithm 1609
M. Hajian 1, j. Fernandes 2, P. Cunha 2, L. Ligthart 1
1 IRCR/TU Delft, The Netherlands
2 Technical University of Lisbon, Portugal
Maximum Likelihood Channel Estimation with Noise of Unknown Power Spectrum 1614
D. Hui, K. Zangi
Ericsson Research, USA
Off-line Frequency Correction for Equalization in the EDGE System 1619
A. Kuzminskiy, C. Luschi, P. Strauch
Lucent Technologies Optimus, USA
Performance Analysis of DS-CDMA Indoor Infrared Wireless Systems using Equalizer on Diffuse Channels 1624
M. Matsuo 1, T. Ohtsuki 2, I. Sasase 1
1 Keio University, Japan
2 Keio University, Japan
Turbo Equalization and Incremental Redundancy for Advanced TDMA Systems 1629
R. Visoz 1, A. Berthet 2, A. Saadani 1, B. Penther 3
1 France Telecom R&D, France
2 Alcatel Space Industries, France
3 Mitsubishi Electric ITE, France
Iterative Turbo Decoder with Decision Feedback Equalizer for Signals Transmitted Over Multipath Channels 1634
X. Yu
Motorola Inc., USA
QML-MC Algorithm for Frequency Estimation on Multipath Channels 1639
M. Terre 1, V. Cueff 2
1 Conservatoire National des Arts et Metiers, France
2 Alcatel CIT, France

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 25 of 49

Adaptive MLSE Space-Diversity Reception Technique in Mobile Radio Channels 1644
L. Rubio, N. Cardona, J. Reig, A. Gonzales
Universidad Politecnica de Valencia, Spain
Unconditionally Convergent pre-Distortion of non-Linear High Power Amplifiers 1649
J. Sala, H. Durney
Universitat Politecnica de Catalunya, Spain
A New Reduced Complexity Turbo-Detector for Highly Selective Long Delay Spread ISI Channels: A Solution for 4G Mobile Systems? 1654
A. Berthet 1, B. Penther 2, R. Visoz 3, J. Boutros 4
1 Alcatel Space Industries, France
2 Mitsubishi Electric ITE, France
3 France Telecom R&D, France
4 ENST Paris, France
Fast Blind and Semi-Blind Channel Identification of Mobile Radio Fading Channels Using A-Priori Information 1659
A. Schmidbauer
Munich University of Technology, Germany
A Code-Aided Adaptive Equalizer using Soft Decision-Directed Algorithm and Convolutional Coding for Fading Channels 1664
Y. Lee, M. Wang
Hong Kong University, Hong Kong
An Efficient Equalizer for 8-PSK EDGE Cellular Radio Systems 1668
J. Olivier 1, C. Xiao 2, K. Mann 3
1 Nokia Research Center, USA
2 University of Missouri-Columbia, USA
3 Wireless Solutions, Canada
Transmit Diversity and Equalization for Frequency Selective Fading Channels 1673
L. Li, H. Li, Y. Yao
Stevens Institute of Technology, USA
A Effective Scheme of Combining Turbo-Codes and Transmitting Diversity 1678
Z. Li, Y. Xu, W. Song, H. Luo

35 - Synchronization 1683

Shanghai Jiatong University, P.R. China
NBI Suppression for Code Acquisition in a DS/CDMA Overlay Environment 1684
J. Kim
Kwangwoon University, Korea
A Carrier Frequency Offset Correction Scheme for MC-CDMA 1689
A. McCormick, P. Grant, J. Thompson, E. Al-Susa
The University of Edinburgh, UK
Comparison of Downlink and Uplink MC-DS-CDMA Sensitivity to Carrier Frequency Offsets 1693
H. Steendam, M. Moeneclaey
Ghent University, Belgium
Algorithms of Reduced Power Consumption and Reduced Complexity for Code Tracking Loops 1698
J. Scheim, B. Bobrovsky
Tel Aviv University, Israel
Performance of Iterative DS-CDMA M-ARY Demodulation in the Presence of Synchronization Errors 1703
P. Xiao, E. Strom
Chalmers University of Technology, Sweden
An Improved Automatic Frequency Correction Scheme for Discontinuous Pilot Mobile Communication System 1708
Y. Zhang, X. Yu
Southeast University, P.R. China
An Iterative Frequency Estimator for Feedforward Frequency Synchronization 1713
T. Brown, M. Wang
Motorola Inc., USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 26 of 49

Coherent Slot Detection under Frequency Offset for W-CDMA 1719
T. Chulajata 1, H. Kwon 1, K. Min 2
1 Wichita State University, USA
2 Neoreach Inc., USA
Least Squares Approach to Data-Aided Frequency Estimation in Frequency-Selective Fading Channels 1724
E. Jeong 1, S. Jo 2, Y. Kim 1, Y. Lee 1
1 Korea Advanced Inst. of Sci. and Technology, Korea
2 Samsung Electronics Co., LTD., Korea
Optimized Timing-Error-Detector for DS-CDMA Applications in Multipath Scenarios 1729
G. Fock, P.Schulz-Rittich, J. Baltersee
Aachen University of Technology, Germany

36 Multi-user Detection 1734

Maximum Likelihood Semiblind Linear Multiuser Interference Suppression for CDMA Systems 1735
M. Bugallo, J. Miguez, L. Castedo
University of Corunia, Spain
A Semi-Blind Multiuser Projection Receiver Based on Conjugate Gradient and Subspace Tracking 1740
Q. Wu, C. Li
Modern Communication Research Inst., P.R. China
Enhancing the Cellular Downlink Capacity via Co-processing at the Transmitting End 1745
S. Shamai, B. Zaidel
Technion-Israel Institute of Technology, Israel
Blind Signal Recovery for High Rate CDMA Systems 1750
J. Zhang, W. Ser, J. Zhu
Nanyang Technological University, Singapore
Synchronisation Error Resistant Multiuser Detection for Asychronous CDMA 1755
F. Zheng
Victoria University of Technology, Australia
Minimum Variance Decorrelating Receiver in Time Variant Frequency Selective Rayleigh CDMA Channel 1760
X. Tang, Y. Bar-Ness
New Jersey Inst. of Technology, USA
Robust Joint Channel Estimation and Multiuser Detection with Differential Modulation in DS/CDMA Systems 1765
Z. Guo, K. Letaief
Hong Kong University, Hong Kong
An Adaptive Decision-Feedback Multiuser Detector Using Parallel Interference Cancellation for CDMA Systems 1770
Y. Huang 1, J. Wen 1, H.T Wu 2
1 National Chung Cheng University, P.R. China
2 Southern Taiwan University, R.O.C
A New CMA-based Blind Adaptive Multiuser Detction 1775
Q. Xue 1, X. Jiang 2, W. Wu 1
1 Beijing University of Posts & Telecomm, P.R. China
2 Northern Jiao Tong University, P.R. China
Hybrid MMSE and SIC for Multiuser Detection 1779
C. Tsai 1, W. Fang 1, J. Chen 2
1 National Taiwan University, P.R. China
2 National Tsing Hua University, P.R. China
A Computationally Efficient Hybrid of Joint Detection and Successive Interference Cancellation 1784
R. Misra, J. Pan, A. Zeira
InterDigital Communication Corp., USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 27 of 49

Group-Blind Multiuser Detection for UTRA-TDD 1789
J. Yu 1, A. Host-Madsen 2, X. Wang 3, G. Messier 4
1 Ericsson Wireless Communications Inc., USA
2 University of Hawaii, USA
3 A&M University, USA
4 TRLabs, Canada

Genetic Algorithm Based Antenna Diversity Assisted Multiuser Detection for Synchronous CDMA Systems 1794
K. Yen, L. Hanzo
University of Southampton, UK

Space-Time Iterative and Multistage Receiver Structures for CDMA Mobile Communication Systems 1799
S. Marinkovic 1, B. Vucetic 1, N. Ishii 2, S. Yoshida 2, A. Ushirokawa 2
1 University of Sydney, Australia
2 NEC Corporation, Australia

Multiple Access Interference Cancellation in Fading Multipath Channels: Progress and Limitations 1804
J. Andrews, T. Meng
Stanford University, USA

Partial Interference Subspace Rejection in CDMA Systems 1809
H. Hansen 1, S. Affes 2, P. Mermelstein 2
1 University of Denmark, Denmark
2 University of Quebec, Canada

