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(54) **EXPANDABLE SPINAL IMPLANT AND TOOL SYSTEM**

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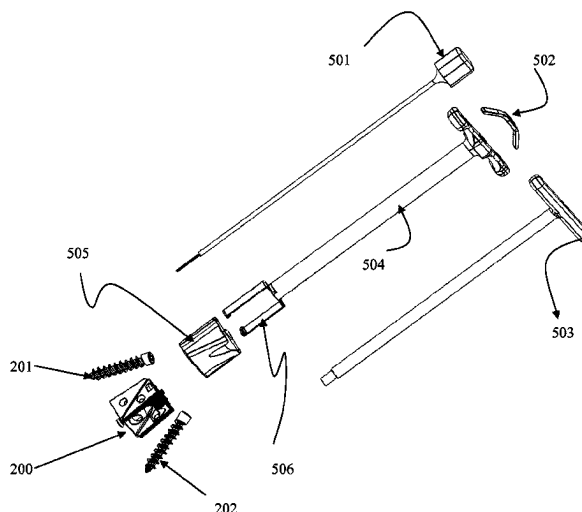
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(57) **ABSTRACT**

A self-drilling bone fusion screw apparatus is disclosed which includes at least first and second sliding boxes. A first screw member having a tapered end and a threaded body is disposed within the first sliding box, and a second screw member having a tapered end and a threaded body disposed within the second sliding box. An adjuster adjusts the height of the sliding boxes. The screw members are screwed into vertebral bodies in order to fuse the vertebral bodies together. A plurality of the self-drilling bone fusion screw apparatuses may be attached together and/or integrated via a plate or cage. Also disclosed is a cervical facet staple that includes a curved staple base and at least two prongs attached to the bottom surface of the curved staple base.

20 Claims, 38 Drawing Sheets



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continuation of application No. 15/894,471, filed on Feb. 12, 2018, now Pat. No. 10,390,969, which is a continuation of application No. 13/210,157, filed on Aug. 15, 2011, now Pat. No. 9,889,022, which is a continuation of application No. 13/108,982, filed on May 16, 2011, now Pat. No. 9,005,293, and a continuation of application No. 13/084,543, filed on Apr. 11, 2011, now Pat. No. 8,353,913, which is a continuation of application No. 11/842,855, filed on Aug. 21, 2007, now Pat. No. 7,942,903, said application No. 13/108,982 is a continuation of application No. 11/842,855, filed on Aug. 21, 2007, now Pat. No. 7,942,903, which is a continuation-in-part of application No. 11/536,815, filed on Sep. 29, 2006, now Pat. No. 7,846,188, which is a continuation-in-part of application No. 11/208,644, filed on Aug. 23, 2005, now Pat. No. 7,704,279.

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See application file for complete search history.

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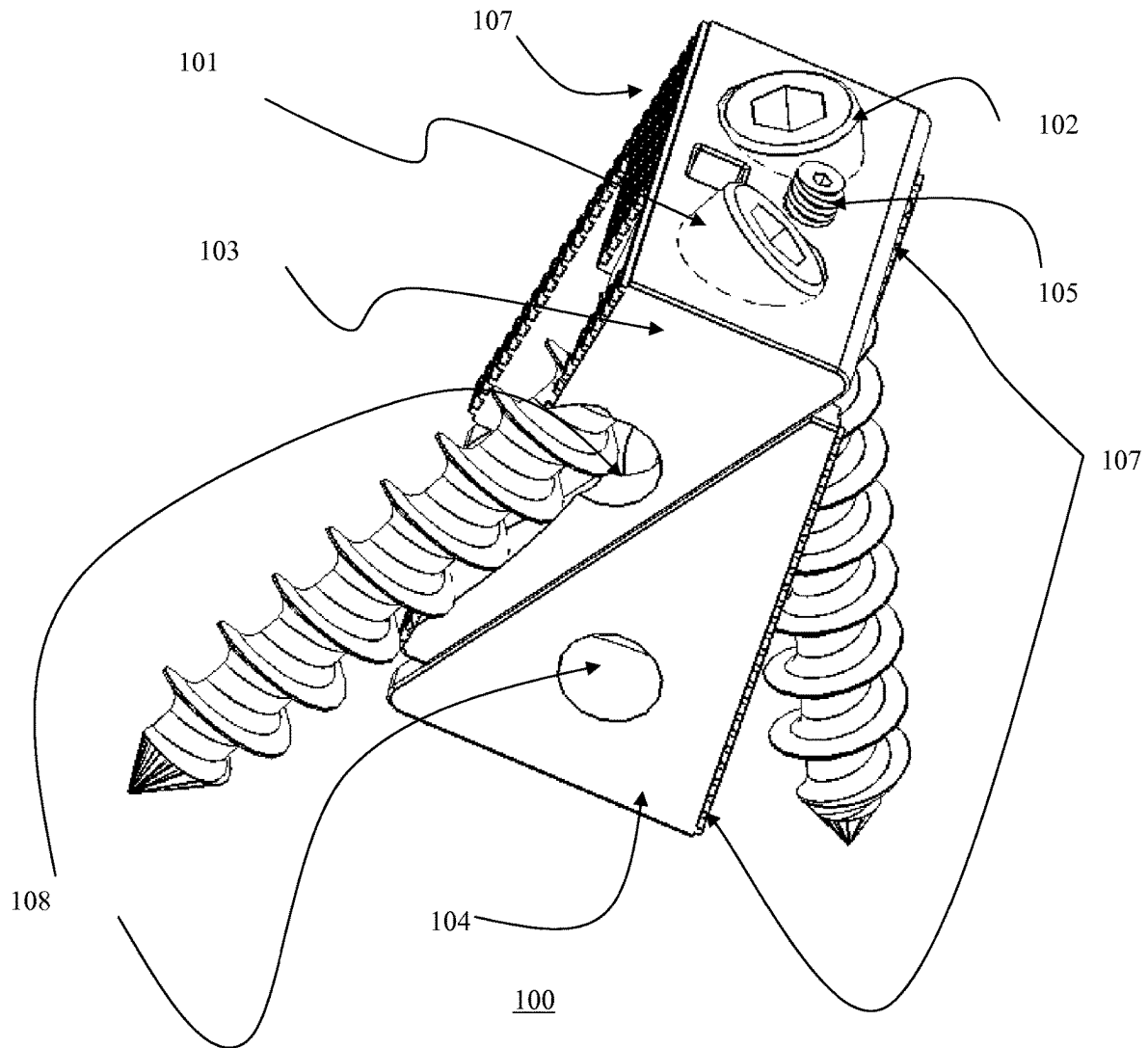


