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(54) **COMBINED CLOSED LOOP/OPEN LOOP
POWER CONTROL IN A TIME DIVISION
DUPLEX COMMUNICATION SYSTEM**

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(22) Filed: **Mar. 21, 2000**

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H04B 1/713**

(52) U.S. Cl. **375/130; 375/295; 455/522;
370/342**

(58) Field of Search **375/130, 140,
375/295; 455/522, 69; 370/342, 252**

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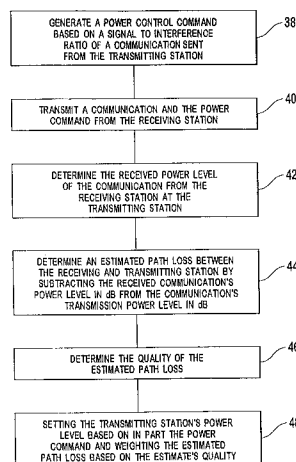
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(57) **ABSTRACT**

Combined closed loop/open loop power control controls
transmission power levels in a spread spectrum time division
duplex communication station. The first station transmits
power commands based on in part a reception quality of the
received communications. The first station transmits a first
communication having transmission power commands
based on in part a reception quality of the received com-
munications. The first station transmits a first communica-
tion having a transmission power level in a first time slot.
The second station received the first communication and the
power commands. A power level of the first communication
as received is measured. A path loss estimate is determined
based on in part the measured received first communication
power level and the first communication transmission power
level. The second station transmits a first communication to
the first station in a first time slot. The second communica-
tion transmission power level is set based on in part the path
loss estimate weighted by a factor and power commands.
The factor is a function of a time separation of the first and
second time slots.