Sensitivity of Blind Adaptive LMMSE Single-User Receivers to Path Delay and Phase Estimation Errors in Multipath Fading Channel 1814
L. Mucchi 1,2, M. Latva-aho 1, E. Del Re 2, R. Fantacci 2
1 University of Oulu, Finland
2 University of Firenze, Italy

Performance Analysis of MAI Canceller Combined with Adaptive Array Antenna for DS-CDMA 1819
K. Yano, S. Hirose, H. Murata, S. Yoshida
Kyoto University, Japan

On the fading channel Performance of Temporal-Spatial Filters for CDMA 1824
A. Yener 1, S. Ulukus 2
1 Lehigh University, USA
2 AT&T Labs Research, USA

On the Performance of Multisensor Reception in CDMA by Fast Independent Component Analysis 1829
T. Ristaniemi, R. Wu
University of Jyvaskyla, Finland

A Channel-Shortening Multiuser Detector for DS-CDMA Systems 1834
I. Medvedev, V. Tarokh
Massachusetts Institute of Technology, USA

Double-Threshold Selective PIC Receiver for CDMA Communications in Multipath Fading Channel 1839
R. Fantacci, S. Morosi, S. Villano
University of Firenze, Italy

Adaptive Blind Multiuser Detection in Asynchronous CDMA 1844
J. Murillo-Feuntes, M. Sanchez-Fernandez, F. Gonzalez-Serrano
Universidad Carlos III de Madrid, Spain

A Code Acquisition Scheme with Interference Cancellation for DS-CDMA Systems 1849
J. Lee, S. Oh
Ajou University, Korea

Projection Multiuser Detectors for Hierarchical Cell Structures in CDMA Cellular Systems 1853
A. Catovic, S. Tekinay
New Jersey Inst.of Technology, USA

Blind PSP-Based Turbo Equalization 1858
S. Vlahoyiannatos, L. Hanzo
Univ. of Southampton, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 28 of 49

Reduced Complexity Multiuser Receiver for Asynchronous Trellis Coded DS-CDMA Systems 1863
G. Corral-Briones, M. Hueda, C. Rodriguez
Universidad Nacional de Cordoba, Argentina
Blind Adaptive Stochastic Neural Network for Multiuser Detection 1868
G. Jeney, J. Levendovszky, L. Kovacs
Budapest University of Technology and Economics, Hungary

37 Software Radio 1873

A 'Low Cost' Software Radio Test Bed 1874
J. Dixon, J. Wilkes
Telcordia Technologies, USA
Channel Diversity in a Software Autoradio 1879
H. Schnepp, T. Muller, J. Luy
DaimlerChrysler AG, Germany
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Y. Or, G. Kutz, A. Chass, A. Gubeskys, E. Pollak
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Z. Tiejun
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M. Faulkner
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Z. Wu, C. Luo, X. Su, X. Xu
Tsinghua University, P.R. China
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Westminster University, UK
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R. Ramos, K. Madani
Westminster University, UK

38 Transceiver Design 1932

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M. Choi, Y. Yao, H. Heffes
Stevens Inst. of Technology, USA
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W. Chung, H. Lee, J. Moon
Shinsegi Telecomm Inc., Korea

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 29 of 49

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P. Fu, K. Chen
National Taiwan University, Taiwan
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Y. Hu 1,2, H. Zhu 1, J. Zhu 2
1 Anhui University, P.R. China
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Kyushu University, Japan
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M. Sellathurai, S. Haykin
McMaster University, Canada
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P. Schulz-Rittich, J. Baltersee, G. Fock
Aachen University of Technology, Germany
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J. Concha 1, S. Ulukus 2
1 Princeton University, USA
2 AT&T Labs, USA
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S. Mann 1,2, M. Beach 1, P. Warr 1, J. McGeehan 1
1 University of Bristol, UK
2 Tait Electronics Ltd., NZ
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I. Barbounakis 1, P. Stavroulakis 1, J. Gardiner 2
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2 University of Bradford, UK
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A. Tzimas 1, G. Kalivas 2
1 THETA microelectronics S.A., GREECE
2 University of Patras, Greece
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1 AT&T Labs-Research, USA
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C. Xu, X. Yu
Southeast University, P.R. China

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 30 of 49

4 Multimedia, Networks and Systems 2009
41 Mobile multimedia Technology 2010

The Study of the Interconnection of GSM Mobile Communication Systems Over IP Based Network 2011
L. Chin 1, J. Wen 2, T. Liu 2
1 Shih-Chien University, Taiwan
2 National Chung Cheng University, Taiwan

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J. Kim
Kwangwoon University, Korea

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F. Li, N. Stol
Norwegian University (NTNU), Norway

Integrating IEEE 1394 as Infotainment Backbone into the Automotive Environment 2026
M. Rabel, A. Schmeiser, H. Grossmann
University of Ulm, Germany

General Modeling of Radio Resource Management Scheme for Multimedia Data Packet Transmission in Wireless Forward Channel 2032
J. Seok, Y. Chung, D. Cho
Korea Advanced Inst. of Sci. and Technology, Korea

A New Unequal Error Protection Scheme for Mobile Hierarchical Image Transmission System Using Multilevel Codes 2036
D. Yuan, Z. Li, F. Zhang
Shandong University, P.R. China

Reverse-link Analysis and Performance Evaluation of H.263 Video Transmission for Cellular DS/CDMA Systems in Frequency-selective Lognormal-Nakagami Fading 2041
C. Iskander, P. Mathiopoulos
The University of British Columbia, Canada

Fast Handover Schemes for Future Wireless IP Networks: A Proposal and Analysis 2046
A. Stephane, A. Aghvami
Centre for Telecommunications Research, UK

An Adaptive MPEG2-TS Packet Scheduling Discipline for Multimedia Broadcasting 2051
S. Teruhi, K. Nidaira, M. Nakayama, H. Suda
NTT Network Innovation Laboratories, Japan

Wireless Transmission of MPEG-4 Video: Performance Evaluation of Unequal Error Protection Over a Block Fading Channel 2056
M. Martini, M. Chiani
University of Bologna, Italy

On the Effect of Smart Antennas on Error Statistics and TCP Performance 2061
M. Zorzi 1, A. Acampora 2
1 Universita di Ferrara, Italy
2 UC San Diego, USA

Provision of Scalable Streaming Audio Services Over EGPRS 2066
S. Fabri, M. Farrugia, A. Kondoz
CCSR, University of Surrey, UK

Image Transmission with Multiuser Detection over DS/CDMA Channels 2071
H. Lee 1, P. Varshney 1, W. Ye 2
1 Syracuse University, USA
2 Galaxy Engineering, USA

Adaptive Segmentation Based Joint Source-Channel Coding for Wireless Video Transmission 2076
Y. Su 1, J. Lu 1, J. Wang 1, K. Letaief 2, J. Gu 2
1 Tsinghua University, P.R. China
2 Hong Kong University, Hong Kong

Fair Bandwidth Allocation for Multi-class of Adaptive Multimedia Services in Wireless/Mobile Networks 2081
Y. Xiao, C. Chen, Y. Wang
Wright State University, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 31 of 49

Adaptive Error Resilient Video Transmission over Wide-Band CDMA Networks 2086
C. Li 1, J. Lu 1, K. Letaief 2
1 Tsinghua University, P.R. China
2 HKUST, Hong Kong
Wireless Multimedia: Trends and Requirements 2091
A. Mihovska, J. Pereira, R. Prasad