Fig. 1A

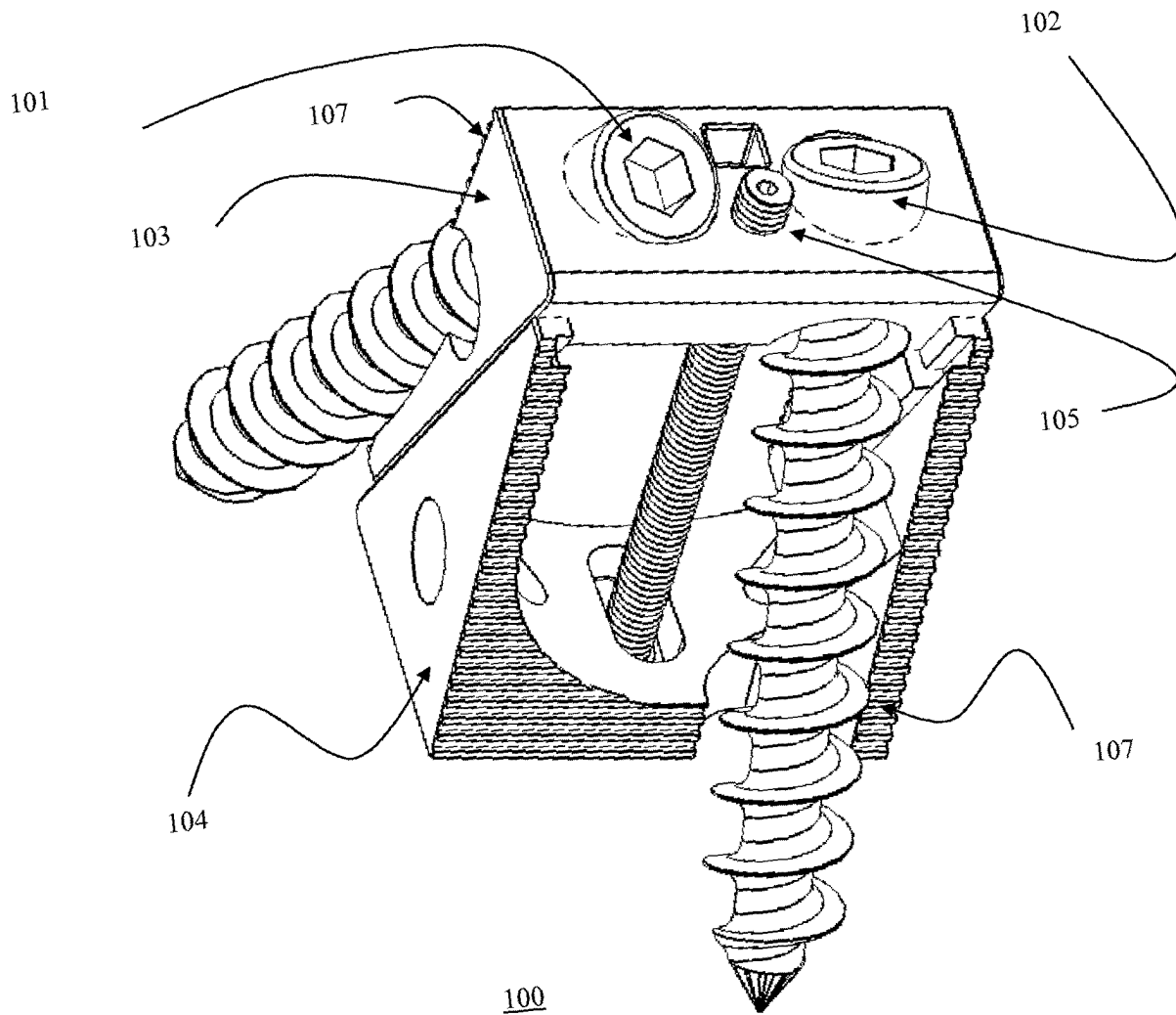


Fig. 1B

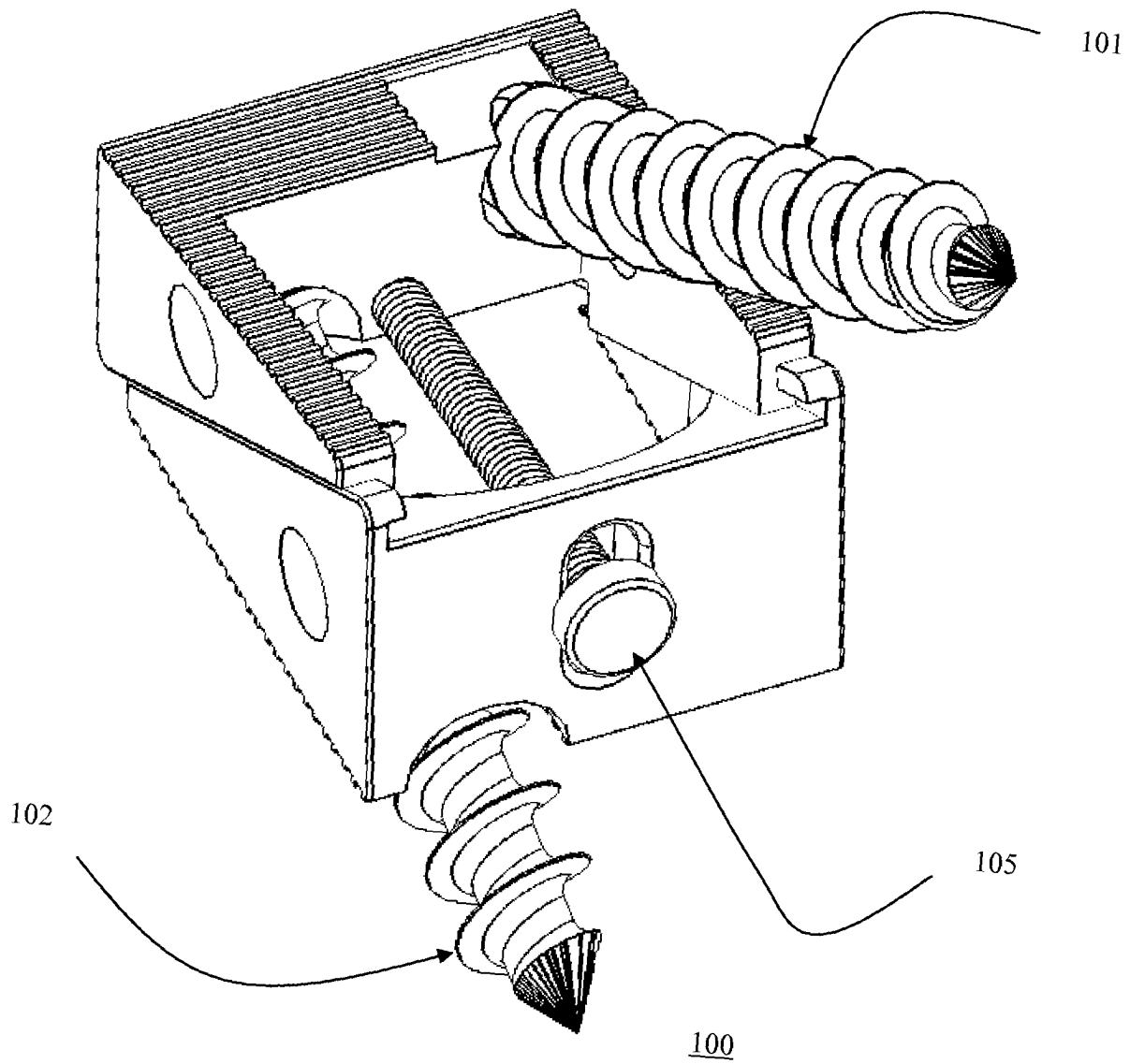


Fig. 1C

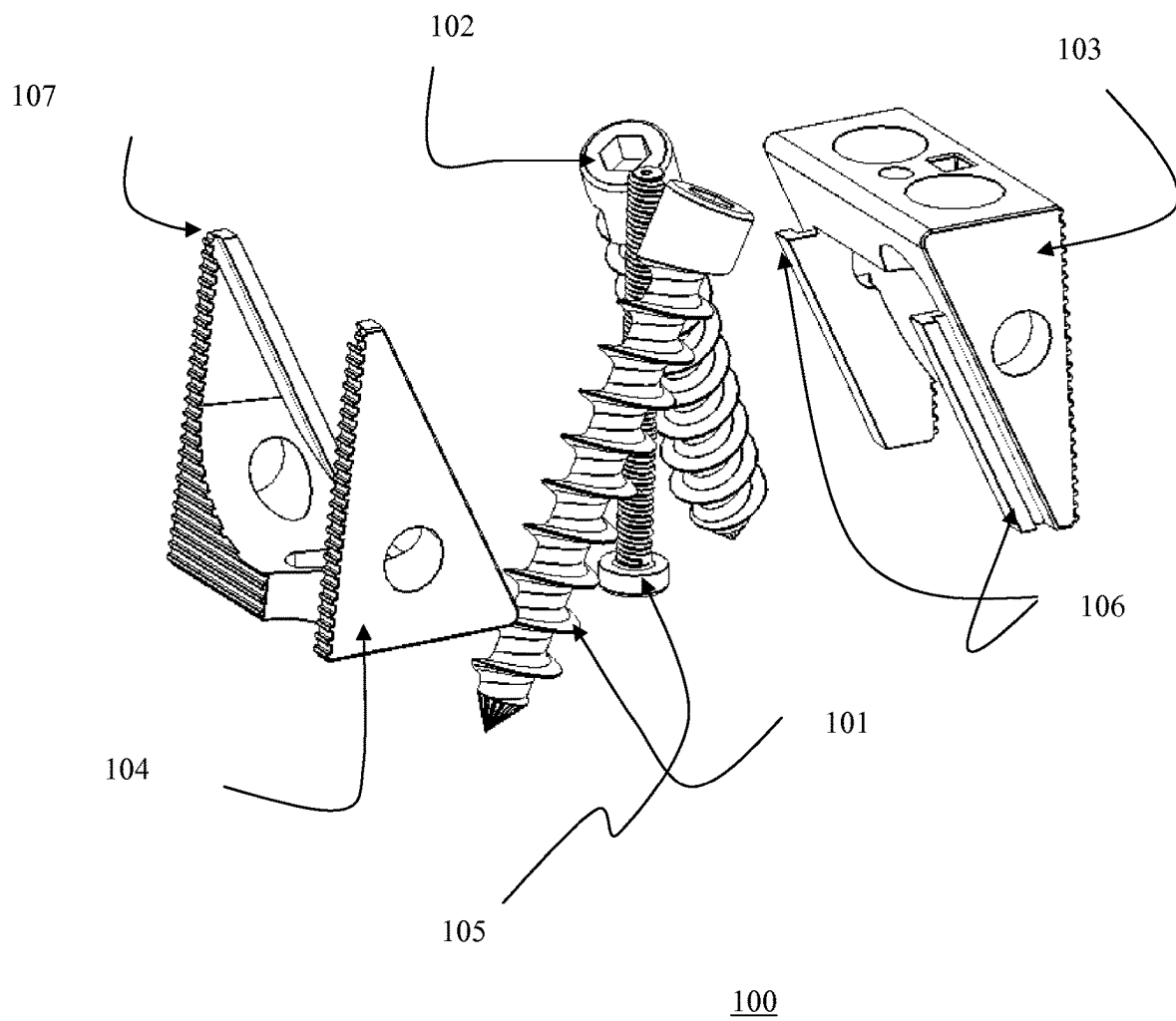


Fig. 1D