23 Claims, 7 Drawing Sheets



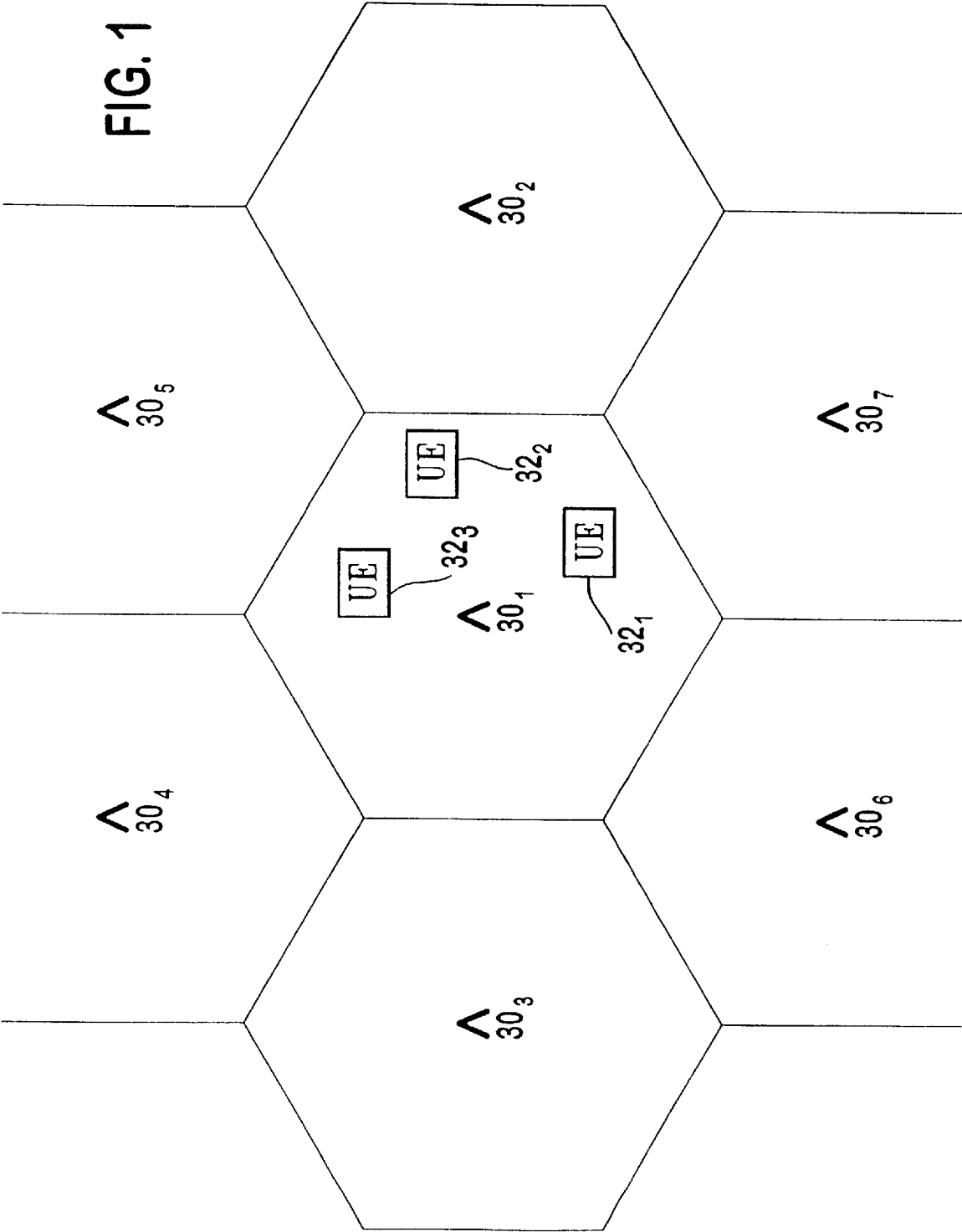


FIG. 2

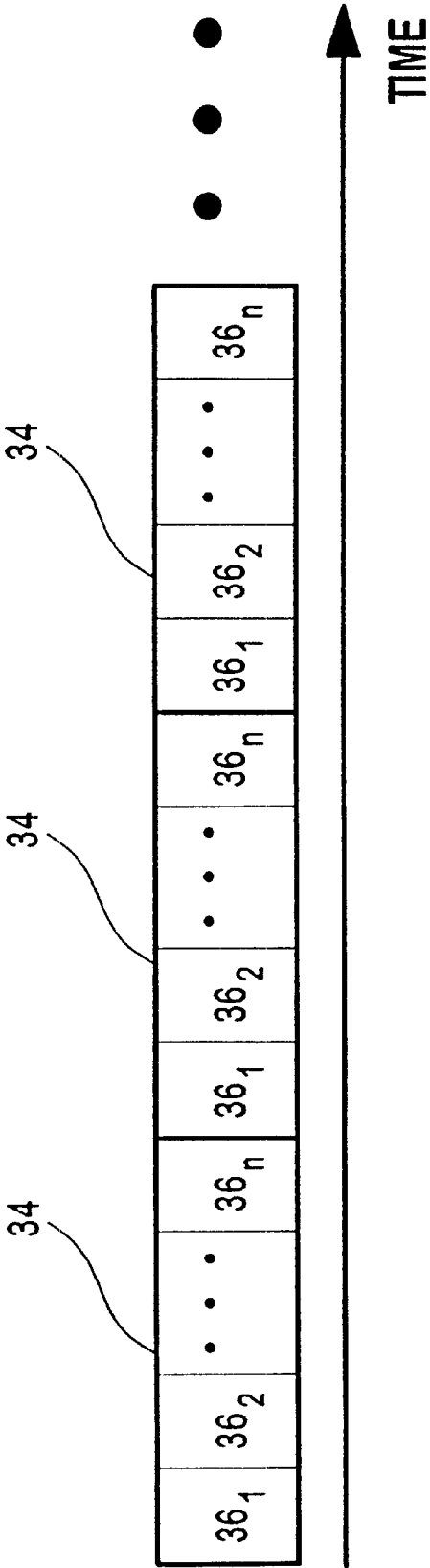
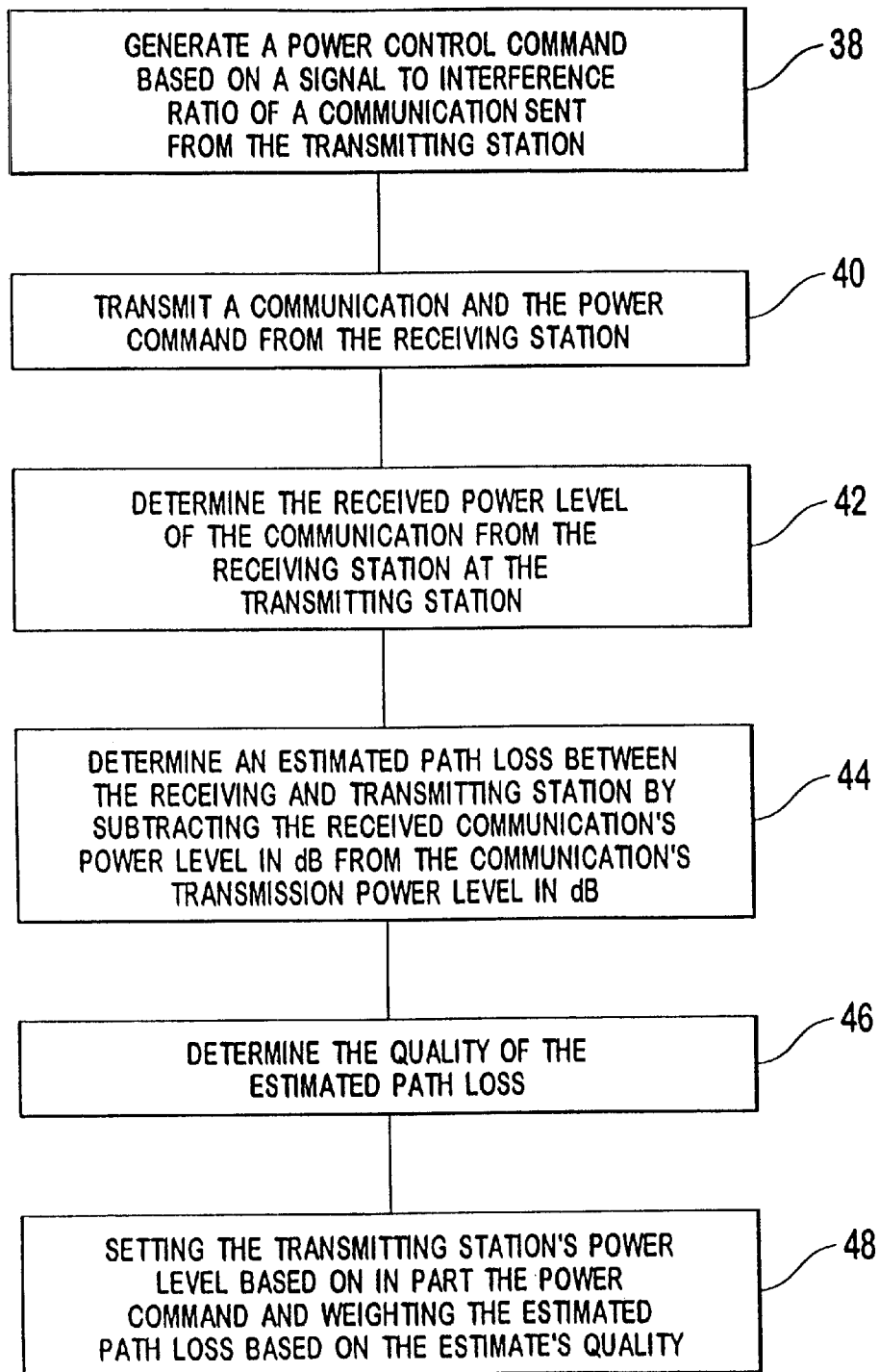