42 Mobile data networks 2097

The Relation of CLR and blocking Probability for CBR Traffic in the Wireless ATM Access Network 2098
H. Lee 1, B. Lee 2
1 Yuhan College, Korea
2 Hankuk Aviaton University, Korea
Snoop TCP Performance Over GPRS 2103
J. Rendon, F. Casadevall, D. Serarols
Politecnic University of Catalonia, Spain
Modeling and Performance Evaluation of GPRS 2108
C. Foh 1, B. Meini 2, B. Wydrowski 1, M. Zukerman 1
1 The University of Melbourne, Australia
2 Universita di Pisa, Italy
Performance of Dynamic Frame Reservation Multiple Access-Dynamic Permission (DFRMA-DP) Protocol for Integrated Voice and Data Service in Wireless Communication Systems 2113
A. Thanasorravit, A. Charoenpanitkit, L. Wuttisittikulkij
Chulalongkorn University, Thailand
HiperLAN/2 Multihop Ad Hoc Communication by Multiple-Frequency Forwarding 2118
J. Peetz
Aachen University of Technology, Germany
The Performance of Hiperlane/2 Systems with Multiple Antennas 2125
M. Butler 1, A. Nix 1, D. Bull 1, P. Karlsson 2
1 University of Bristol, UK
2 Malmoe, Sweden
New Analytical Model for the TCP Throughput in Wireless Environment 2128
K. Naito 1, H. Okada 1, T. Yamazato 1, M. Katayama 1, A. Ogawa 2
1 Nagoya University, Japan
2 Meijo University, Japan
Service and Network Management Platforms for UMTS 2133
P. Demestichas, A. Taskaris, V. Stavroulaki, M. Theologou, N. Mitrou
National Technical Univ. of Athens, Greece
Bluetooth TCP Booster 2137
D. Melpignano, D. Siorpaes
Philips Research Monza, Italy
Modeling RF Impact on TCP/RLP in IS-95B 2142
I. Vukovic, J. Pettinger, J. Harris - IL
Motorola Inc., USA
Adaptive and Integrated Video Communications for Wireless ATM in WCDMA Systems 2147
X. Zhou, S. Zhao, X. Wang
Texas A&M University, USA
Waiting Time Analysis for the Generalized PEDF and HOLPRO Algorithms in a system with Heterogeneous Traffic 2152
A. Varsou, V. Poor
Princeton University, USA
Reliable Multicast Protocol by Sequence (RMPS) 2157
T. Yu 1, K. Kwak 2
1 SK Telecom, Korea
2 Inha University, Korea
Subscription Management and Charging for Value Added Services in UMTS Networks 2162
M. Koutsopoulou, C. Farmakis, E. Gazis
University of Athens, Greece

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 32 of 49

MODeRN: Multicast On-Demand QoS-based Routing in Wireless Networks 2167
N. Banerjee, S. Das
The University of Texax, USA
Dynamic QoS Provisioning in Wireless Data Networks 2172
S. Ganguly, D. Niculescu, B. Vickers
Rutgers University, USA
Performance Evaluation of TCP Throughput on Wireless Cellular Networks 2177
M. Miyoshi 1, M. Sugano 2, M. Murata 1
1 Osaka University, Japan
2 Osaka Prefecture College, Japan
A Differential-Service based approach to deliver multicast messages over mobile IP 2182
H. Gossain, D. Agrawal
University of Cincinnati, USA
A Comparison between Collaborative and Non-Collaborative Coexistence Mechanisms for Interference Mitigation in ISM Bands 2187
C. Chiasserini 1, R. Rao 2
1 Politecnico di Torino, Italy
2 University of California, USA

43 mobile computing networks 2192

Secure Communication in PCS 2193
M. Xu, S. Upadhyaya
SUNY at Buffalo, USA
TCP and GSM Link Layer Interactions: Implications for the Wireless Internet 2198
A. Wennstrom 1, J. Garcia 1, A. Brunstrom 1, J. Gustafsson 2
1 Karlstad University, Sweden
2 Telia Mobile AB, Sweden
Multicast Routing Considering Reliabiliy and Network Load in Wireless Ad-hoc Network 2203
C. Lee, H. Cho
KAIST, Korea
Cellular Traffic and Ethernet 2208
O. Panfilov
Motorola Inc., USA

45 Wireless Packet networks 2213

Performance Analysis of A Packet Scheduling Policy for a Ds - CDMA Cellular System 2214
A. Abrardo, G. Benelli, G.Giambene, D. Sennati
University degli Studi di Siena, Italy
The Study of the Interconnection of GSM Mobile Communication Systems over IP Based Network 2219
L. Chin 1, J. Wen 2, T. Liu 2
1 Shih-Chien University, Taiwan
2 National Chung Cheng University, Taiwan
Heavy Tail Jitter in Mobile Packet Networks 2224
D. Munoz 1,3, S. Villarreal 1, F. Houmayoun 2, K. Basu 2
1 ITESM, Mexico
2 Nortel Networks, USA
3 University of Texas, USA
Quality of Service Scheduling in Wireless Multimedia Communications 2229
D. Huang, J. Shi
Ericsson Inc., USA
High Speed Downlink Packet Access Performance 2234
R. Love, A. Ghosh, R. Nikides, L. Jalloul, M. Cudak, B. Classon
Motorola Inc., USA
New USF Codes for RT-EGPRS Systems 2239
J. Wu, C. Demetrescu, G. Foster
Motorola GSD, UK

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 33 of 49

Interactions between TCP and RLP Protocols in a Cellular System 2244
Z. Kostic, X. Qiu, L. Chang
AT&T Labs-Research, USA
An Adaptive Routing Protocol for Ad-hoc Networks using Multiple Disjoint Paths 2249
Y. Hwang, H. Lee, P. Varshney
Syracuse University, USA
Priority Schemes for Packet Data and Multi-Slot Operation on Edge 2254
M. Rivero Angeles, D. Lara-Rodriguez
CINVESTAV-IPN, Mexico
QoS Metrics for Performance Assessment in Integrated Terrestrial-Satellite Multimedia Platforms 2260
A. Iera 1, R. Ferraro 1, G. Tomasicchio 2
1 D.I.M.E.T.-University of Reggio Calabria, Italy
2 Alenia Spazio, Italy
A Study of TCP Performance Over Wireless Data Networks 2265
A. Srivastava, R. Friday, M. Ritter, W. Filippo
Metricom Inc., USA
Wireless Multimedia through Heterogeneous Satellite Networks 2270
A. Conti, A. Giorgetti
University of Bologna, Italy

5 Wireless Personal Communications 2275

51 IMT-2000 2276

VHE Provisioning in 3G Mobile Networks 2277
T. Dagiuklas 1, P. Philippopoulos 2
1 Intracom S.A., Greece
2 OTE-CONSULTING, Greece
On the Performance of Space-Time Blockcodes 2282
M. Stege, M. Bronzel, G. Fettweis
Dresden University of Technology, Germany
The Evolution of WCDMA Towards Higher Speed Downlink Packet Data Access 2287
S. Parkvall, E. Dahlman, P. Frenger, P. Beming, M. Persson
Ericsson Research, Sweden
Performance Evaluation of Start of Message Indicator Mechanism for Uplink Common Packet Channel in UMTS W-CDMA 2292
Y. Lee, S. Kwon, J. Choi, J. Park, S. Yi
LG Eelectronics R&D Complex, Korea
Multipath Interference Canceller for High-Speed Packet Transmission with Adaptive Modulation and Coding Scheme in W-CDMA Forward Link 2297
K. Higuchi, A. Fujiwara, M. Sawahashi
NTT Docomo Inc., Japan
Optimum Transmit Antenna Weight Generation Method for Adaptive Antenna Array Transmit Diversity in W-CDMA Forward Link 2302
S. Tanaka, T. Ihara, M. Sawahashi
NTT Docomo Inc., Japan
Multi-Rate Parallel Interference Cancellers for IMT-2000 3GPP Systems 2307
J. Kim, S. Oh, M. Sunwoo, M. Jung
Ajou University, Korea

52 Broadband mobile communication systems 2312

Rate-Adaptive Modulation Techniques for Indoor Wireless Infrared Links at Bit Rates of Wide Dynamic Range 2313
A. Garcia-Zambrana, A. Puerta-Notario
Universidad de Malaga, Spain
Optimizing UMTS Link Layer Parameters for a TCP Connection 2318
F. Lefevre, G. Vivier
Motorola Labs, France

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 34 of 49

Hiperlan/2 System Throughput and QOS with Interference Improving Strategies 2323
J. Rapp
Aachen University of Technology, Germany
Power Prediction on Broadband Channel 2328
M. Sternad, T. Ekman, A. Ahlen
Uppsala University, Sweden
Integrated 2-Hop Communication for the HiperLAN/2 Infrastructue Mode 2333
N. Esseling, A. Winkler
Aachen University of Technology, Germany
Soft Handoff Performances of 3-Sector and 6-Sector Multicell CDMA Systems 2338
W. Wang, I. Lu, S. Liu
Polytechnic University, USA