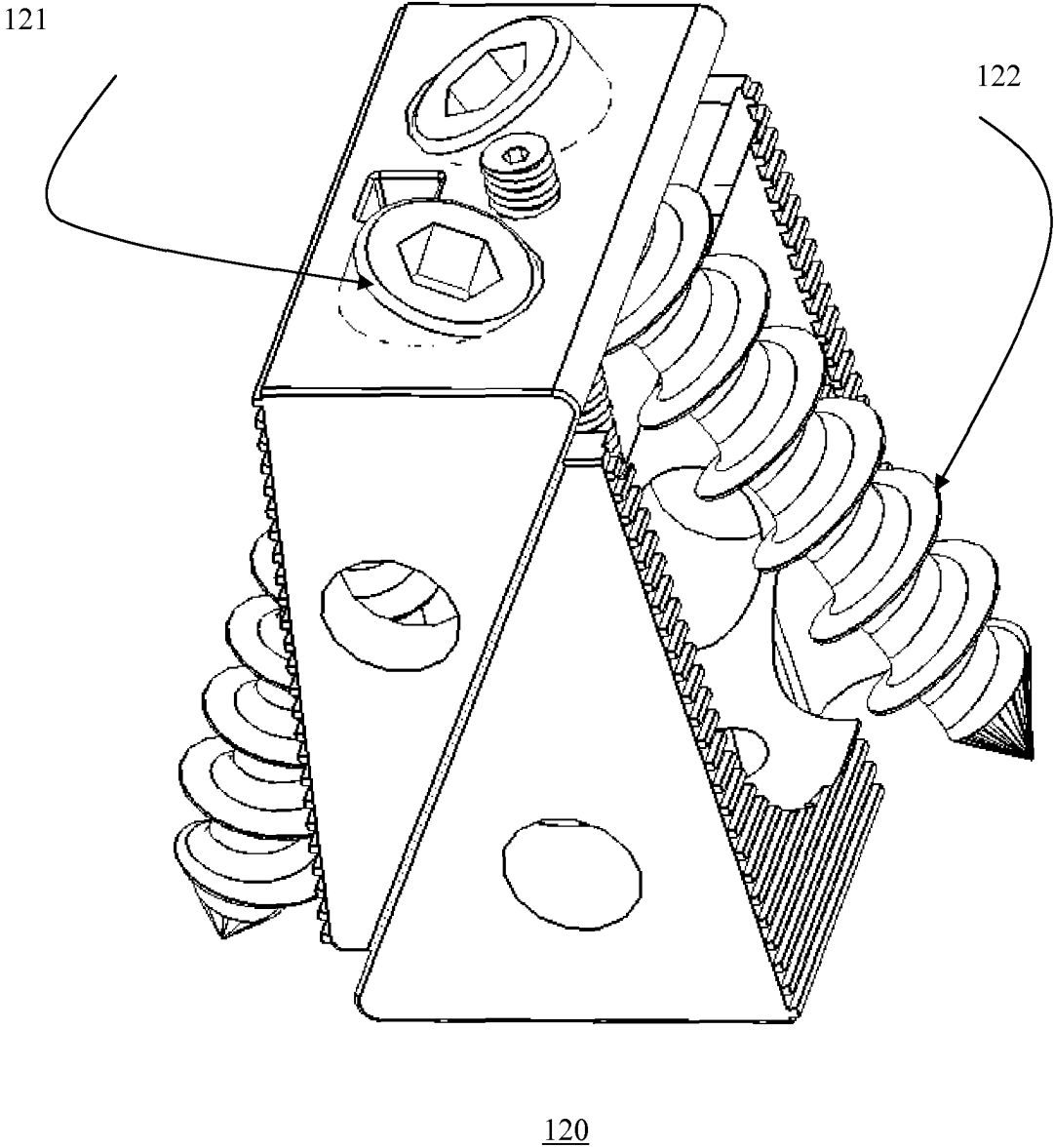


Fig. 1E

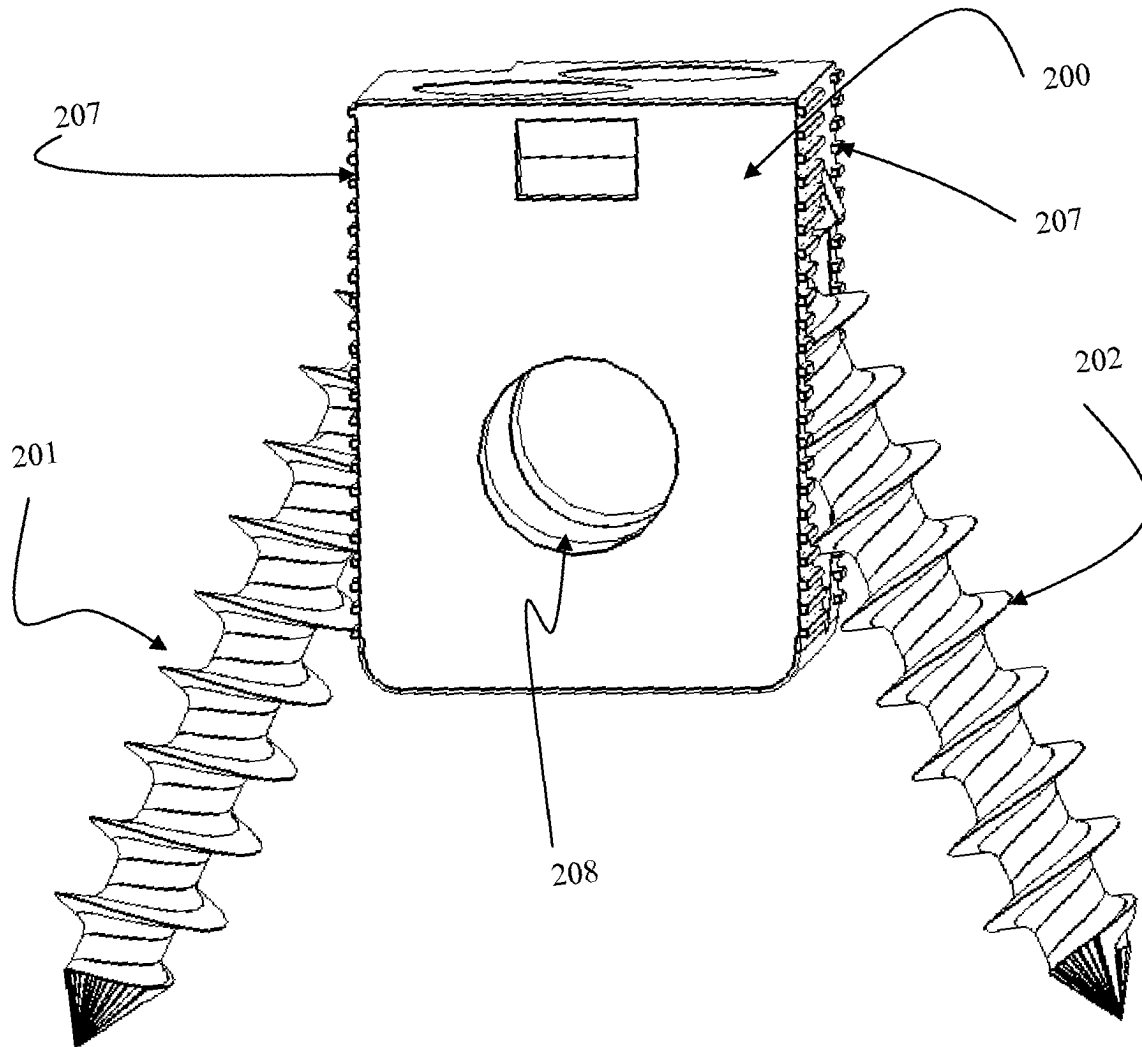


Fig. 2A

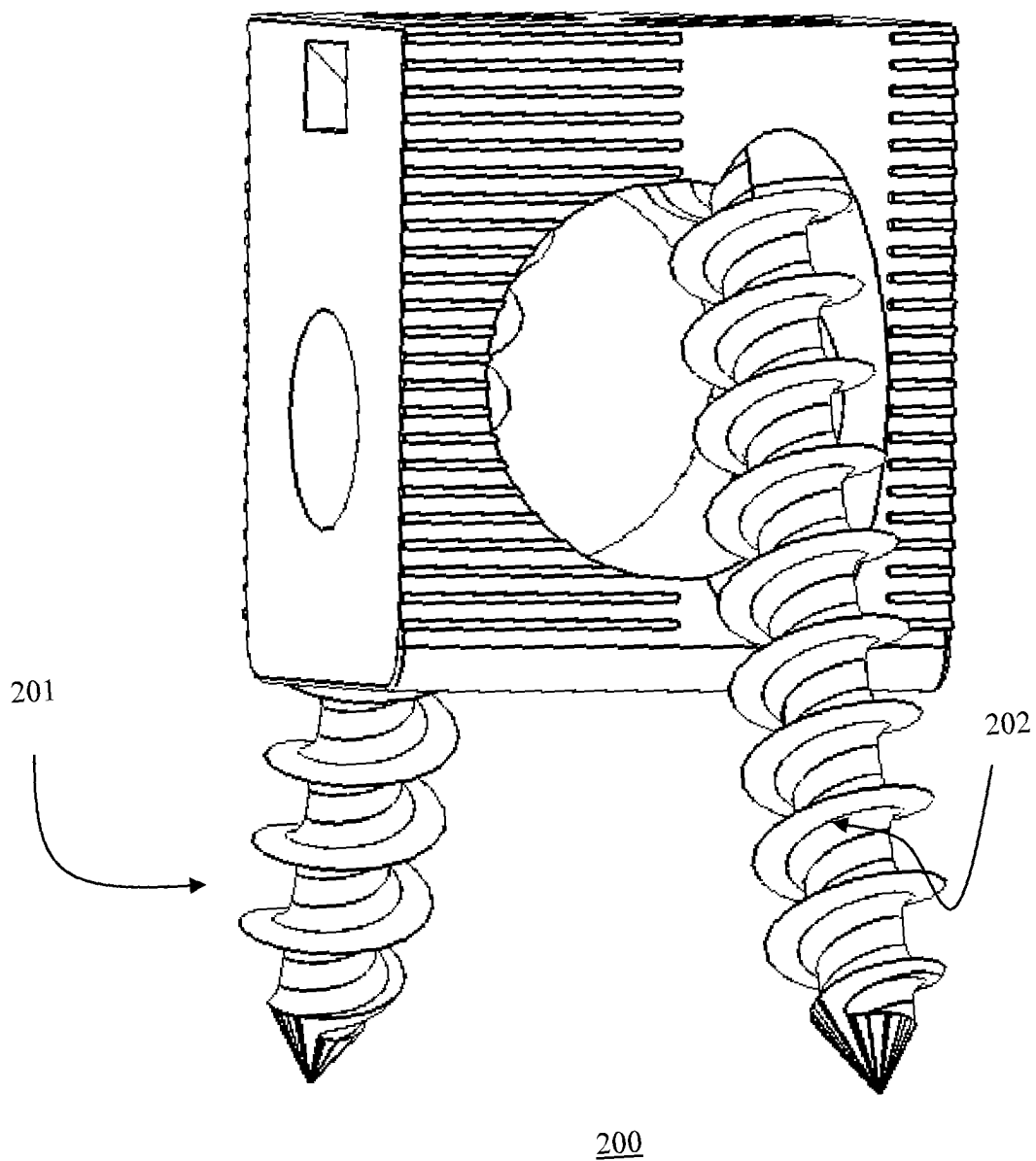


Fig. 2B

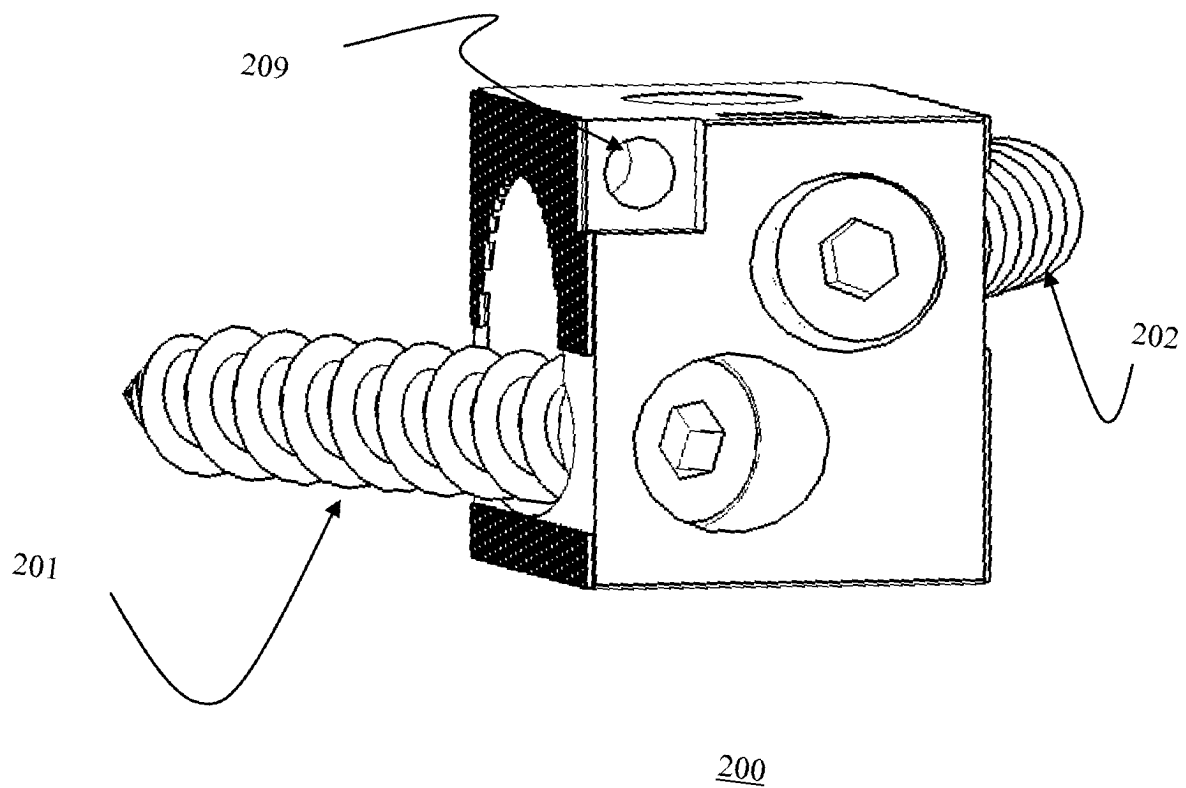