FIG. 3



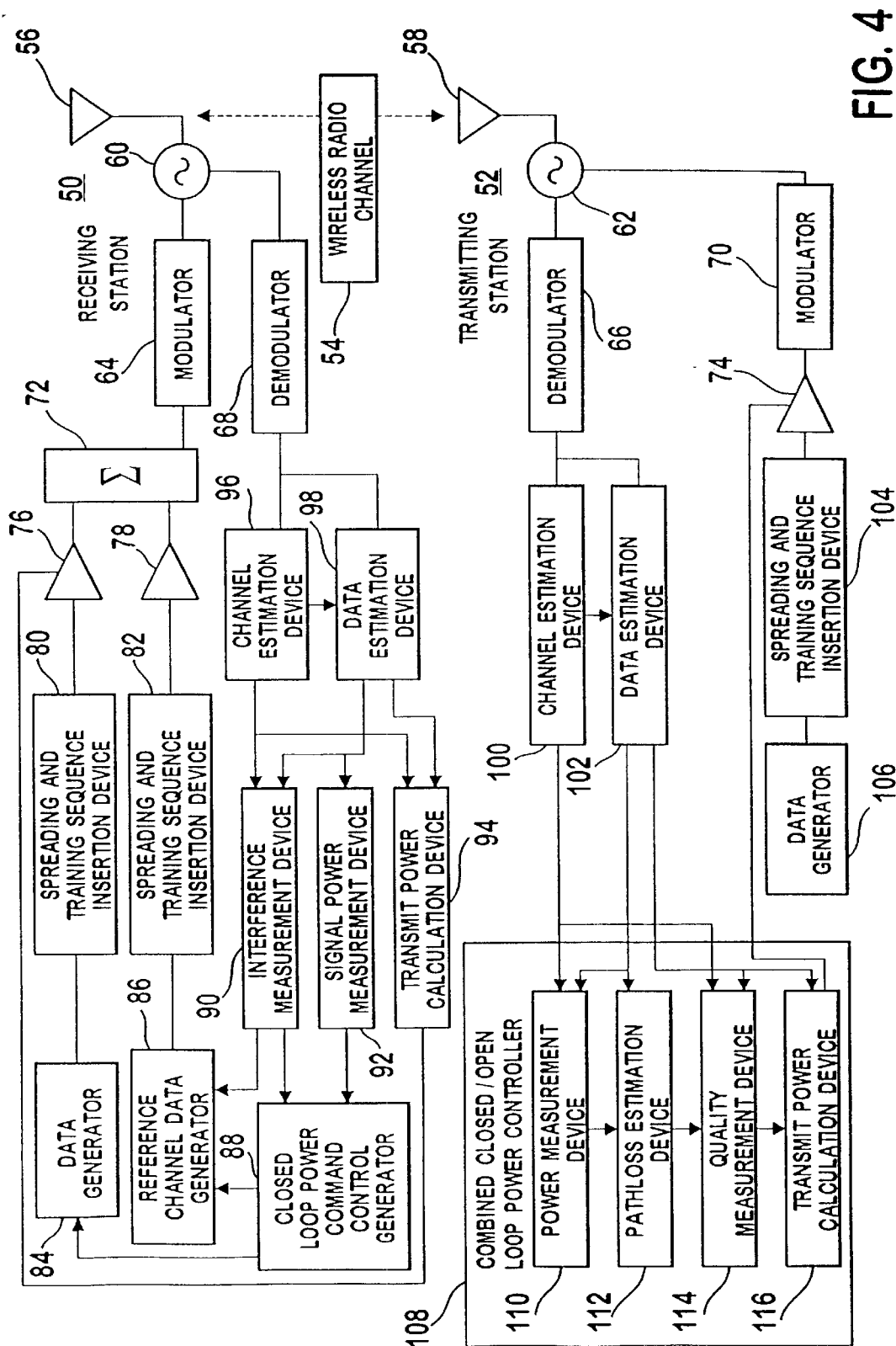


FIG. 4

FIG. 5

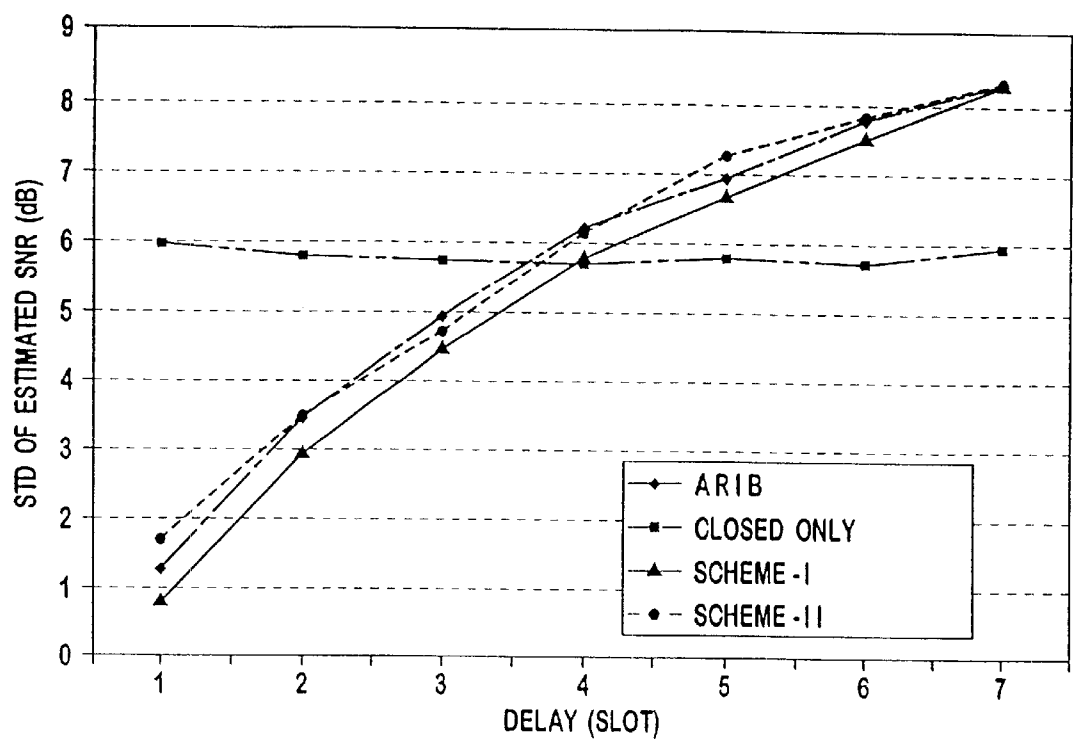


FIG. 6

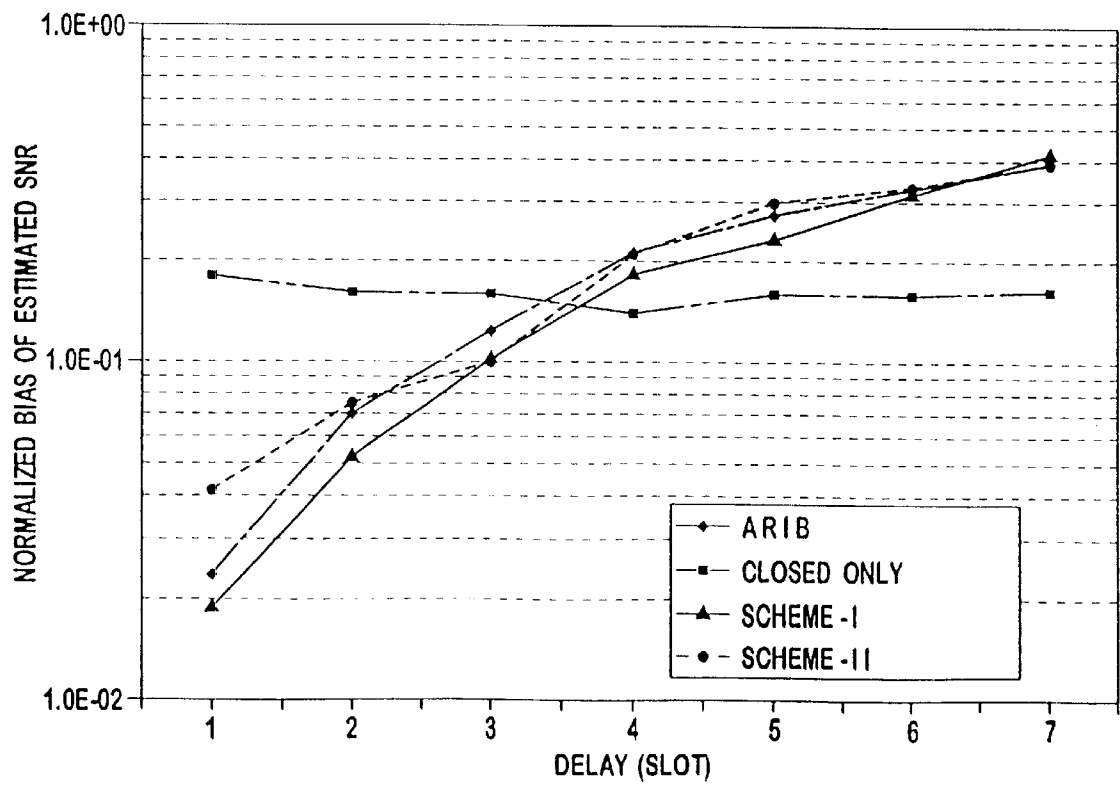


FIG. 7