53 Cellular Technology 2343

The Optimization of Cell Sizes and Base Stations Power Level in Cell Planning 2344
I. Cavdar, O. Akcay
Karadeniz Technical University, Turkey
Optimal Transmission Parameters of Hopping Pilot Beacon for Inter-frequency Handoff in CDMA Mobile Cellular Networks 2349
W. Choi 1, J. Kim 2
1 Korea Telecomm Freetel, Korea
2 Kwangwoon University, Korea
Performance of an Adaptive Antenna System in Egprs Networks 2354
B. Lau, M. Berg, S. Andersson, B. Hagerman, M. Olsson
Ericsson Research, Sweden
Downlink Capacity of Multirate Multicell CDMA Wireless Local Loop System with Narrowbeam Antenna and SIR based Power Control 2359
Y. Zhou 2, F. Chin 1, Y. Liang 1, C. Ko 2
1 Center for Wireless Communications, Singapore
2 National University of Singapore, Singapore
Nonlinear Equalizer for CDMA in Fading Channels 2364
F. Gonzalez-Serrano, F. Escribano-Aparicio, J. Murillo-Feuntes
Universidad Carlos III de Madrid, Spain
Users Clustering Concept: Dyanamic Concentric Cells Performance in WCDMA System 2369
F. Goeusse 1, D. Calin 2, P. Sartori 3
1 Nortel Networks, Canada
2 Motorola Labs, France
3 Motorola Labs, France
Blind Channel Estimation Based on Subspace for Multicarrier CDMA 2374
J. Wu 1, Y. Wang 2, K. Cheng 1
1 The Chinese Univrsity of Hong Kong, Hong Kong
2 Tsinghua Univesity, P.R. China
A Novel Approach to Reproduce GSM Fieldtests in a controlled Laboratory Environment 2379
H. Joanni 1, A. Riemann 2, H. Wieker 3
1 CEGECOM S.A, Luxembourg
2 CETECOM GmbH, Germany
3 University of Saarland, Germany
Downlink Channel Covariance Matrix (DCCM) Estimation for FDD SDMA 2382
Y. Liang 1, F. Chin 1, A. Kot 2
1 Center for Wireless Communications, Singapore
2 School of EEE, Singapore
Downlink Radio Resource Management for IP Packet Services in UMTS 2387
I. Lopez 1, P. Ameigeiras 1, J. Wigard 2, P. Mogensen 2
1 Aalborg University, Denmark
2 Nokia Networks, Denemark
Characterization of the GPRS Radio Interface by Means of a Statistical Model 2392
J. Rendon, F. Casadevall, L. Garcia, R. Jimenez
Politecnic University of Catalonia, Spain

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 35 of 49

Reverse Link Capacity for CDMA2000 2397
S. Sarkar
QUALCOMM Inc., USA
Soft Handoff Analysis of Hierarchical CDMA Cellular Systems 2402
J. Kim 1, G. Stuber 1, B. Chung 2
1 Georgia Institute of Technology, USA
2 Korea Telecomm.com, Korea
Layer Selection Method Using Power Control in Hierarchical Cellular Systems 2407
S. Zhichun, W. Ying, Z. Ping, L.Baoling
Beijing University of Posts & Telecomm, P.R. China
The Realization of Breathing Function in HCS CDMA System Level Simulation 2412
W. Weidong, S. Dan, Z. Ping
Beijing University of Posts & Telecomm, P.R. China
Decision-Directed Channel Estimation for Multi-user OFDM Environments 2417
M. Munster, L. Hanzo
University of Southampton, UK
On the Differences between Uplink and Downlink Transmission in Code-Spread CDMA Systems 2421
A. Persson, J. Lassing, T. Ottosson, E. Strom
Chalmers University of Technology, Sweden
A Consideration on Adaptive Rake Receivers for Single-User MMSE Detection 2426
S. Kim 1, Y. Jung 2, J. Choi 3, Y. Lee 2
1 Radio & Broadcasting Tech. Lab. ETRI, Korea
2 KAIST, Korea
3 Adelaide University, Korea
Scrambling Code Planning for 3GPP W-CDMA Systems 2431
Y. Jung, Y. Lee
KAIST, Korea
Impact of the Variation in the Background Noise Floor on UMTS System Capacity 2435
T. Neubauer 1, E. Bonek 1,2
1 Technische Universitat Wien, Austria
2 Telekommunikation Wien, Austria
Performance Analysis of an Integrated Voice/Data CDMA System with Dynamic Admission/Access Control 2440
B. Bae, K. Jin, D. Cho
KAIST, Korea
Time Slot Allocation Scheme based on a Region Division in CDMA/TDD Systems 2445
S. Wie, D. Cho
KAIST, Korea
Comparative Study of TCM, TTCM, BICM and BICM-ID Schemes 2450
S. Ng, T. Liew, L. Yang, L. Hanzo
University of Southampton, UK
The Network Performance of Multi-Rate FDD-Mode UMTS 2455
J. Blogh, L. Hanzo
University of Southampton, UK
Acquisition Performance Study of Single- and Multi-carrier DS-CDMA Over Nakagami-m Fading Channels 2460
L. Yang, L. Hanzo
University of Southampton, UK
The use of Service Discovery to Support Reconfigurable Terminals 2465
G. Clemo, T. Farnham
Toshiba Research Europe Limited, UK
Mode Synchronization in Adaptive Coding and Interleaving Systems 2470
S. Lei, V. Lau
Hong Kong University, Hong Kong
Air-Interface for1XTREME/1XEV-DV 2474
A. Ghosh, L. Jalloul, B. Love, M. Cudak, B. Classon
Motorola Inc., USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 36 of 49

Performcance and Interference Analysis of WCDMA System 2479
D. Calin 1, F. Goeusse 2, P. Sartori 3
1 Motorola Labs, France
2 Nortel Networks, Canada
3 Motorola Labs, IL
Signal-to-Interference Ratio Estimation Based on Decision Feedback 2484
D. Jeske, A. Sampath
Lucent Technologies, USA
System Level Interference Mitigation Schemes in EGPRS: Mode-0 and Scheduling 2489
K. Balachandran 1, K. Chang 2, W. Luo 1, S. Nanda 3
1 Lucent Technologies, USA
2 Coree Networks, USA
3 Narad Networks, USA
Design of Optimal Energy Aware protocols for Wireless Sensor Networks 2494
V. Srinivasan, P. Nuggehalli, R. Rao
University of California, USA
Second Order Statistics of the SIR for Cellular Mobile Networks in the Presence of Correlated Co-channel Interferers 2499
F. Graziosi, L. Fuciarelli, F. Santucci
University of L'Aquila, Italy
Database Correlation Method for GSM Location 2504
H. Laitinen, J. Lahteenmaki, T. Nordstrom
VTT Information Technology, Finland
An Adaptive Time Slot Allocation Strategy for W-CDMA/TDD System 2509
J. Lee 1, Y. Han 1, D. Kwon 2
1 Information and Communications University, Korea
2 ETRI, Korea
Multi-Stage SIC Structure for Uplink UMTS Multiuser Receiver over Multipath Rayleigh Channels 2514
M. Ammar, T. Chonavel, S. Saoudi
ENST de Bretagne, France
Acknowledgment of 3GPP WCDMA Random and Packet Access Applying Space-Time Transmit-Diversity 2519
M. Schulist
Ericsson Eurolab, Germany
Decision-Feedback Blind Adaptive Multiuser Detector with MSE Equalizer in Synchronous DS-CDMA 2524
B. Choi 1, K. Kwack 2
1 LG R&D Complex LG Electronics Inc., Korea
2 Inha University, Korea
A Practical DCA implementation for GSM networks: Dynamic Frequency and Channel Assignment 2529
M. Salmenkaita, J. Gimenez, P. Tapia
Nokia Networks, Spain
A Novel Handoff Scheme in Integrated Voice/Data Cellular Systems 2534
J. Hailin, Z. Ruifeng, T. Zhenhui
Northern Jiaotong University, P.R. China
The Impact of Mobility on UMTS Network Planning 2539
R. Litjens
KPN Research, The Netherlands
A Proposal for Seamless Handovers in GSM Indoor Wireless Networks 2544
V. Di Claudio 1, F. Graziosi 2, F. Maurizio 2, F. Mecella 1, F. Santucci 2
1 Telit Networks S.P.a., Italy
2 University of L'Aquila, Italy
Soft Handoff Algorithm Parameter Optimization in Various Propagation Environments 2549
S.J. Hong, I.T. Lu
Center of Advanced Technology in Telecommunications, USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 37 of 49

54 Location Techniques 2554

An Automatic Drawing Method for Location Tracking in Wireless Networks 2555
I. Han, S. Choi, D. Cho
KAIST, Korea

Query Processing in a Cellular Network - a Database Approach 2560
S. Mitra, S. Das(Bit)
B.E. College, India

Velocity Estimation Using Adaptive Array Antennas 2565
Y. Chung, D. Cho
KAIST, Korea

Position Location Technologies Using Signal Strength in Cellular Systems 2570
R. Yamamoto, H. Matsutani, H. Matsuki, T. Oono, H. Ohtsuka
NTT Docomo Inc., Japan