Fig. 2C

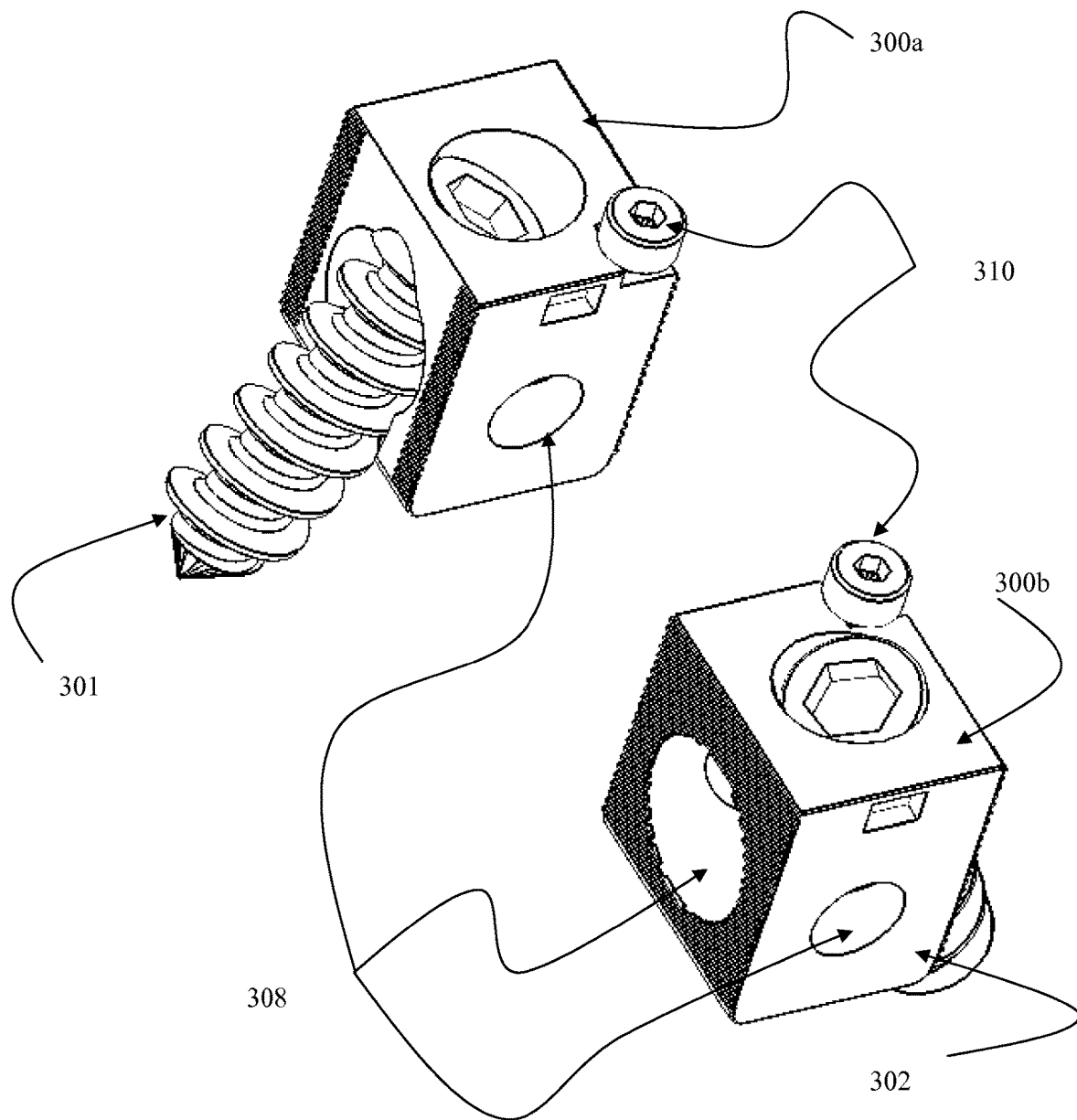


Fig. 3

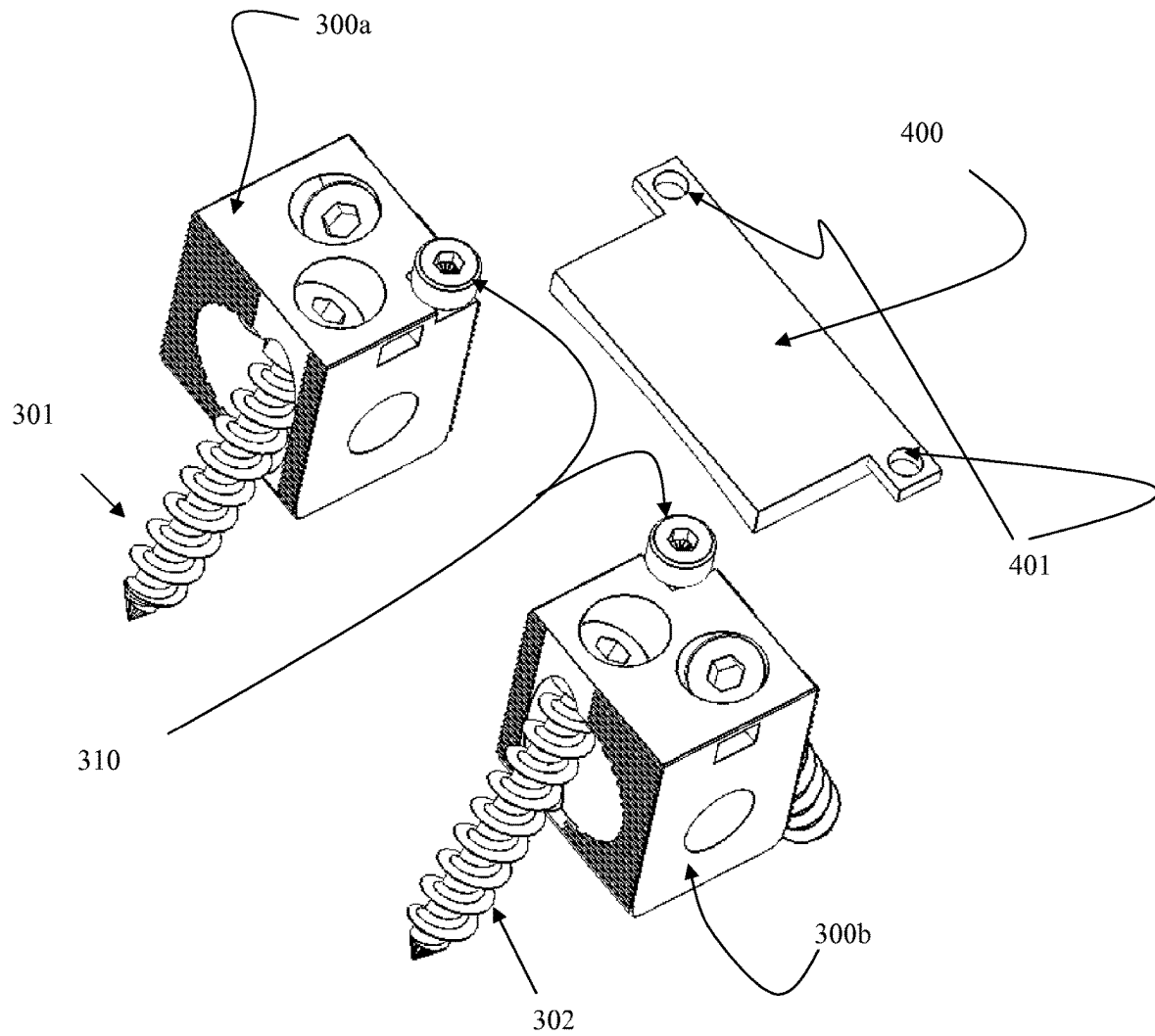


Fig. 4A

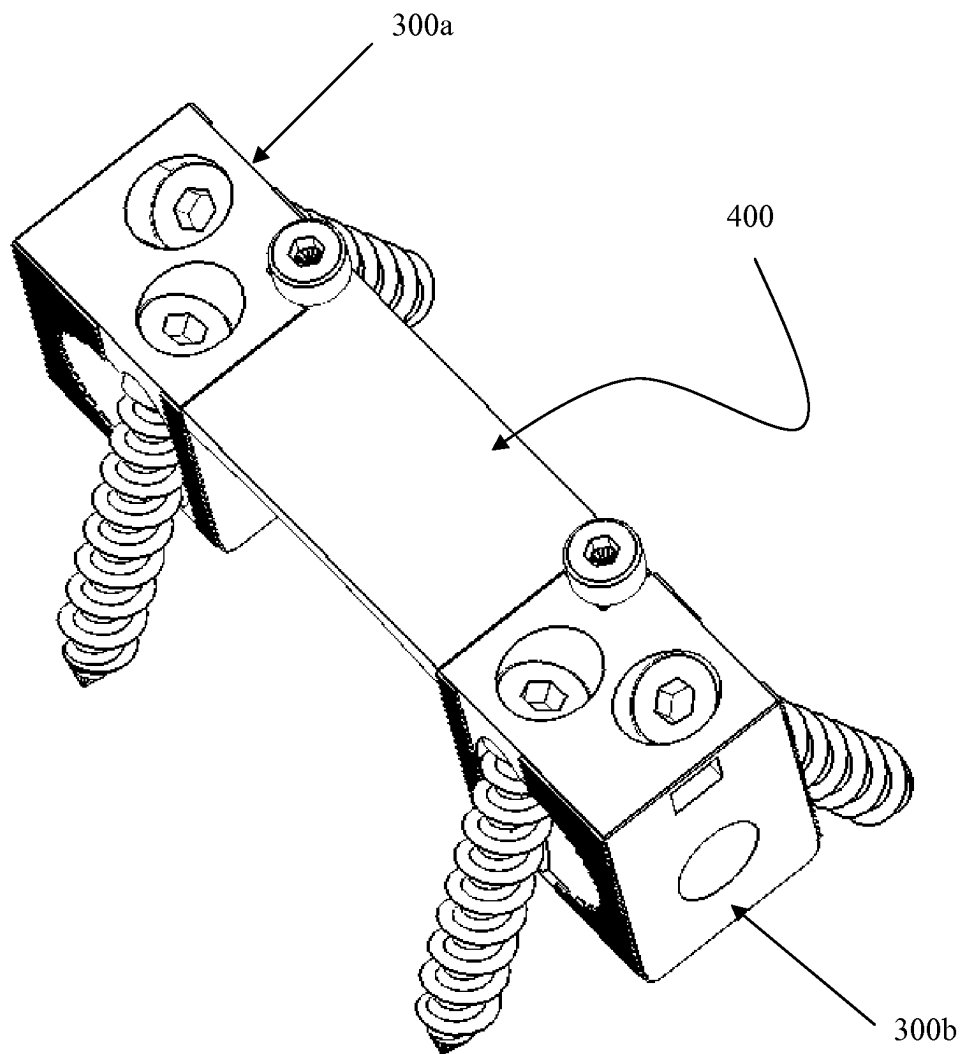


Fig. 4B