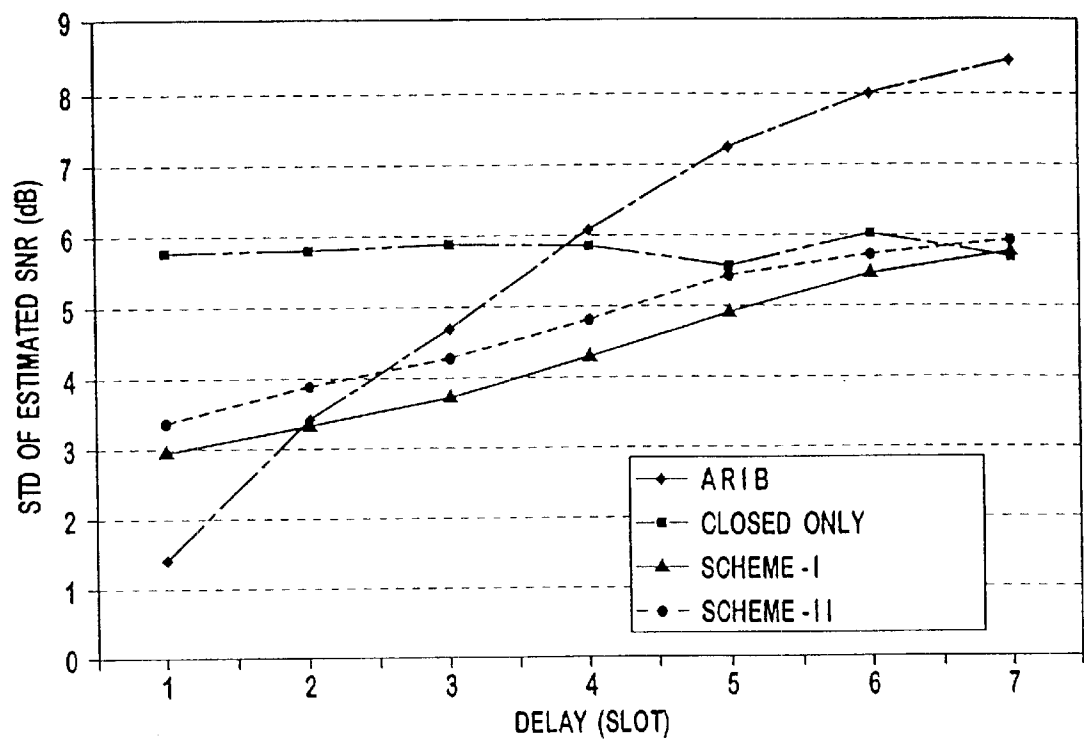


FIG. 8

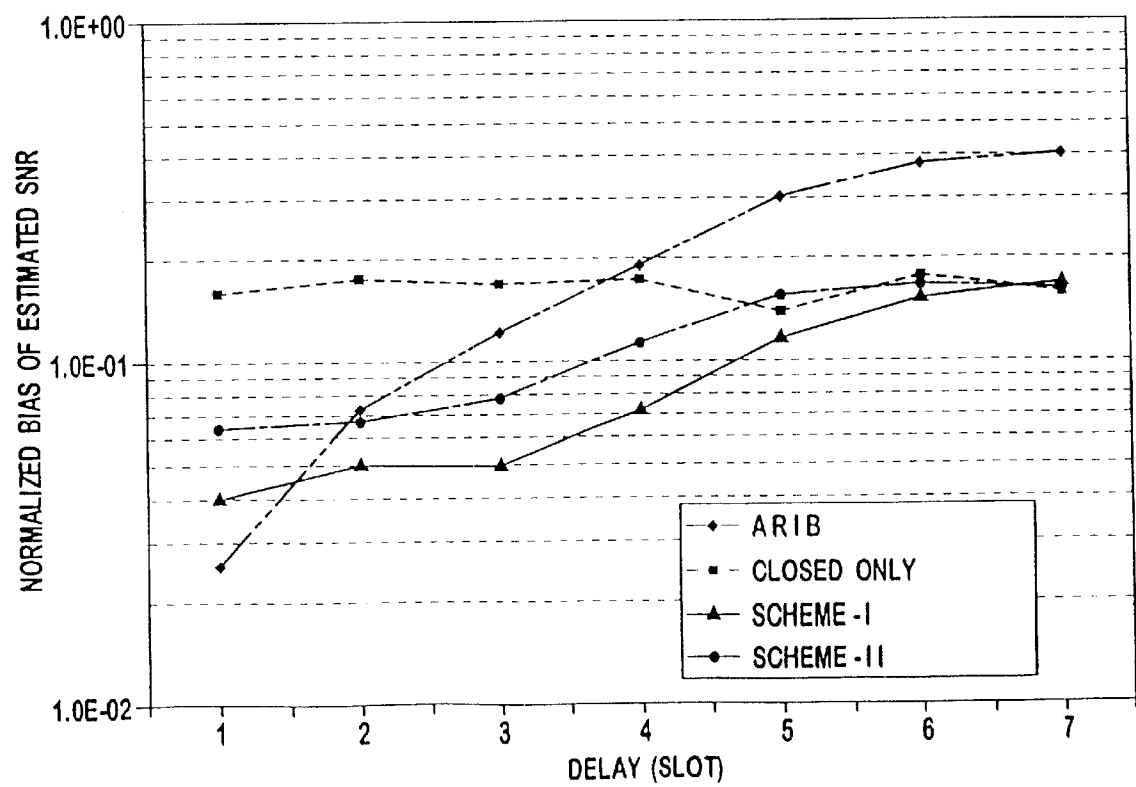


FIG. 9

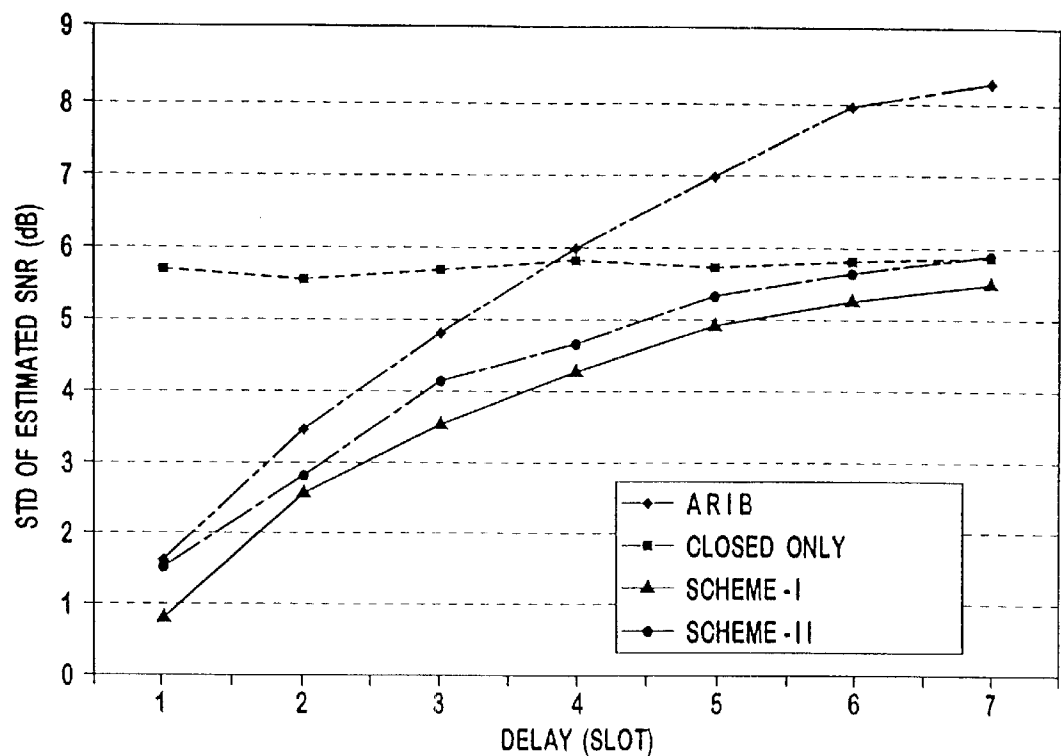
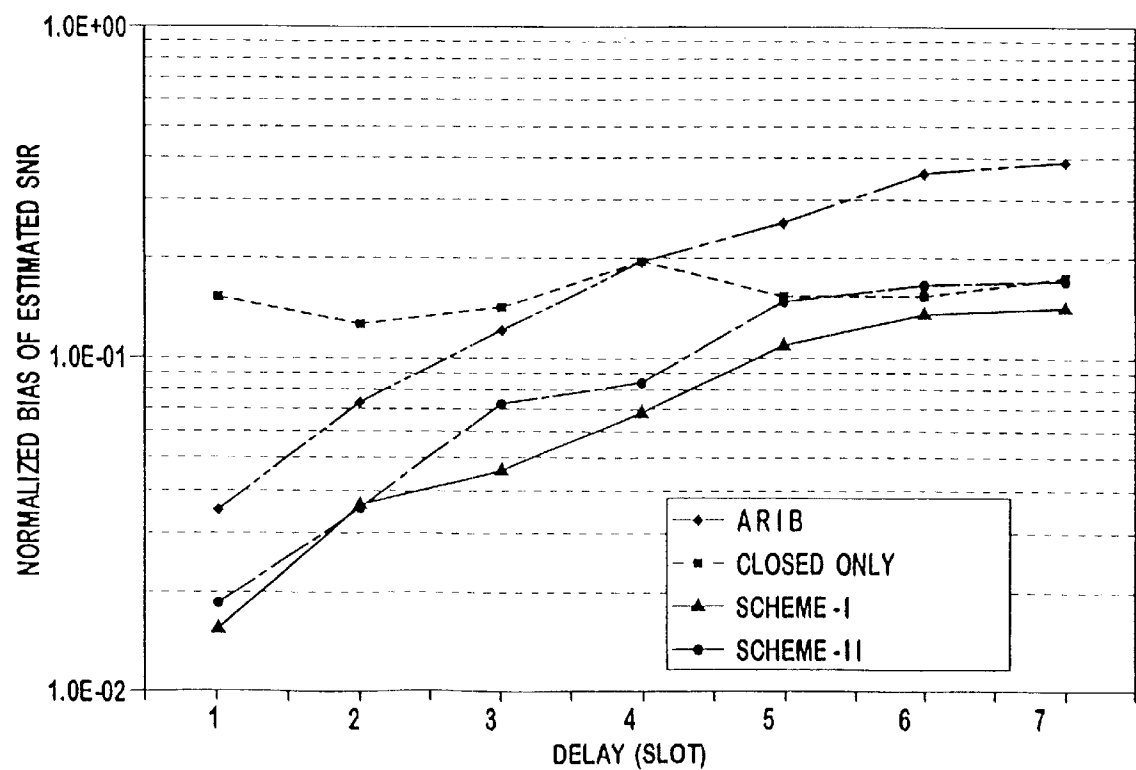