Positioning Accuracy when Tracking UMTS Mobiles in Delay & Angular Dispersive Channels 2575
J. Vidal, M. Najar, M. Cabrera, R. Jativa
Universidad Politecnica de Catalunya, Spain

Analysis of Down-Link Location Methods for WCDMA and CDMA2000 2580
S. Wang, M. Green, M. Malkawi
Nokia Research Center, USA

Efective Handoff Method Using Mobile Location Information 2585
S. Wang, C. Wu
Nokia Research Center, USA

A New Metric for Analyzing Multi-Step Paging Schemes in Mobile Networks 2590
S. Mishra 1, O. Tonguz 2
1 State University of New York, USA
2 Carnegie Mellon University, USA

Replication of Location Information in Mobile Networks Using Sliding-Frames 2595
H. Lin, C. Ho
National Tsing Hua University, Taiwan

Optimal Geolocation Updating for Location Aware Service Provisioning in Wireless Networks 2600
S. Tekinay, A. Catovic
New Jersey Inst. of Technology, USA

Calibration of NLOS Error for Positioning Systems 2605
Y. Jeong 1, H. You 2, C. Lee 1
1 Yonsei University, Korea
2 Access Network Lab., Korea

Mocont: A New System for Automatic Identification and Location of Containers 2609
V. Recagno 1, A. Derito 2, R. Nurchi 2
1 SCIRO S.r.l, Italy
2 CRT- Universita di Genova, Italy

55 2.5 G and 3G system performance 2614

Energy Efficiency of Radio Link Protocols in 3GPP Systems 2615
C. Chiasserini, M. Meo
Politecnico di Torino, Italy

Forward Link Capacity of 3G Wideband CDMA System with Mixed Traffic Sources 2620
W. Choi 1, J. Kim 2
1 Korea Telecomm Freetel, Korea
2 Kwangwoon University, Korea

MAC Scheduling for Uplink Transmission in UMTS WCDMA 2625
K. Dimou, P. Godlewski
Ecole Nationale Superieure de Telecommunications, France

System Capacity with Transmit Diversity Techniques in GERAN 2630
C. Tidestav 1, K. Zangi 2, F. Kronestedt 1, D. Hui 2, M. Eriksson 1, J. Cheng 2
1 Ericsson Radio Systems AB, Sweden
2 Ericsson Inc., USA

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 38 of 49

Mixed Service Management with QoS Control for GERAN - The GSM/EDGE Radio Access Network 2635
A. Furuskar 1, P. de Bruin 2, C. Johansson 2, A. Simonsson 2
1 Royal Institute of Technology, Sweden
2 Ericsson Research, Sweden
Simulated and Measured Performance of 4-Branch Uplink Reception in WCDMA 2640
H. Holma, A. Tolli
Nokia Networks, Finland
QOS Scheduling of Mixed Priority Non Real-Time Traffic 2645
K. Johnsson, D. Cox
Stanford University, USA
Transmit Diversity for High Data-rates in WCDMA Indoor Systems 2650
A. Johansson, K. Johansson, D. Astely
Nokia Networks, Sweden
Impact of FDD/TDD Co-existence on Overall UMTS System Performance 2655
T. Lee, C. Faure, D. Grandblaise
Motorola Labs, France
Troughput Analysis of Link Adaptation in Interference-Limited Cellular Systems 2660
N. Mehta, A. Goldsmith
Stanford University, USA
Performance of Lucent CDMA2000 3G1X Packet Data Experimental System 2665
G. Li, M. Lu, M. Meyers, D. Patel, J. Stekas
Lucent Technologies Optimus, USA
Synchronization Strategies for GSM/EDGE Networks 2670
S. Craig, H. Nyberg, E. Edgren, S. Magnusson
Ericsson Radio Systems AB, Sweden
Channel Estimation Algorithms for Third Generation W-CDMA Communication Systems 2675
K. Qaraqe 1, S. Roe 2
1 Tality Corporation, USA
2 Cisco Systems, Inc., USA
A Comparatvie Study of Power Control Strategies for Soft Handover in UTRA FDD WCDMA System 2680
S. Akhtar, S. Malik, D. Zeghlache
Institut National des Telecommunications, France
Implementation of Channel Decoding and other Bit Rate Processing Algorithms for 3rd Generation W-CDMA Mobile Terminals 2685
J. Woodard, T. Fisher-Jeffes
UbiNetics Ltd., UK
Performance of Downlink Shared Channels in WCDMA Radio Networks 2690
K. Helmersson, G. Bark
Ericsson Radio Systems AB, Sweden
Performance of a Multi-Service GSM/GPRS-Capable Network under Various Loading Conditions 2695
C. Konstantinopoulou, K. Koutsopoulos, P. Demestichas, M. Theologou
National Technical University of Athens, Greece
Simulated Performance of W-CDMA Random Access Channel 2700
P. Choudhary, A. Ghosh, L. Jalloul
Motorola Inc., USA
Analysis of IPDL Patterns for Increased Signal Detection Probability in UMTS 2705
N. Thomas, D. Cruickshank, D. Laurenson
The University of Edinburgh, UK
Evaluation of Load Control Strategies in an Utra/FDD Network 2710
W. Rave, T. Kohler, J. Voigt, G. Fettweis
Dresden University of Technology, Germany
Fair Scheduling of Integrated IP and ATM Based Traffic in 3G Mobile Communication Networks 2715
C. Dou, S. Jiang
National Yunlin University of Sci. and Tech., Taiwan

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 39 of 49

Performance of Hybrid ARQ Techniques for WCDMA High Data Rates 2720
E. Malkamaki, D. Mathew, S. Hamalainen
Nokia Research Center, Finland
UMTS Air Interface Voice/Data Capacity- Part 1: Reverse link analysis 2725
Q. Zhang, O. Yue
Lucent Technologies, USA
UMTS Air Interface Voice/Data Capacity - Part 2: Forward Link Analysis 2730
Q. Zhang
Lucent Technologies, USA
Overlay of CDMA2000 on IS-136 2735
J. Castaneda-Camacho, C. Mira-Gonzalez, D. Lara-Rodriguez
CINVESTAV-IPN, Mexico
Performance Evaluation of Beamforming Using Pilot Channel in CDMA2000 Reverse Link 2740
S. Lim, C. Yoo, S. Kim
Hyundai Electronics Industries Co. Ltd., Korea
Implementation of Chip Rate Processing Algorithms for 3rd Generation W-CDMA Mobile Terminals 2745
T. Keller, D. Giancola
UbiNetics Ltd., UK

56 Radio Network Design 2750

Estimation and Prediction of the Local Mean Signal Power in Mobile Systems 2751
D. Avidor, S. Mukherjee
Lucent Technologies, USA
Channel Allocation Tiering (CHAT): Taking GSM/EDGE Networks Beyond One Reuse 2756
S. Craig, M. Berg, A. Brostrom, F. Kronestedt, M. Olsson, P. Schramm
Ericsson Radio Systems AB, Sweden
UMTS Border Planning Issues 2761
C. Faure 1, T. Lee 2, D. Boscovic 3
1 Alcatel Espace, France
2 Vodafone, France
3 Motorola Labs, France
Highway Traffic Models for Wireless Networks 2766
G. Lizee 1, A. Fapojuwo 2
1 The University of Calgary, USA
2 Nortel Networks, USA
Dynamic Simulator for Studying WCDMA Radio Network Performance 2771
R. Hoppe, H. Buddendick, G. Wolfle, F. Landstrofer
University of Stutgart, Germany
Co-existence EMC Aspects of Dect Wireless Local Loops (WLL) and Dect Cordless Telephones 2776
D. Bem, M. Nawrocki, T. Wieckowski, R. Zielinski
Wroclaw University of Technology, Poland
An Analysis of Effect of Wireless Network by a Repeater in CDMA System 2781
S. Park 1, W. Kim 2, B. Kwon 1
1 SK TELLECOM, Korea
2 Chungnam National University, Korea
Adaptive Coverage for UMTS Macrocells Based on Situation Awareness 2786
S. Sharma, A. Spilling, A. Nix
University of Bristol, UK
Reduction of Co-Channel Inerference by Optimum Distributed of Transmitters Powers 2791
M. Wnuk, E. Sedek, C. Ziolkowski
Military University of Technology, Poland
Overlay of a Wireless Local Loop System on CDMA2000 Cellular System 2795
J. Castaneda-Camacho 1, D. Lara-Rodriguez 1, M. Lara 1, D. Munoz-Rodriguez 2
1 CINVESTAV-IPN, Mexico
2 ITESM Monterrey, Mexico