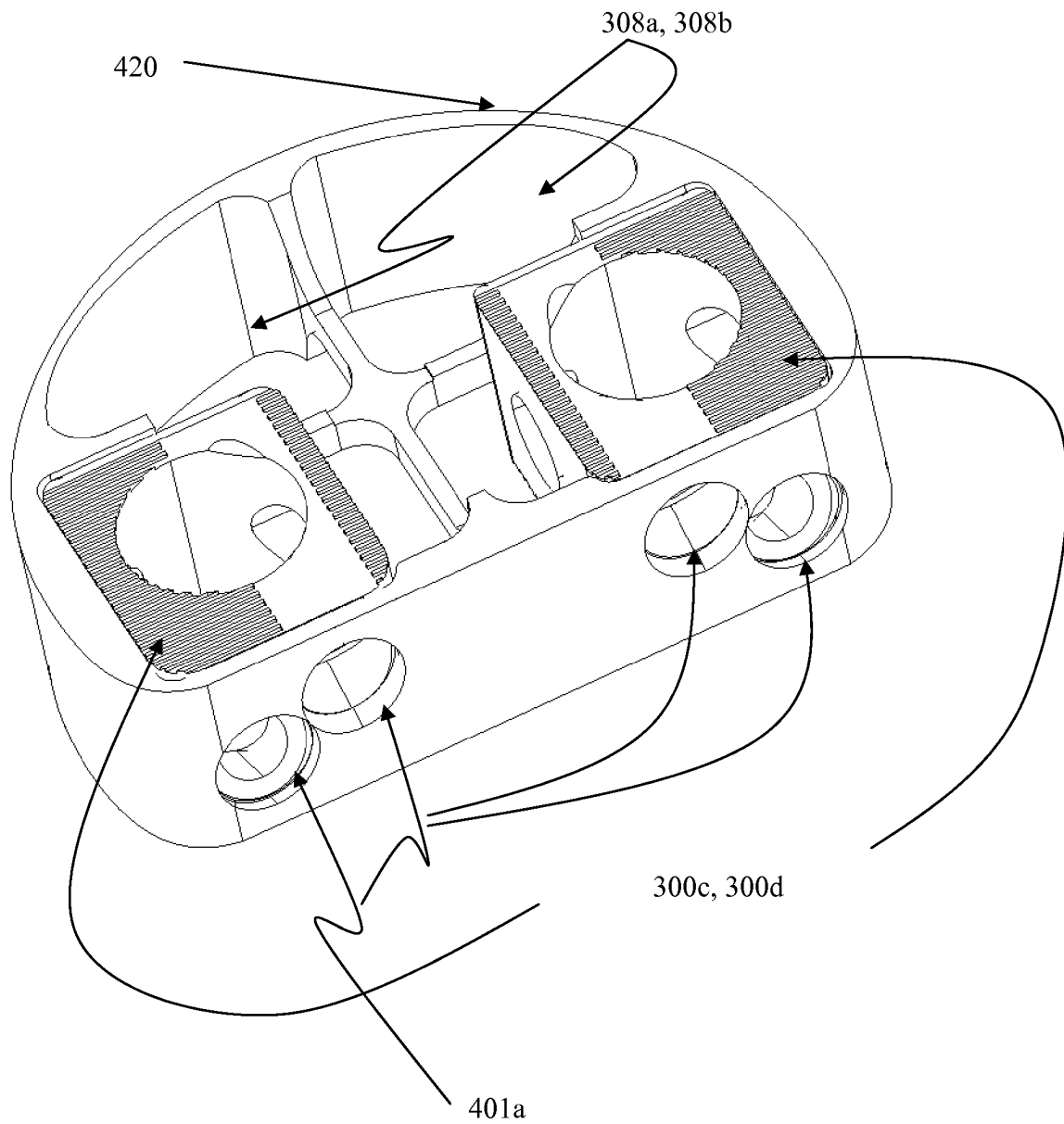


FIG. 4C

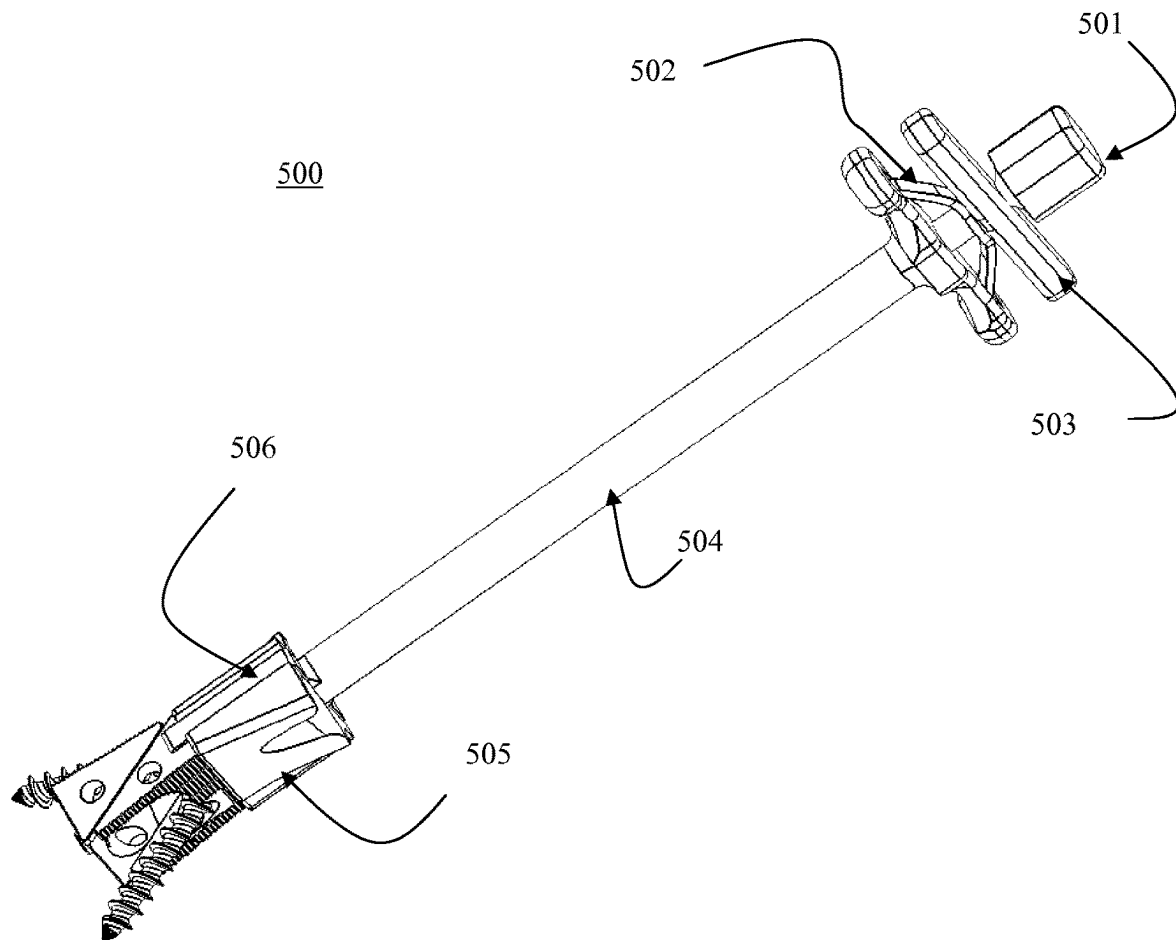


Fig. 5A

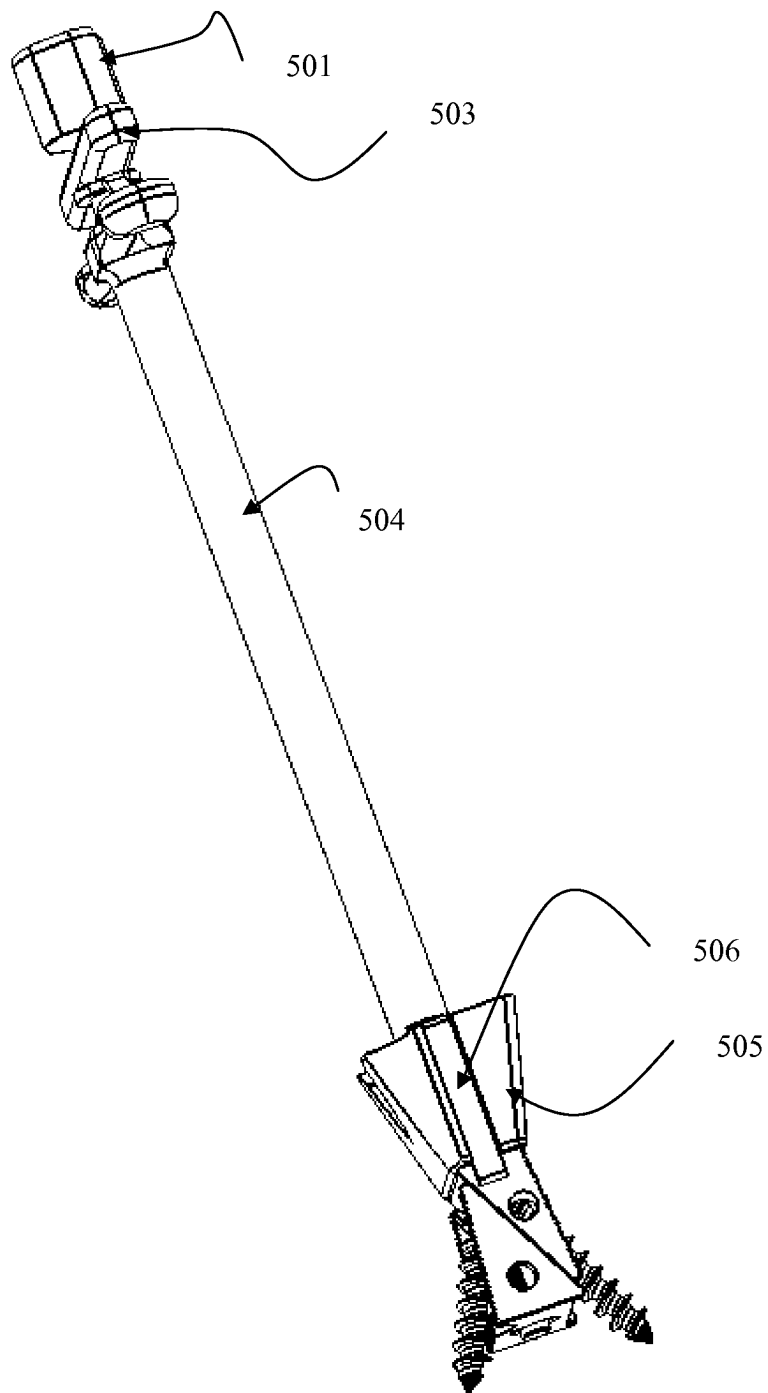


Fig. 5B

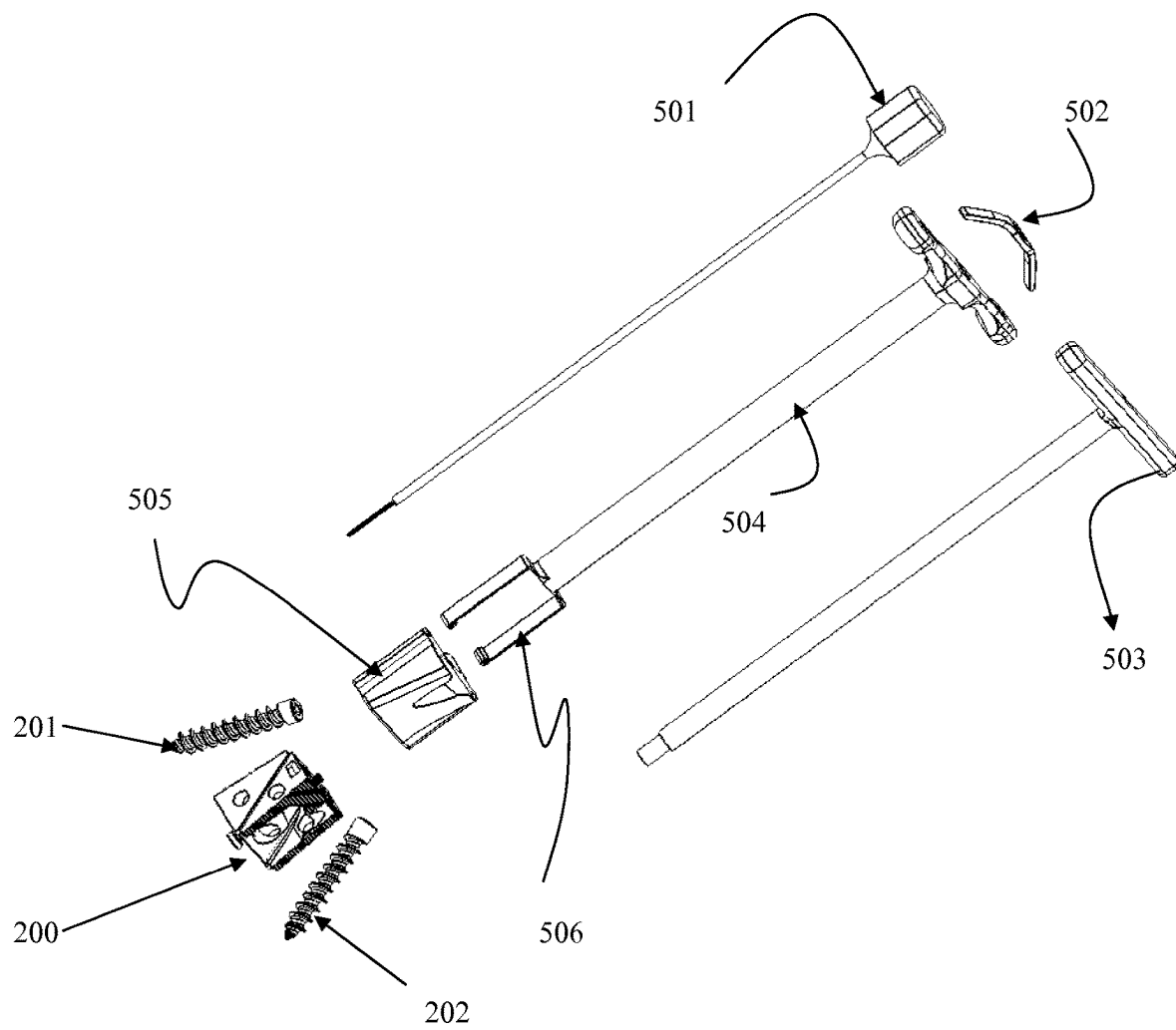