FIG. 10



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COMBINED CLOSED LOOP/OPEN LOOP POWER CONTROL IN A TIME DIVISION DUPLEX COMMUNICATION SYSTEM

BACKGROUND

This invention generally relates to spread spectrum time division duplex (TDD) communication systems. More particularly, the present invention relates to a system and method for controlling transmission power within TDD communication systems.

FIG. 1 depicts a wireless spread spectrum time division duplex (TDD) communication system. The system has a plurality of base stations 30_1 – 30_7 . Each base station 30_1 communicates with user equipments (UEs) 32_1 – 32_3 in its operating area. Communications transmitted from a base station 30_1 to a UE 32_1 are referred to as downlink communications and communications transmitted from a UE 32_1 to a base station 30_1 are referred to as uplink communications.

In addition to communicating over different frequency spectrums, spread spectrum TDD systems carry multiple communications over the same spectrum. The multiple signals are distinguished by their respective chip code sequences (codes). Also, to more efficiently use the spread spectrum, TDD systems as illustrated in FIG. 2 use repeating frames 34 divided into a number of time slots 36_1 – 36_n , such as fifteen time slots. In such systems, a communication is sent in selected time slots 36_1 – 36_n using selected codes. Accordingly, one frame 34 is capable of carrying multiple communications distinguished by both time slot 36_1 – 36_n and code. The combination of a single code in a single time slot is referred to as a resource unit. Based on the bandwidth required to support a communication, one or multiple resource units are assigned to that communication.

Most TDD systems adaptively control transmission power levels. In a TDD system, many communications may share the same time slot and spectrum. When a UE 32_1 or base station 30_1 is receiving a specific communication, all the other communications using the same time slot and spectrum cause interference to the specific communication. Increasing the transmission power level of one communication degrades the signal quality of all other communications within that time slot and spectrum. However, reducing the transmission power level too far results in undesirable signal to noise ratios (SNRs) and bit error rates (BERs) at the receivers. To maintain both the signal quality of communications and low transmission power levels, transmission power control is used.

One approach to control transmission power levels is open loop power control. In open loop power control, typically a base station 30_1 transmits to a UE 32_1 a reference downlink communication and the transmission power level of that communication. The UE 32_1 receives the reference communication and measures its received power level. By subtracting the received power level from the transmission power level, a pathloss for the reference communication is determined. To determine a transmission power level for the uplink, the downlink pathloss is added to a desired received power level at the base station 30_1 . The UE's transmission power level is set to the determined uplink transmission power level.

Another approach to control transmission power level is closed loop power control. In closed loop power control, typically the base station 30_1 determines the signal to interference ratio (SIR) of a communication received from

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the UE 32_1 . The determined SIR is compared to a target SIR (SIR_{TARGET}). Based on the comparison, the base station 30_1 transmits a power command, b_{TPC} . After receiving the power command, the UE 32_1 increases or decreases its transmission power level based on the received power command.

Both closed loop and open loop power control have disadvantages. Under certain conditions, the performance of closed loop systems degrades. For instance, if communications sent between a UE and a base station are in a highly dynamic environment, such as due to the UE moving, such systems may not be able to adapt fast enough to compensate for the changes. The update rate of closed loop power control in TDD is 100 cycles per second which is not sufficient for fast fading channels. Open loop power control is sensitive to uncertainties in the uplink and downlink gain chains and interference levels.

One approach to combining closed loop and open loop power control was proposed by the Association of Radio Industries and Business (ARIB) and uses Equations 1, 2, and 3.

$$T_{UE} = P_{BS}(n) + L \quad \text{Equation 1}$$

$$P_{BS}(n) = P_{BS}(n-1) + b_{TPC} \Delta_{TPC} \quad \text{Equation 2}$$

$$b_{TPC} = \begin{cases} 1: & \text{if } SIR_{BS} < SIR_{TARGET} \\ -1: & \text{if } SIR_{BS} > SIR_{TARGET} \end{cases} \quad \text{Equation 3}$$

T_{UE} is the determined transmission power level of the UE 32_1 . L is the estimated downlink pathloss. $P_{BS}(n)$ is the desired received power level of the base station 30_1 as adjusted by Equation 2. For each received power command, b_{TPC} , the desired received power level is increased or decreased by Δ_{TPC} . Δ_{TPC} is typically one decibel (dB). The power command, b_{TPC} , is one, when the SIR of the UE's uplink communication as measured at the base station 30_1 , SIR_{BS} , is less than a target SIR, SIR_{TARGET} . Conversely, the power command is minus one, when SIR_{BS} is larger than SIR_{TARGET} .

Under certain conditions, the performance of these systems degrades. For instance, if communications sent between a UE 32 and a base station 30 are in a highly dynamic environment, such as due to the UE 32 moving, the path loss estimate for open loop severely degrades the overall system's performance. Accordingly, there is a need for alternate approaches to maintain signal quality and low transmission power levels for all environments and scenarios.