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 40 of 49

Static WCDMA System Simulator for Indoor Environments 2800
K. Tigerstedt, K. Heiska
Nokia Networks, Finland
Network Synchronization for UTRA TDD 2804
A. Hulbert 1, M. Purat 2, S. Oestreich 2
1 Roke Manor Resrarch Ltd., Germany
2 Siemens AG, Germany
Automatic Cell Planning of Broadband Fixed Wireless Networks 2809
S. Allen, S. Hurley, R. Taplin, R. Whitaker
Cardiff University, UK
An ISM Band CMOS Integrated Wireless Telemetry Transceiver 2813
J. Kim, R. Harjani
University of Minnesota, USA
Performance of a Microcell with Optimal Power Allocation for Multiple Class Trafic in Hierarchically Structured Cellular CDMA Systems 2818
C. Joh, K. Kim, Y. Han
Information and Communication University, Korea
Investigations on the Throughput in EDGE- and GPRS- Radio Networks 2823
E. Hallmann, R. Helmchen
Siemens AG, Germany
Optimizing Base Station Siting in UMTS Networks 2828
E. Amaldi, A. Capone, F. Malucelli
Politecnico di Milano, Italy
Longevity of Routes in Mobile Ad hoc Networks 2833
D. Turgut, S. Das, M. Chatterjee
The University of Texax, USA
Energy Efficiency in Energy-Limited Wireless Networks for Session-Based Multicasting 2838
J. Wieselthier 1, G. Nguyen 1, A. Ephremides 2
1 Naval Research Laboratory, USA
2 University of Marylang, USA
Hierarchical Markov Model for Burst Error Analysis in Wireless Communications 2843
T. Tao 1, J. Lu 1, J. Chuang 2
1 Tsinghua University, P.R. China
2 AT&T Labs Research, USA

57 Power control Techniques 2848

Dynamic Uplink Power Control for Cellular Radio Systems over Fast Fading Channel 2849
L. Dong, G. Xu
The University of Texax, USA
On the Convergence of Linear Power Control for Cellular Radio Systems 2854
R. Jantti 1, S. Kim 2
1 Helsinki University of Technology, Finland
2 Information and Communication University, Korea
Impact of Mobility and Closed-Loop Power Control to Received Signal Statistics in Rayleigh Fading Channels 2859
P. Pirinen
University of Oulu, Finland
Enhanced Predictive Fast Power Control for 3G Systems 2864
I. Virtej 1, O. Kansanen 2, H. Koivo 2
1 Nokia Research Center, Finland
2 Helsinki University of Technology, Finland
A Power Control Algorithm for CDMA Cellular System 2869
W. Weidong, S. Zhichun, S. Dan, Z. Ping
Beijing University of Posts & Telecomm, P.R. China
Enhanced CDMA Transmission with Mulitple Antennas and Joint Power Control 2873
J. Wu, S. Affes, P. Mermelstein
University of Quebec, Canada

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 41 of 49

New Adaptive Power Control Scheme Baed on Mobile Velocity in Wireless Mobile Communication Systems 2878
H. Lee, D. Cho
KAIST, Korea
Performance of Optimum Transmitter Power Control in Multimedia CDMA Cellular Mobile Systems 2883
J. Wen, J. Sheu, J. Chen
National Chung Cheng University, P.R. China
Optimum Power and Rate Allocation Strategies for Multiple Acess Fading Channels 2888
S. Vishwanath, S. Jafar, A. Goldsmith
Stanford University, USA
Two-Mode Fast Power Control For WCDMA Systems 2893
M. Rintamaki 1, I. Virtej 2, H. Koivo 1
1 Helsinki University of Technology, Finland
2 Nokia Group, Finland
A Quality-based Downlink Power Control Algorithm for General Packet Radio Service (GPRS) 2898
K. Budka, A. Das, K. Murti
Lucent Technologies, USA
Zone-based Power Control Scheme for Multi-cell Interference Environments 2903
S. Yun, S. Bae, J. Lim
Ajou University, Korea
Convergence of UTRA TDD Uplink Power Control 2908
J. Kurjenniemi 1, S. Hamalainen 2, T. Ristaniemi 1, O. Lehtinen 3, P. Patronen 4
1 University of Jyvaskyla, Finland
2 Nokia Research Center, Finland
3 Nokia Mobile Phones, Finland
4 Nokia Networks, Finland
Uplink Transmit Power Control during Soft Handoff in DS/CDMA Systems 2913
S. Park 1, D. Sung 1, C. Kang 2, S. Shin 2
1 KAIST, Korea
2 ETRI, Korea

6 Mobile Satellite Communications 2918

61 Mobile Satellite Communications 2919

Lower Bound on the Average Power Consumption of CDMA Mobile Wireless Users Communcating via Satellite 2920
S. Arnon
Ben Gurion University, Israel
Maximum Information Rate for Satellite Down Link Communication with Mobile Users 2925
S. Arnon
Ben Gurion University, Israel
Prediction of coverage for a LEO system in MID- and high- latitude urban Areas using a photogrammetric techique 2930
L. Braten 1, C. Amaya 2, D. Rogers 2
1 Telenor Resrarch and Development, Norway
2 Communications Research Centre Canada, Canada
Noncoherent Sequence Detection of Trellis Coded CPFSK Over Rician Channels 2935
C. Teng, J. Fonseka, I. Korn
The University of Texax, USA
Un-Phased Equal Gain Combining of CPFSK Signals with Differential Phase Detection 2940
J. Fonseka, I. Korn
The University of Texax, USA
Turbo-Coded OFDM System for a Mobile Satellite Broadcasting System 2945
J. Kim
Kwangwoon University, Korea
Satellite Mobile Packet System Characteristics and Performance Evaluation 2950
T. Yamashita, M. Inoue, Y. Nishi
NTT Docomo Inc., Japan

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 42 of 49

Performance Evaluation of ARQ Operations with Inter-Satellite Links 2955
A. Chen 1, Y. Yao 2, C. Chang 1
1 San Diego State University, USA
2 Stevens Inst. of Technology, USA
Development of a New Method for Computing Interference between Low Earth Orbit Satellite Networks and Terrestrial Radiocommunication Systems 2960
R. Chavez Santiago, V. Kontorovich, M. Lara- Barron
CINVESTAV-IPN, Mexico
A Multistep Power Control Algorithm for Land Mobile Satellite with High Dynamic Channel 2965
W. Li, C. Law, V. Dubey
Nanyang Technological University, Singapore
Location of Third Generation Mobile Devices: A comparison Between Terrestrial and Satellite Positioning Systems 2970
D. Porcino
Philips Research Labs, UK
A Channel Reservation Algorithm for Handover Issues in LEO Satellite Systems Based on a Satellite-fixed Cell Coverage 2975
L. Boukhatem 1,2, D. Gaiti 2,3, G. Pujolle 2
1 Universite de Versailles, France
2 Universite de Paris 6, France
3 Universite de Technologie de Troyes, France
Intermediate Frequency PN Code Acquisition Employing Sequential Detection Algorithm for Satellite CDMA System 2980
M. Yuchu, G. Xuemai, Z. Naitong
Harbin Institute of Technology, P.R. China
Analysis and Performance Evaluation of Dynamic Channel Reservation Techniques for Leo Mobile Satellite Systems 2985
Z. Wang, T. Mathiopoulos
The University of British Columbia, Canada
Building Empirical Models of Sattellite-Mobile Channels 2990
M. Pourmir, A. Beffani, L. Husson, J. Dany
SUPELEC Service Radioelectricite et Electronique, France
Adaptive Scheme for M-DPSK Signals in LEO Satellite Communications 2993
F. Nunes, J. Leitao
Institut de Telecommunications, Portugal
Mobile Communications based on an Emitter/Receiver Dynamics Model 2998
F. Sousa, J. Leitao
Institut de Telecommunications, Portugal
Frequency Estimation and Tracking for Low Earth Orbit Satellites 3003
E. Aboutanios, S. Reisenfeld
University of Sydney, Australia
A Two-Level, Multi-State Markov Model for Satellite Propagation Channels 3005
J. Hsieh 1, H. Lin 2, C. Yang 2
1 National Tsing Hua University, ROC
2 National Taipei University of Tech., ROC

63 Navigation 3010

Using Diversity of Satellite Channels for Navigation Systems 3011
R. Bischoff 1, M. Namokel 1, W. Schulz 1, G. Heinrichs 2
1 University of Paderborn, Germany
2 MAN Technologie AG, Germany