Fig. 5C

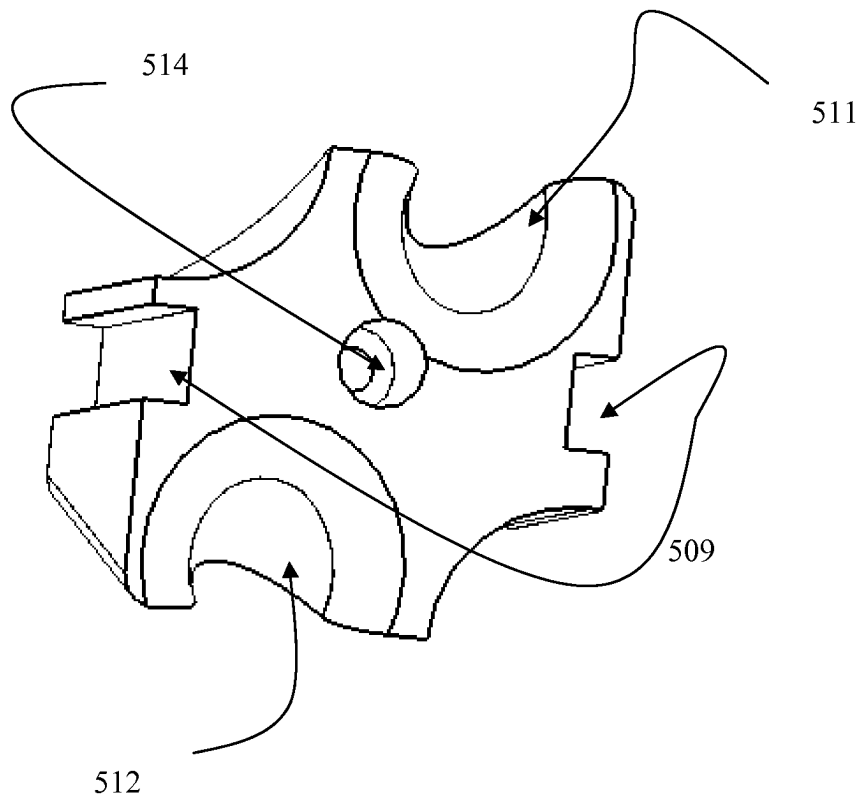


Fig. 5D

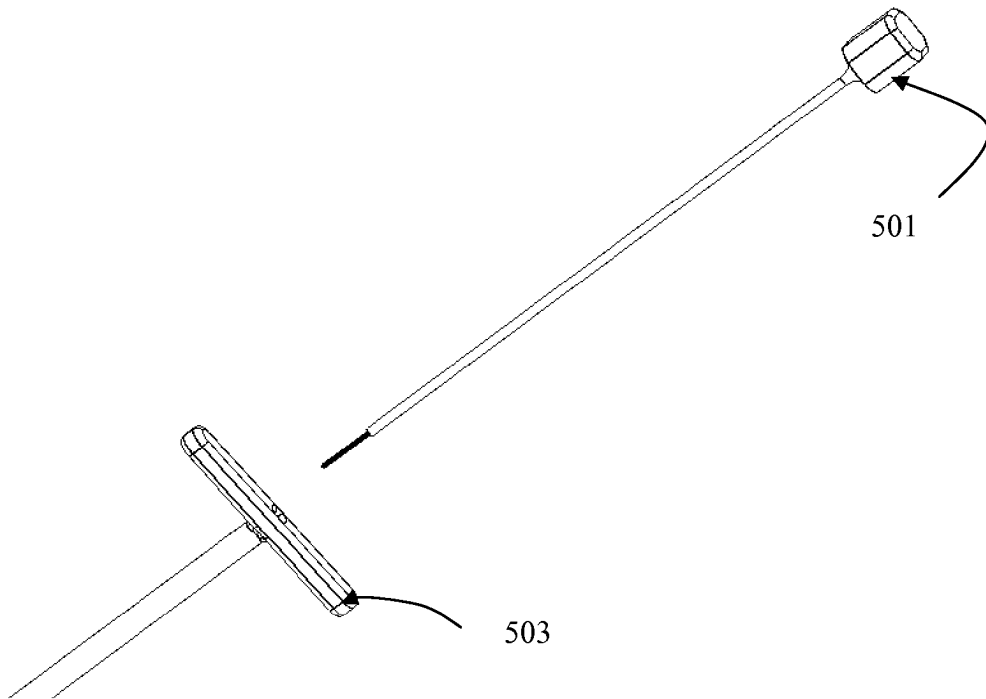


Fig. 5E

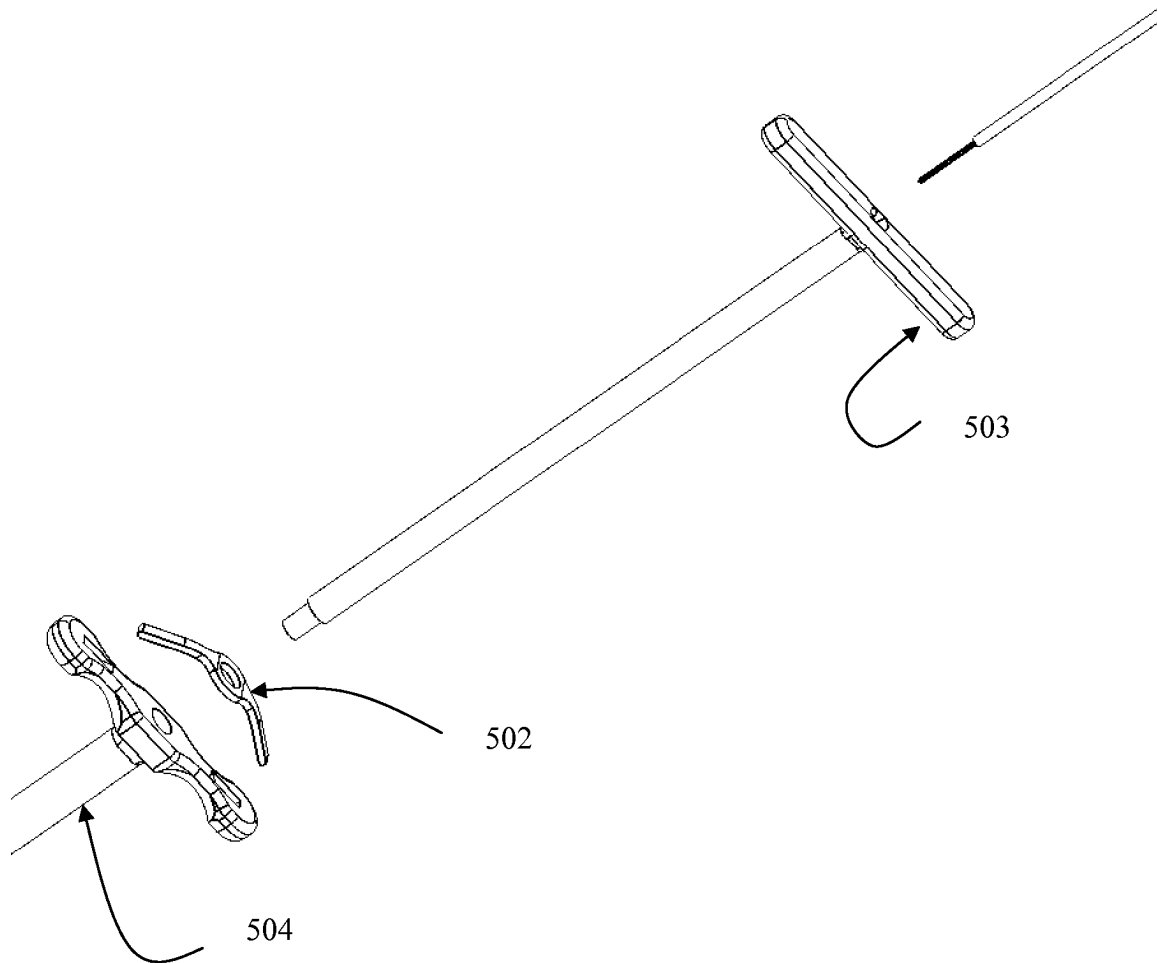


Fig. 5F