SUMMARY

Combined closed loop/open loop power control controls transmission power levels in a spread spectrum time division duplex communication station. The first station transmits power commands based on in part a reception quality of the received communications. The first station transmits a first communication having transmission power commands based on in part a reception quality of the received communications. The first station transmits a first communication having a transmission power level in a first time slot. The second station received the second communication and the power commands. A power level of the first communication as received is measured. A path loss estimate is determined based on in part the measured received first communication power level and the first communication transmission power level. The first station transmits a first

communication to the first station in a second time slot. The second communication transmission power level is set based on in part the path loss estimate weighted by a factor and power commands. The factor is a function of a time separation of the first and second time slots.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 illustrates a prior art TDD system.

FIG. 2 illustrates time slots in repeating frames of a TDD system.

FIG. 3 is a flow chart of combined closed loop/open loop power control.

FIG. 4 is a diagram of components of two communication stations using combined closed loop/open loop power control.

FIGS. 5–10 depict graphs of the performance of a closed loop, ARIB's proposal and two (2) schemes of combined closed loop/open loop power control.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The preferred embodiments will be described with reference to the drawing figures where like numerals represent like elements throughout. Combined closed loop/open loop power control will be explained using the flow chart of FIG. 3 and the components of two simplified communication stations 50, 52 as shown in FIG. 4. For the following discussion, the communication station having its transmitter's power controlled is referred to as the transmitting station 52 and the communication station receiving power controlled communications is referred to as the receiving station 50. Since combined closed loop/open loop power control may be used for uplink, downlink or both types of communications, the transmitter having its power controlled may be located at a base station 30₁, UE 32₁ or both. Accordingly, if both uplink and downlink power control are used, the receiving and transmitting station's components are located at both the base station 30₁ and UE 32₁.

The receiving station 50 receives various radio frequency signals including communications from the transmitting station 52 using an antenna 56, or alternately, an antenna array. The received signals are passed through an isolator 60 to a demodulator 68 to produce a baseband signal. The baseband signal is processed, such as by a channel estimation device 96 and a data estimation device 98, in the time slots and with the appropriate codes assigned to the transmitting station's communication. The channel estimation device 96 commonly uses the training sequence component in the baseband signal to provide channel information, such as channel impulse responses. The channel information is used by the data estimation device 98, the interference measurement device 90, the signal power measurement device 92 and the transmit power calculation device 94. The data estimation device 98 recovers data from the channel by estimating soft symbols using the channel information. Using the soft symbols and channel information, the transmit power calculation device 94 controls the receiving station's transmission power level by controlling the gain of an amplifier 76.

The signal power measurement device 92 uses either the soft symbols or the channel information, or both, to determine the received signal power of the communication in decibels (dB). The interference measurement device 90 determines the interference level in dB, I_{RS} , within the channel, based on either the channel information, or the soft symbols generated by the data estimation device 98, or both.

The closed loop power command generator 88 uses the measured communication's received power level and the interference level, I_{RS} , to determine the Signal to Interference Ratio (SIR) of the received communication. Based on a comparison of the determined SIR with a target SIR (SIR_{TARGET}), a closed loop power command is generated, b_{TPC} , such as a power command bit, b_{TPC} , step 38. Alternately, the power command may be based on any quality measurement of the received signal.

For use in estimating the path loss between the receiving and transmitting stations 50, 52 and sending data, the receiving station 50 sends a communication to the transmitting station 58, step 40. The communication may be sent on any one of various channels. Typically, in a TDD system, the channels used for estimating path loss are referred to as reference channels, although other channels may be used. If the receiving station 50 is a base station 30₁, the communication is preferably sent over a downlink common channel or a common control physical channel (CCPCH). Data to be communicated to the transmitting station 52 over the reference channel is referred to as reference channel data. The reference data may include, as shown, the interference level, I_{RS} multiplexed with other reference data, such as the transmission power level of the reference channel, T_{RS} . The interference level, I_{RS} , and reference channel power level, T_{RS} , may be sent in other channels, such as a signaling channel. The closed loop power control command, b_{TPC} , is typically sent in a dedicated channel. The dedicated channel is dedicated to the communication between the receiving station 50 and transmitting station 52, step 40.

The reference channel data is generated by a reference channel data generator 86. The reference data is assigned one or multiple resource units based on the communication's bandwidth requirements. A spreading and training sequence insertion device 82 spreads the reference channel data and makes the spread reference data time-multiplexed with a training sequence in the appropriate time slots and codes of the assigned resource units. The resulting sequence is referred to as a communication burst. The communication burst is subsequently amplified by an amplifier 78. The amplified communication burst may be summed by a sum device 72 with any other communication burst created through devices, such as a data generator 84, spreading and training sequence insertion device 80 and amplifier 76.

The summed communication bursts are modulated by a modulator 64. The modulated signal is passed through an isolator 60 and radiated by an antenna 56 as shown or, alternately, through an antenna array. The radiated signal is passed through a wireless radio channel 54 to an antenna 58 of the transmitting station 52. The type of modulation used for the transmitted communication can be any of the those known to those skilled in the art, such as direct phase shift keying (DPSK) or quadrature phase shift keying (QPSK).

The antenna 58 or, alternately, antenna array of the transmitting station 52 receives various radio frequency signals. The received signals are passed through an isolator 62 to a demodulator 66 to produce a baseband signal. The baseband signal is processed, such as by a channel estimation device 100 and a data estimation device 102, in the time slots and with the appropriate codes assigned to the communication burst of the receiving station 50. The channel estimation device 100 commonly uses the training sequence component in the baseband signal to provide channel information, such as channel impulse responses. The channel information is used by the data estimation device 102, a power measurement device 110 and a quality measurement device 114.

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The power level of the processed communication corresponding to the reference channel, R_{TS} , is measured by the power measurement device 110 and sent to a pathloss estimation device 112, step 42. Both the channel estimation device 100 and the data estimation device 102 are capable of separating the reference channel from all other channels. If an automatic gain control device or amplifier is used for processing the received signals, the measured power level is adjusted to correct for the gain of these devices at either the power measurement device 110 or the pathloss estimation device 112. The power measurement device 110 is a component of the combined closed loop/open loop controller 108. As illustrated in FIG. 4, the combined closed loop/open loop power controller 108 comprises the power measurement device 110, pathloss estimation device 112, quality measurement device 114, and transmit power calculation device 116.

To determine the path loss, L , the transmitting station 52 also requires the communication's transmitted power level, T_{RS} . The transmitted power level, T_{RS} , may be sent along with the communication's data or in a signaling channel. If the power level, T_{RS} , is sent along with the communication's data, the data estimation device 102 interprets the power level and sends the interpreted power level to the pathloss estimation device 112. If the receiving station 50 is a base station 30₁, preferably the transmitted power level, T_{RS} , is sent via the broadcast channel (BCH) from the base station 30₁. By subtracting the received communication's power level, R_{TS} in dB, from the sent communication's transmitted power level, T_{RS} in dB, the pathloss estimation device 112 estimates the path loss, L , between the two stations 50, 52, step 44. In certain situations, instead of transmitting the transmitted power level, T_{RS} , the receiving station 50 may transmit a reference for the transmitted power level. In that case, the pathloss estimation device 112 provides reference levels for the path loss, L .

If a time delay exists between the estimated path loss and the transmitted communication, the path loss experienced by the transmitted communication may differ from the calculated loss. In TDD systems where communications are sent in differing time slots 36₁–36_{*n*}, the time slot delay between received and transmitted communications may degrade the performance of an open loop power control system. Combined closed loop/open loop power control utilizes both closed loop and open loop power control aspects. If the quality of the path loss measurement is high, the system primarily acts as an open loop system. If the quality of the path loss measurement is low, the system primarily acts as a closed loop system. To combine the two power control aspects, the system weights the open loop aspect based on the quality of the path loss measurement.