7 Transportation Applications 3016
71 Intelligent Transportation system 3017

Ventilation Control for Improved Cabin Air Quality and Vehicle Safety 3018
K. Galatsis, W. Wlodarski, Y. Li, K. Kalantar-zadeh
RMIT University, Australia

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 43 of 49

A Method of Vehicle Classification using Models and Neural Networks 3022
W. Wei, Q. Zhang, M. Wang,
Changsha Communications University, P.R China
User Modeling and Uplink Scheduling in IP-based ITS Network 3027
F. Gotoh, S. Uno
Motorola Japan Research Lab, Japan
State Estimation for Vehicle Maneuvering Control with Stochastic Model in Communication Network 3032
J. Choi, T. Fang
Pusan National University, Korea
Pros and Cons of Emerging Event Data Recorders (EDRs) in the Highway Mode of Transportation 3037
T. Kowalick
Click Inc. Transportation Safety Technology, USA

8 Applications 3042

81 wireless Internet methods 3043

Capacity Analysis of TDD Cell Sharing Underutilized FDD Uplink 3044
D. Kim 1, P. Song 1, C. Kang 2
1 ETRI, Korea
2 Korea University, Korea
Necessity of an Emulator to Validate New Resources Allocation Protocols 3049
M. Bourgois 3, E. Vivier 1, M. Terre 2, N. Bret 3, B. Ridard 3
1 Institut Superierur d'Electronique de Paris, France
2 Conservatoire National des Arts et Metiers, France
3 COGISYS, France

83 software agents 3053

An Agent-Based Framework with QOS-Aware Content Negotiation for Gateway-Based Nomadic Applications 3054
C. Dou, B. Shih, H. Wu
National Yunlin Univ. of Sci. and Tech., Taiwan

84 Hybrid solutions 3059

Multipath Hardware and Software Mobile Channel Simulator 3060
C. Briso- Rodriguez, J. Alonso-Montes
Universidad Politecnica de Madrid, Spain
Point-to-multipoint ARQ Protocol with Efficient Acknowledgement Transmission 3064
M. Lott 1, A. Kramling 2, E. Schulz 1
1 Siemens AG, Germany
2 Aachen University of Technology, Germany

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 44 of 49

Database Correlation Method for GSM Location

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Abstract

Cellular location methods based on angle of arrival (AOA) or time difference (e.g. E-OTD) measurements assume line-of-sight propagation between base stations and the mobile station. This assumption is not valid in urban microcellular environments. We present a Database Correlation Method (DCM) that can utilize any location-dependent signals available in cellular systems. This method works best in densely built urban areas. An application of DCM to GSM, using signal strength measurements, is described and trial results from urban and suburban environments are given. Comparison with AOA and E-OTD trials shows that DCM is a competitive alternative for GSM location in urban and suburban environments.

1. Introduction

Cellular location techniques have received a lot of attention recently. This is due to the great number of new value-added services that can be realized using location technology. Also, the requirement set by the United States Federal Communications Commission (FCC) to locate emergency calls according to certain accuracy criteria by October 2001 has been a driver for the development of location methods. Several techniques have been tested in trials and also in commercial networks. However, it is difficult to estimate which of the competing techniques is the best in terms of accuracy, or which of them fulfil the FCC requirement. This is due to the fact that the accuracy of each location method can not be presented by a single number but by a statistical error distribution, and a large amount of experimental data must be collected in order to find the distribution. Furthermore, the accuracy of any cellular location method is dependent on the network density as well as radio propagation effects.

Most of the proposed methods aiming at higher accuracy than simple cell identification are based either on signal time delay or angle of arrival measurements. Angle of arrival (AOA) technique requires antenna arrays at base stations [1], which makes it expensive to implement in current networks and impractical in microcell sites. GSM standardization includes two methods based on cellular signal timing measurements: uplink Time of Arrival (TOA) and downlink Enhanced Observed Time Difference (E-OTD) [2]. Also these methods require new hardware to the network, and E-OTD requires modifications to handsets as well. Another drawback of these methods is the narrow bandwidth of GSM signals, which does not allow highly accurate signal timing measurements.

In general, the performance of AOA and signal timing based methods is not optimal in densely built urban environments. With these methods, the location of the mobile station (MS) is calculated under the assumption of line-of-sight propagation between the base stations (BSs) and the MS. This assumption is not valid in city centers where high buildings often block the line of sight and signal propagates with less attenuation along street canyons than through the buildings. Moreover, severe multipath propagation characteristic to these environments makes it difficult to detect the angle of arrival or time of arrival of the direct component i.e. the resolution of these measurements is not as good as in more open propagation environments. Consequently, these methods can not fully exploit the dense cellular network of urban environments.

Some location methods, e.g. Enhanced Signal Strength method and Location Fingerprinting [3] have been designed to obtain optimal performance in urban environments. Such methods are important because many foreseen location applications will be used in urban environments and the accuracy requirement in such an environment is typically higher than in an open rural environment. In this paper, we present a new method [4], referred to as the Database Correlation Method (DCM), which can be implemented in GSM using the signal strength measurements performed by all GSM handsets. A common feature of all cellular location methods that are

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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 45 of 49

designed to perform well in urban environments is that they can not rely on the assumption of line-of-sight propagation. As opposed to Location Fingerprinting, DCM is an approach that requires no new hardware at BS sites because it takes advantage of the measurements available in the system. The difference between Enhanced Signal Strength method and our DCM trial is that we have obtained the signal strength database through measurements instead of computations.

2. Database Correlation Method

2.1. Generic location method

DCM is a general location method that can be applied to any cellular or WLAN network. The key idea is to store the signal information seen by a MS, from the whole coverage area of the location system, in a database that is used by a location server. The database should contain signal information samples, called fingerprints, with a resolution comparable to the accuracy that can be achieved with the method, and this resolution may vary in different environments. Depending on the particular cellular system, the signal fingerprints could include signal strength, signal time delay, or even channel impulse response. Any location-dependent signal information that can be measured by the MS is useful for the DCM technique. Also, it is possible to use measurements performed by the network as well as by the MS. When the MS needs to be located, the necessary measurements are performed and transmitted to the location server. The location server then calculates the MS location by comparing the transmitted fingerprint and the fingerprints of the database. The architecture of a DCM location system is illustrated in Figure 1. It is highlighted that DCM can be implemented in any wireless system, the MS only needs to be able to transmit a location-dependent fingerprint to the location server. This fingerprint may consist of signals measured from GSM, UMTS, WLAN, or GPS system also. The location server must be powerful enough to process all location requests in a reasonable time. In a large-scale implementation, this may require distributed processing.

The major effort in applying DCM is the creation and maintenance of the database. The signal fingerprints for the database can be collected either by measurements or by a computational network planning tool. Measurements are more laborious but produce more accurate fingerprint data. Also a combination of measured and computed fingerprints can be used. The compensation for the effort to build the database is an optimal location accuracy in environments where the assumption of line-of-sight propagation is not valid, e.g. in dense urban and indoor environments. The only assumption is that the database contains up-to-date data. However, minor changes in the

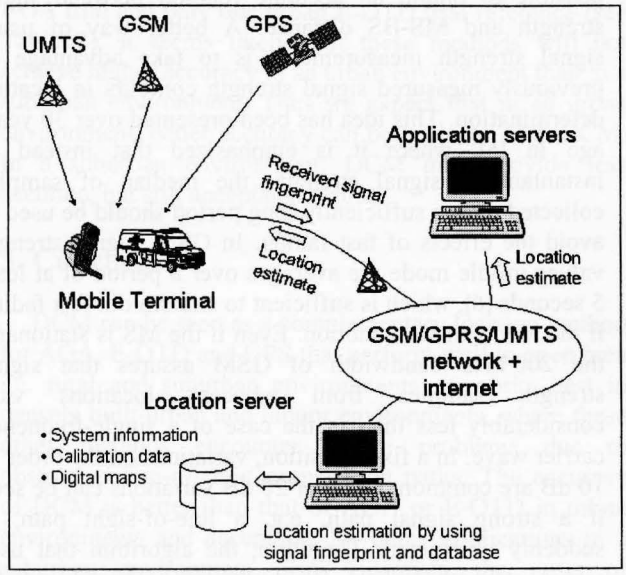


Figure 1. Architecture of DCM system.

network or propagation environment, e.g. new buildings, will only be seen as lowered location accuracy if the database is not updated. Also, it should be noted that similar information that is contained in the DCM database is also needed in network planning. Therefore, the creation and maintenance of the database also support network planning.