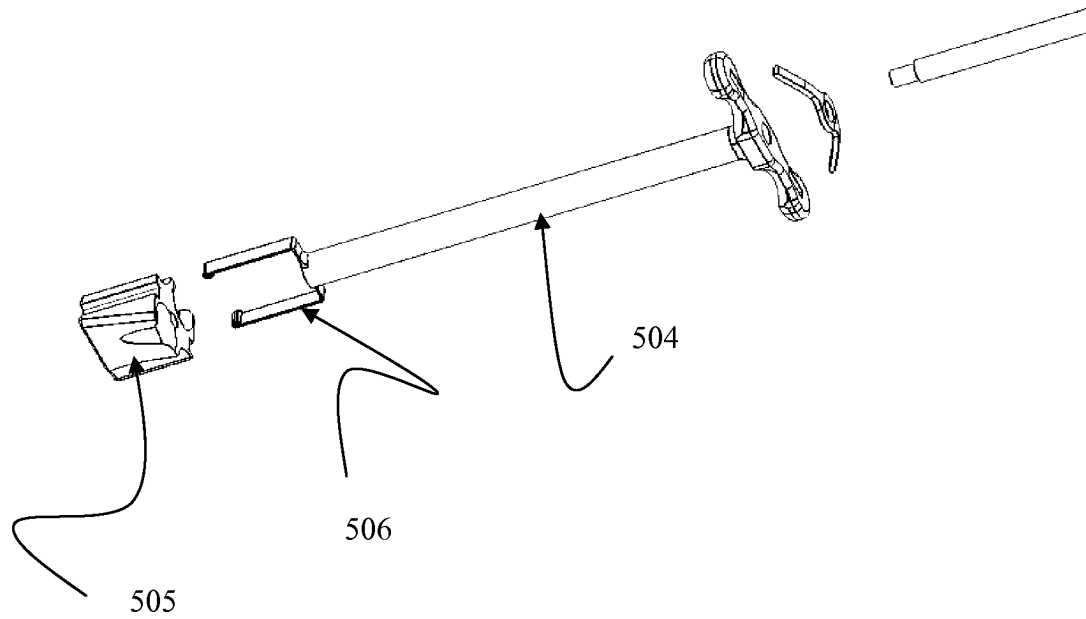


Fig. 5G

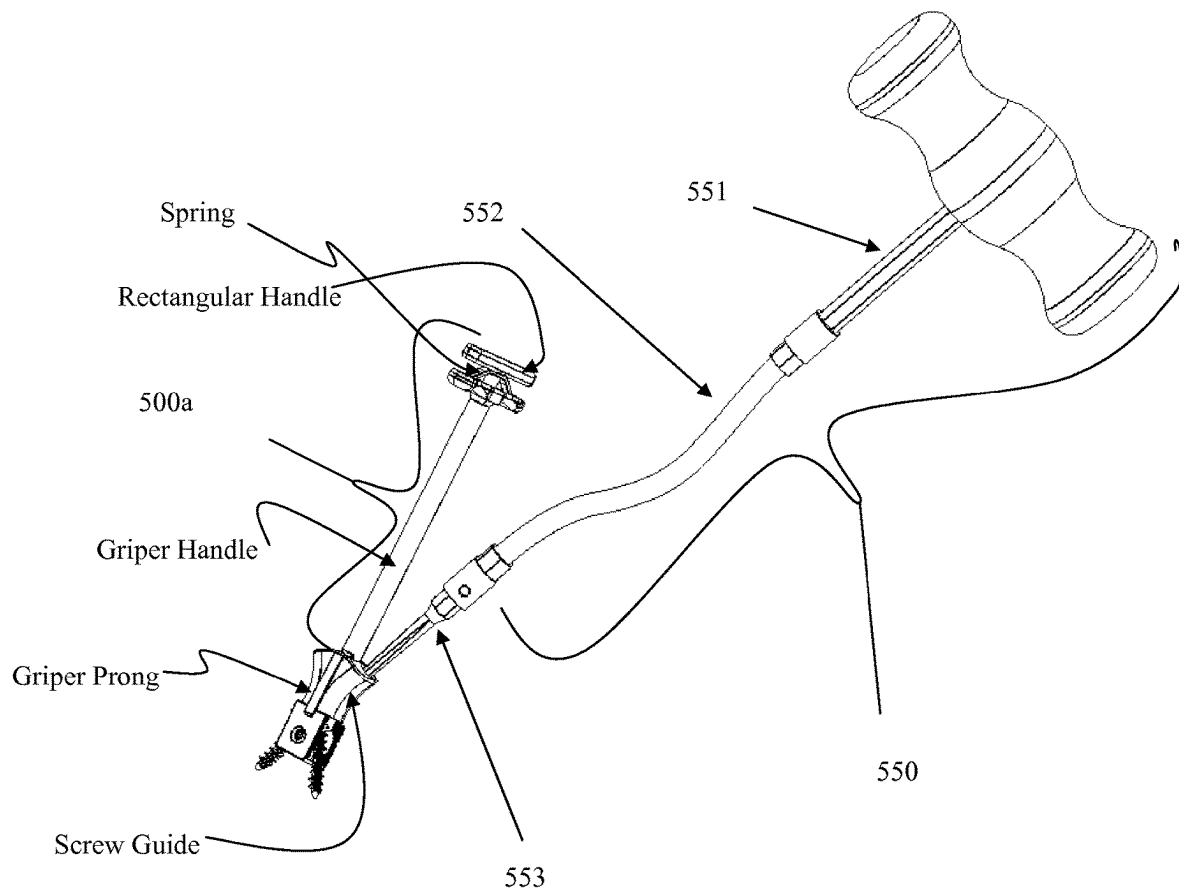


FIG. 5H

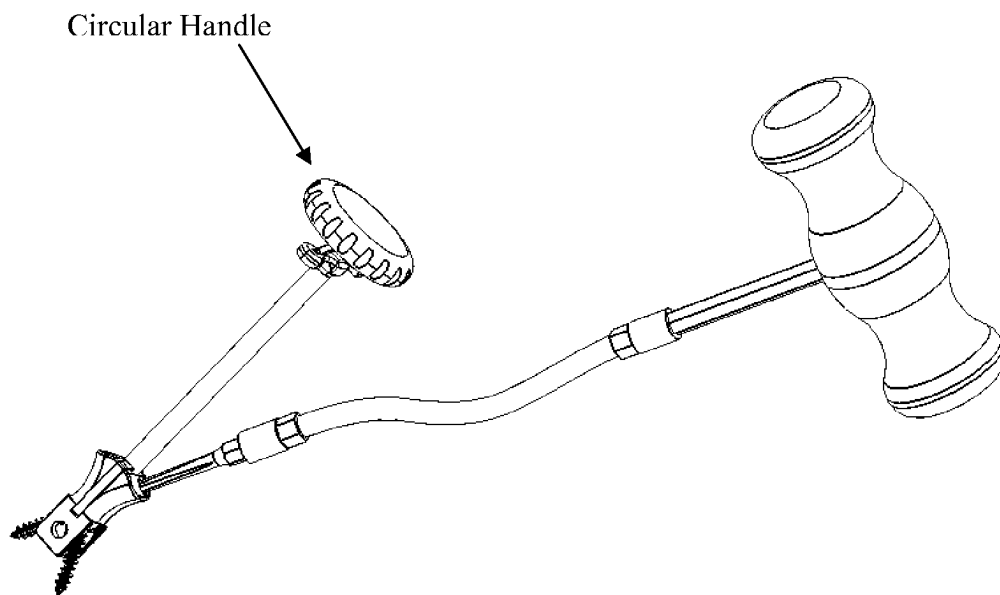


FIG. 5I

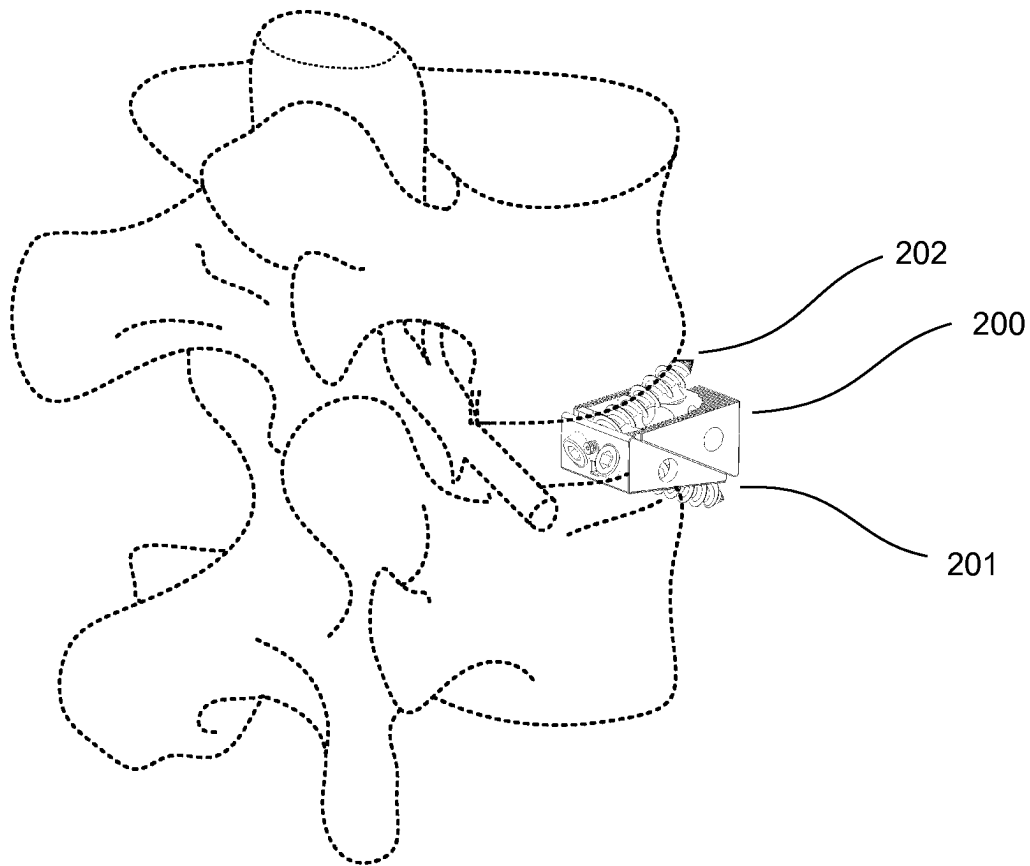