A quality measurement device 114 in a weighted open loop power controller 108 determines the quality of the estimated path loss, step 46. The quality may be determined using the channel information generated by the channel estimation device 100, the soft symbols generated by the data estimation device 102 or other quality measurement techniques. The estimated path loss quality is used to weight the path loss estimate by the transmit power calculation device 116. If the power command, b_{TPC} , was sent in the communication's data, the data estimation device 102 interprets the closed loop power command, b_{TPC} . Using the closed loop power command, b_{TPC} , and the weighted path loss, the transmit power calculation device 116 sets the transmit power level of the receiving station 50, step 48.

The following is one of the preferred combined closed loop/open loop power control algorithms. The transmitting

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station's power level in decibels, P_{TS} , is determined using Equations 4 and 6.

$$P_{TS} = P_0 + G(n) + \alpha L \quad \text{Equation 4}$$

P_0 is the power level that the receiving station 50 desires to receive the transmitting station's communication in dB. P_0 is determined by the desired SIR at the receiving station 50, SIR_{TARGET} , and the interference level, I_{RS} , at the receiving station 50 using Equation 5.

$$P_0 = SIR_{TARGET} + I_{RS} \quad \text{Equation 5}$$

I_{RS} is either signaled or broadcasted from the receiving station 50 to the transmitting station 52. For downlink power control, SIR_{TARGET} is known at the transmitting station 52. For uplink power control, SIR_{TARGET} is signaled from the receiving station 50 to the transmitting station 52. $G(n)$ is the closed loop power control factor. Equation 6 is one equation for determining $G(n)$.

$$G(n) = G(n-1) + b_{TPC} \Delta TPC \quad \text{Equation 6}$$

$G(n-1)$ is the previous closed loop power control factor. The power command, b_{TPC} , for use in Equation 6 is either +1 or -1. One technique for determining the power command, b_{TPC} , is Equation 3. The power command, b_{TPC} , is typically updated at a rate of 100 ms in a TDD system, although other update rates may be used. ΔTPC is the change in power level. The change in power level is typically 1 dB although other values may be used. As a result, the closed loop factor increases by 1 dB if b_{TPC} is +1 and decreases by 1 dB if b_{TPC} is -1.

The weighting value, α , is determined by the quality measurement device 114. α is a measure of the quality of the estimated path loss and is, preferably, based on the number of time slots, D , between the time slot of the last path loss estimate and the first time slot of the communication transmitted by the transmitting station 52. The value of α is from zero to one. Generally, if the time difference, D , between the time slots is small, the recent path loss estimate will be fairly accurate and α is set at a value close to one. By contrast, if the time difference is large, the path loss estimate may not be accurate and the closed loop aspect is most likely more accurate. Accordingly, α is set at a value closer to zero. Equations 7 and 8 are two equations for determining α , although others may be used.

$$\alpha = 1 - (D-1)/(D_{max}-1) \quad \text{Equation 7}$$

$$\alpha = \max\{1 - (D-1)/(D_{max-allowed}-1), 0\} \quad \text{Equation 8}$$

D_{max} is the maximum possible delay. A typical value for a frame having fifteen time slots is seven. If the delay is D_{max} , α is zero. $D_{max-allowed}$ is the maximum allowed time slot delay for using open loop power control. If the delay exceeds $D_{max-allowed}$, open loop power control is effectively turned off by setting $\alpha=0$. Using the calculated transmit power level, P_{TS} , determined by a transmit power calculation device 116, the combined closed loop/open loop power controller 108 sets the transmit power of the transmitted communication.

Data to be transmitted in a communication from the transmitting station 52 is produced by a data generator 106. The communication data is spread and time-multiplexed with a training sequence by the spreading and training sequence insertion device 104 in the appropriate time slots and codes of the assigned resource units producing a communication burst. The spread signal is amplified by the amplifier 74 and modulated by the modulator 70 to radio frequency.

The combined closed loop/open loop power controller **108** controls the gain of the amplifier **74** to achieve the determined transmit power level, P_{TS} , for the communication. The power controlled communication is passed through the isolator **62** and radiated by the antenna **58**.

Equations 9 and 10 are another preferred combined closed loop/open loop power control algorithm.

$$P_{TS}=P_0+K(n) \quad \text{Equation 9}$$

$$K(n)=K(n-1)+b_{TPC} \Delta_{TPC}+\alpha L \quad \text{Equation 10}$$

$K(n)$ is the combined closed loop/open loop factor. As shown, this factor includes both the closed loop and open loop power control aspects. Equations 4 and 5 segregate the two aspects.

Although the two above algorithms only weighted the open loop factor, the weighting may be applied to the closed loop factor or both the open and closed loop factors. Under certain conditions, the network operator may desire to use solely open loop or solely closed loop power control. For example, the operator may use solely closed loop power control by setting α to zero.

FIGS. 5–10 depict graphs **118–128** illustrating the performance of a combined closed-loop/open-loop power control system. These graphs **118–128** depict the results of simulations comparing the performance of the ARIB proposed system, a closed loop, a combined open loop/closed loop system using Equations 4 and 6 (scheme I) and a combined system using Equations 9 and 10 (scheme II). The simulations were performed at the symbol rate. A spreading factor of sixteen was used for both the uplink and downlink channels. The uplink and downlink channels are International Telecommunication Union (ITU) Channel model [ITU-R M.1225, vehicular, type B]. Additive noises were simulated as being independent of white Gaussian noises with unity variance. The path loss is estimated at the transmitting station **52** which is a UE **32₁** and in particular a mobile station. The BCH channel was used for the path loss estimate. The path loss was estimated two times per frame at a rate of 200 cycles per second. The receiving station **50**, which was a base station **30₁**, sent the BCH transmission power level over the BCH. RAKE combining was used for both the UE **32₁** and base station **30₁**. Antenna diversity combining was used at the base station **30₁**.

Graphs **118, 122, 126** depict the standard deviation of the received signal to noise ratio (SNR) at the base station **30₁** of the UE's power controlled communication as a function of the time slot delay, D . Graphs **120, 124, 128** depict the normalized bias of the received SNR as a function of the delay, D . The normalization was performed with respect to the desired SNR. Each point in the graphs **118–128** represents the average of 3000 Monte-Carlo runs.

Graphs **118, 120** depict the results for an α set at one. For low time slot delays ($D < 4$), scheme I and II outperform closed loop power control. For larger delays ($D \geq 4$), closed loop outperforms both scheme I and II which demonstrates the importance of weighting the open loop and closed loop aspects.

Graphs **122, 124** depict the results for an α set at 0.5. As shown, for all delays excluding the maximum, schemes I and II outperform closed loop power control. The ARIB proposal only outperforms the others at the lowest delay ($D=1$).

Graphs **126, 128** depict the results for an α set using Equation 7 with D_{max} equal to seven. As shown, schemes I and II outperform both closed loop and the ARIB proposal at all delays, D .