2.2. Application to GSM

The essential location-dependent parameters defined in GSM standard are Location Area Code (LAC), serving cell ID, timing advance (TA), and the measured signal strength of the serving cell and its neighbors. In dedicated mode (call on) all these parameters are known to both the MS and the network (signal strength measurements from up to 6 neighbor cells are reported from the MS back to the network). However, in idle mode only the LAC is known to the network. The MS, on the other hand, continuously makes signal strength measurements and also knows the cell ID of the strongest cell. Thus, in order to locate an idle-mode MS using these parameters, the MS must be able to transmit the available parameters to the location server. GSM handsets with the capability to send these measurements through SMS are already available.

LAC, cell ID, and TA, which is known with a resolution of 554 m in dedicated mode only, can be used for rough positioning. For more accurate positioning, it is possible to use signal strength measurements to estimate the distance between the MS and each BS, based on some path loss model. However, this is an unreliable way to measure distance since signal strength variations caused by shadowing will introduce large errors in distance estimates. Especially in urban environments it is seldom

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 46 of 49

possible to obtain an accurate relation between signal strength and MS-BS distance. A better way of using signal strength measurements is to take advantage of previously measured signal strength contours in location determination. This idea has been presented over 30 years ago in [5], where it is emphasized that instead of instantaneous signal strength, the median of samples collected over a sufficiently long period should be used to avoid the effects of fast fading. In GSM, signal strength values in idle mode are averages over a period of at least 5 seconds [6], which is sufficient to smooth out fast fading if the MS is in slow motion. Even if the MS is stationary, the 200 kHz bandwidth of GSM assures that signal strength samples from adjacent locations vary considerably less than in the case of a single-frequency carrier wave. In a fixed position, variations on the order of 10 dB are common, but over 20 dB variations can be seen if a strong signal path, e.g. a line-of-sight path, is suddenly obstructed. Therefore, the algorithm that uses signal strength values for positioning should not be sensitive to such variations.

We have used a simple correlation-type algorithm for finding the best match between the fingerprint to be located and the fingerprints of the database. A difference between the fingerprint to be located and each fingerprint of the database is calculated as

$$d(k) = \sum_i (f_i - g_i(k))^2 + p(k)$$

where f_i is the signal strength of the request fingerprint on the i^{th} Broadcast Control Channel, $g_i(k)$ is the signal strength of k^{th} database fingerprint on the same channel, and the summation is taken over channels that are found in both fingerprints. Each channel that is found in only one of the fingerprints contributes to the penalty term $p(k)$. The coordinates of the database fingerprint that minimizes this difference are returned as the location result. It should be noted that the database search can be limited, based on LAC and cell ID, to a relatively small area. Also other types of algorithms, e.g. pattern matching, could be used.

3. Location trial

We have performed a location trial in two environments: a densely built urban environment (the center of Helsinki, Finland) and a suburban environment (the campus area of Otaniemi in Espoo, Finland). The trial area was approximately 3 km^2 in urban and 1.4 km^2 in suburban environment. In both cases, measurements were performed with a standard GSM phone, which was attached to the dashboard inside a car and connected to a laptop PC. Part of the urban measurements was performed on foot. In all measurements, the phone was in idle mode. The street grid of the trial area was covered once in order to create the database, by collecting on the average two measured fingerprints per second. Reference coordinates for the measured fingerprints were obtained by mouse-clicking marker points on the laptop PC each time the car stopped, started moving, turned, or passed a street corner. Between the marker points, reference coordinates were calculated assuming that the car moved with constant velocity. It was estimated that the errors in reference coordinates caused by the non-constant velocity and inaccurate marker coordinates should be below 20 meters.

During the measurements, the speed of the car was kept below 45 km/h in order to keep the distance the MS moves in 5 seconds, which is approximately the period over which the signal strength is averaged, reasonable. It was observed that lower speed leads to better location accuracy. Furthermore, when inserted in the database, the coordinates for a measured fingerprint were taken to be the reference coordinates of an earlier sample to compensate for the averaging time. We also tried averaging the fingerprints of the database with various grid spacings. If the grid spacing is not too large, averaging has no effect on location accuracy, but reduces the amount of fingerprints in the database and thus processing speed for one location request.

In addition to the measurements forming the database, we drove test routes through the trial area in order to evaluate the location accuracy of our method. In the urban area, three test routes of total length 15 km and in the suburban area one 1.5-km long test route were driven. The lengths of all test routes and the numbers of fingerprints collected are summarized in Table 1. Again, the reference coordinates for a sample fingerprint were taken from an earlier sample to compensate for the delay caused by averaging. This simulates the positioning of a stationary MS. Obviously, such compensation can not be done if a moving vehicle is to be located or tracked in real time. In this case, a tracking algorithm can be used to estimate the current location, but in a one-shot location the averaging delay causes an error proportional to the speed of the vehicle. However, this is true for any cellular location method due to the unavoidable delays in measurements, signaling, and location calculation.

Table 1. Test route lengths and numbers of collected fingerprints.

test route	length	fingerprints
urban 1	1450 m	389
urban 2	8600 m	3604
urban 3	4550 m	1240
suburban	3500 m	766

Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 47 of 49

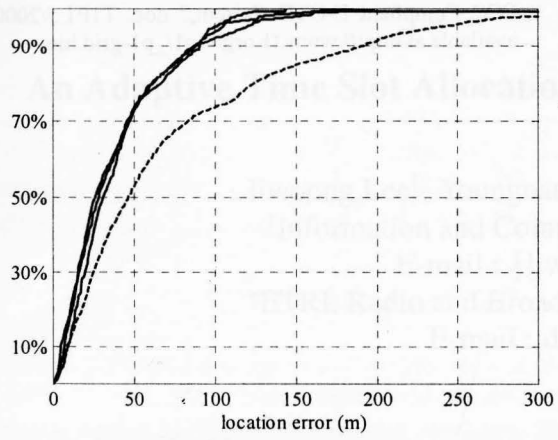


Figure 2. Cumulative location error distribution in urban test routes (solid curves) and suburban test route (dashed curve).

4. Trial results

The cumulative distributions of location error along the test routes are shown in Figure 2. It is seen that the error distribution in the urban test routes does not vary much, but there is a clear difference between urban and suburban accuracy. There are two factors that cause the higher accuracy in the urban environment: denser network and building shadowing. In an urban microcellular environment, the difference in signal strength values on different sides of a (heavy) building is so large that it exceeds random variations caused by e.g. antenna orientation or body shadowing. The signal propagates along street canyons and, as a consequence, the location error is typically directed along the street.

A comparison with the published results from AOA [1] and E-OTD [7,8] trials is shown in Table 2. The results from the two suburban E-OTD trials differ somewhat surprisingly, but the more accurate results [8] are very close to the AOA results [1]. Nevertheless, it can be observed that DCM can be as accurate in an urban environment as AOA or E-OTD in a suburban environment. Although we have no data from an urban AOA trial and only one urban E-OTD trial reference (see Table 2), it seems likely that these methods will not achieve higher accuracy in an urban environment than in a suburban environment. Thus we expect that in an urban environment, better accuracy can be achieved with DCM. In a suburban environment, DCM may provide less accurate, but still acceptable results.

Table 2. Comparison of DCM, AOA [1], and E-OTD [7,8] trial results. 67th and 90th percentiles are shown in all except the last row.

Trial	67%	90%
DCM urban	44 m	90 m
E-OTD urban [7]	141 m	237 m
DCM suburban	74 m	190 m
AOA suburban [1]	45 m	89 m
E-OTD suburban [7]	125 m	231 m
E-OTD suburban [8]	50 m (69%)	100 m (97%)

5. Conclusions

DCM can be seen as a complementary location method for AOA, E-OTD and GPS that perform well in open area i.e. rural and suburban environments. It works best in densely built urban and indoor environments, where these other methods encounter severe problems due to obstructed line-of-sight propagation paths. The accuracy of DCM is better than that of AOA or E-OTD in urban environments and acceptable for many applications in a suburban environment also. However, the costs of applying DCM are lower than for these two methods, since no modifications to the cellular network are needed. The only major cost comes from the construction and maintenance of the database. However, the database can be utilized in network planning and monitoring also.

With DCM, it is possible to use any location-dependent measurements available in the system. Therefore it would be possible to enhance the accuracy of E-OTD in urban environments using DCM. Also, DCM can be used for accurate positioning in WLAN (indoor) and UMTS (urban and indoor) systems.

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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 48 of 49

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Geoscope Exhibit 2029
Apple v. Geoscope
IPR2024-00031, Page 49 of 49