What is claimed is:

1. A method for controlling transmission power levels in a spread spectrum time division duplex communication system having frames with time slots for communication, the method comprising:

receiving at a first communication station communications from a second communication station and transmitting from the first station power commands based on in part a reception quality of the received communications;

transmitting from the first communication station a first communication having a transmission power level in a first time slot;

receiving at the second communication station the first communication and the power commands;

measuring a power level of the first communication as received;

determining a pathloss estimate based on in part the measured received first communication power level and the first communication transmission power level;

setting a transmission power level for a second communication in a second time slot from the second station to the first station based on in part the pathloss estimate weighted by a quality factor and the power commands, wherein the quality factor is a function of a time separation of the first and second time slots; and

determining a quality, α , of the pathloss estimate based on in part a number of time slots, D , between the first and the second time slot; and

wherein the quality factor is α .

2. The method of claim 1 wherein a maximum time slot delay is D_{max} and the determined quality, α , is determined by

$$\alpha=1-(D-1)/(D_{max}-1).$$

3. The method of claim 1 wherein a maximum allowable time slot delay is $D_{max-allowed}$ and the determined quality, α , is determined by

$$\alpha=\max\{1-(D-1)/(D_{max-allowed}-1),0\}.$$

4. The method of claim 1 wherein the setting of the transmission power level is based on in part a desired received power level at the first station, a closed loop factor and an open loop factor; wherein the closed loop factor is based on in part the received power commands and the open loop factor is based on in part the pathloss estimate weighted by the quality factor.

5. The method of claim 1 wherein the setting of the transmission power level is based on in part a desired received power level at the first station and a combined closed loop/open loop factor; wherein the combined closed loop/open loop factor is based on in part the received power commands and the pathloss estimate weighted by the quality factor.

6. The method of claim 4 wherein the closed loop factor is updated for each received power command.

7. The method of claim 5 wherein the combined factor is updated for each received power command.

8. The method of claim 4 wherein the desired received power level is based on in part a target signal to interference ratio and a measured interference level at the first station.

9. The method of claim 5 wherein the desired received power level is based on in part a target signal to interference ratio and a measured interference level at the first station.

10. The method of claim 1 wherein the first station is a base station and the second station is a user equipment.

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11. The method of claim 1 wherein the first station is a user equipment and the second station is a base station.

12. A spread spectrum time division duplex communication system having a first and second communication station, the system using frames with time slots for communication, the system comprising:

the first station comprising:

means for receiving communications from the second communication station and transmitting power commands based on in part a reception quality of the received communications; and

means for transmitting a first communication having a transmission power level in a first time slot; and the second station comprising:

means for receiving the first communication and the power commands;

means for measuring a power level of the first communication as received;

means for determining a pathloss estimate based on in part the measured received first communication power level and the first communication transmission power level; and

means for setting a transmission power level for a second communication in a second time slot from the second station to the first station based on in part the pathloss estimate weighted by a quality factor and the power commands, wherein the quality factor is a function of a time separation of the first and second time slots; and

wherein the second station further comprises means for determining a quality, α , of the pathloss estimate based on in part a number of time slots, D , between the first and second time slot; and the quality factor is α .

13. The system of claim 12 wherein a maximum time slot delay is D_{max} and the determined quality, α , is determined by

$$\alpha = 1 - (D - 1) / (D_{max} - 1).$$

14. The system of claim 12 wherein a maximum allowed time slot delay is $D_{max-allowed}$ and the determined quality, α , is determined by

$$\alpha = \max\{1 - (D - 1) / (D_{max-allowed} - 1), 0\}.$$

15. The system of claim 12 wherein the setting means sets the transmission power level based on in part a desired received power level at the first station, a closed loop factor and an open loop factor, the closed loop factor is based on in part the received power commands and the open loop factor is based on in part the pathloss estimate weighted by the quality factor.

16. The system of claim 12 wherein the setting means sets the transmission power level based on in part a desired received power level at the first station and a combined closed loop/open loop factor, the combined closed loop/open

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loop factor is based on in part the received power commands and the path loss estimate weighted by the quality factor.

17. The system of claim 15 wherein the closed loop factor is updated for each received power command.

18. The system of claim 16 wherein the combined factor is updated for each received power command.

19. The system of claim 15 wherein the desired received power level is based on in part a target signal to interference ratio and a measured interference level at the first station.

20. The system of claim 16 wherein the desired received power level is based on in part a target signal to interference ratio and a measured interference level at the first station.

21. The system of claim 12 wherein the first station is a base station and the second station is a user equipment.

22. The system of claim 12 wherein the first station is a user equipment and the second station is a base station.

23. A communication station having its transmission power level controlled in a spread spectrum time division duplex communication system, the system using frames with time slots for communication and having a second communication station transmitting a first communication in a first time slot and power commands, the communication station comprising:

at least one antenna for receiving the first communication and the power commands and transmitting an amplified second communication in a second time slot;

a channel estimation device having an input configured to receive the received first communication for producing channel information;

a data estimation device having inputs configured to receive the received first communication, the power commands and the channel information for producing soft symbols and recovering the power commands;

a power measurement device having an input configured to receive the channel information for producing a measurement of a received power level;

a pathloss estimation device having an input configured to receive the measured received power level for producing a pathloss estimate for the first communication;

a quality measurement device for producing a quality measurement based at least in part upon a time separation of the first time slot and a second time slot;

a transmit power calculation device having inputs configured to receive the pathloss estimation, the recovered power commands and the quality measurement for producing a power control signal based on in part the pathloss estimate weighted by the quality measurement and the recovered power commands; and

an amplifier having inputs configured to receive the power control signal and a second communication to be transmitted in the second time slot for amplifying the second communication in response to the power control signal to produce the amplified second communication.

* * * * *

UNITED STATES PATENT AND TRADEMARK OFFICE
CERTIFICATE OF CORRECTION

PATENT NO. : 6,600,772 B1
DATED : July 29, 2003
INVENTOR(S) : Zeira et al.

Page 1 of 1

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Title page.

Item [75], Inventors, delete “**Fiath M. Ozluturk**” and insert -- **Fatih M. Ozluturk** --.

Item [73], Assignee, delete “**InterDigital Communications Corporation**” and insert -- **InterDigital Technology Corporation** --.

Item [56], **References Cited**, FOREIGN PATENT DOCUMENTS, insert
-- EP 0500689B1 4/1998 --.

OTHER PUBLICATIONS, delete

“Combined Closed-Loop/Open-Loop Power Control Process for Time Division Duplexing”, Ariela Zeira, Sung-Hyuk Shin and Fiath Ozluturk, Apr. 1999” and insert -- Combined Closed-Loop/Open-Loop Power Control Process for Time Division Duplexing”, Ariela Zeira, Sung-Hyuk Shin and Fatih Ozluturk, Apr. 1999 --.

Item [57], **ABSTRACT**,

Line 10, delete “The second station received the first communication and the power commands”, and insert -- The second station receives the first communication and the power commands --.

Line 15, delete “The second station transmits a first communication to the first station in a first time slot”, and insert -- The second station transmits a second communication to the first station in a second time slot --.

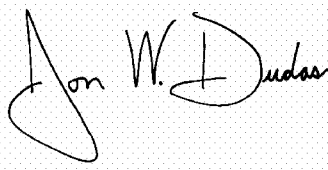
Column 2.

Line 62, delete “received”, and insert -- receives --.

Line 67, after “The”, delete “first” and insert -- second --; and after “a”, delete “first”, and insert -- second --.

Signed and Sealed this

Fourteenth Day of March, 2006

A handwritten signature in black ink on a light gray dotted background. The signature appears to read "Jon W. Dudas" in a cursive, stylized script.

JON W. DUDAS

Director of the United States Patent and Trademark Office