Fig. 6A

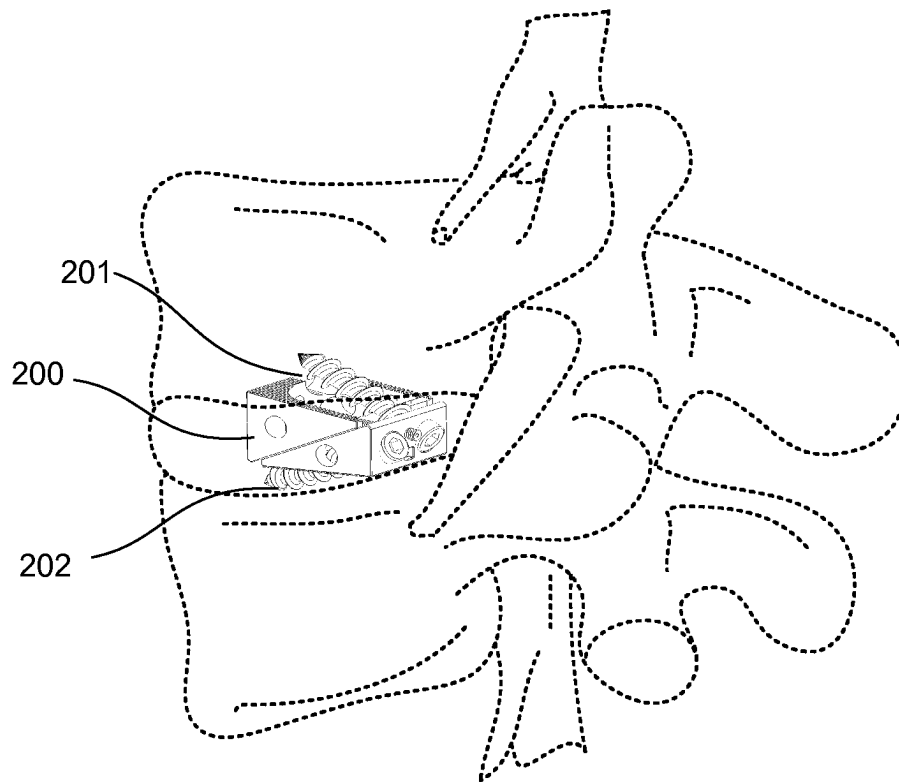


Fig. 6B

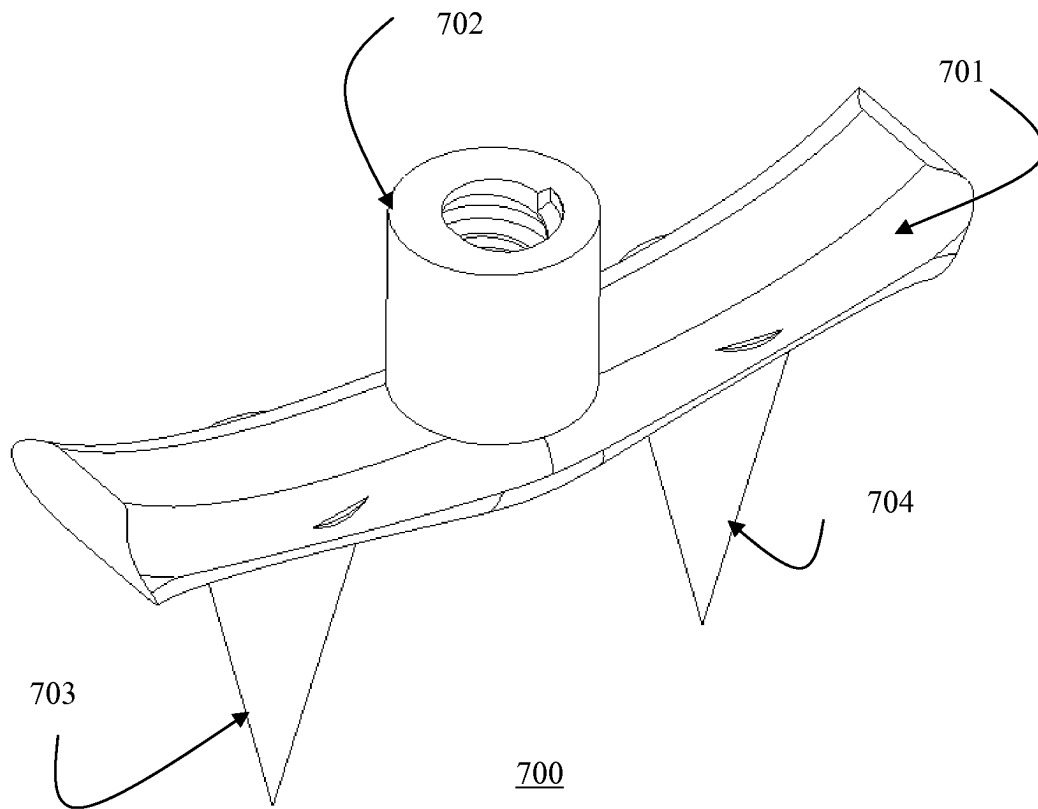


Fig. 7A

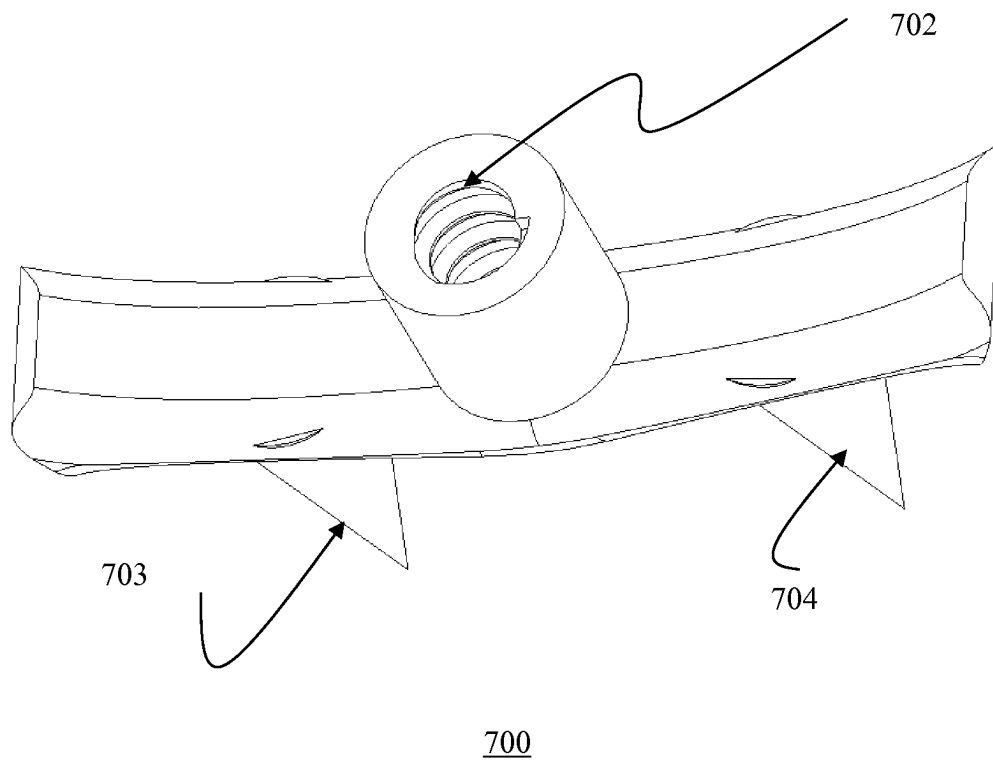


Fig. 7B

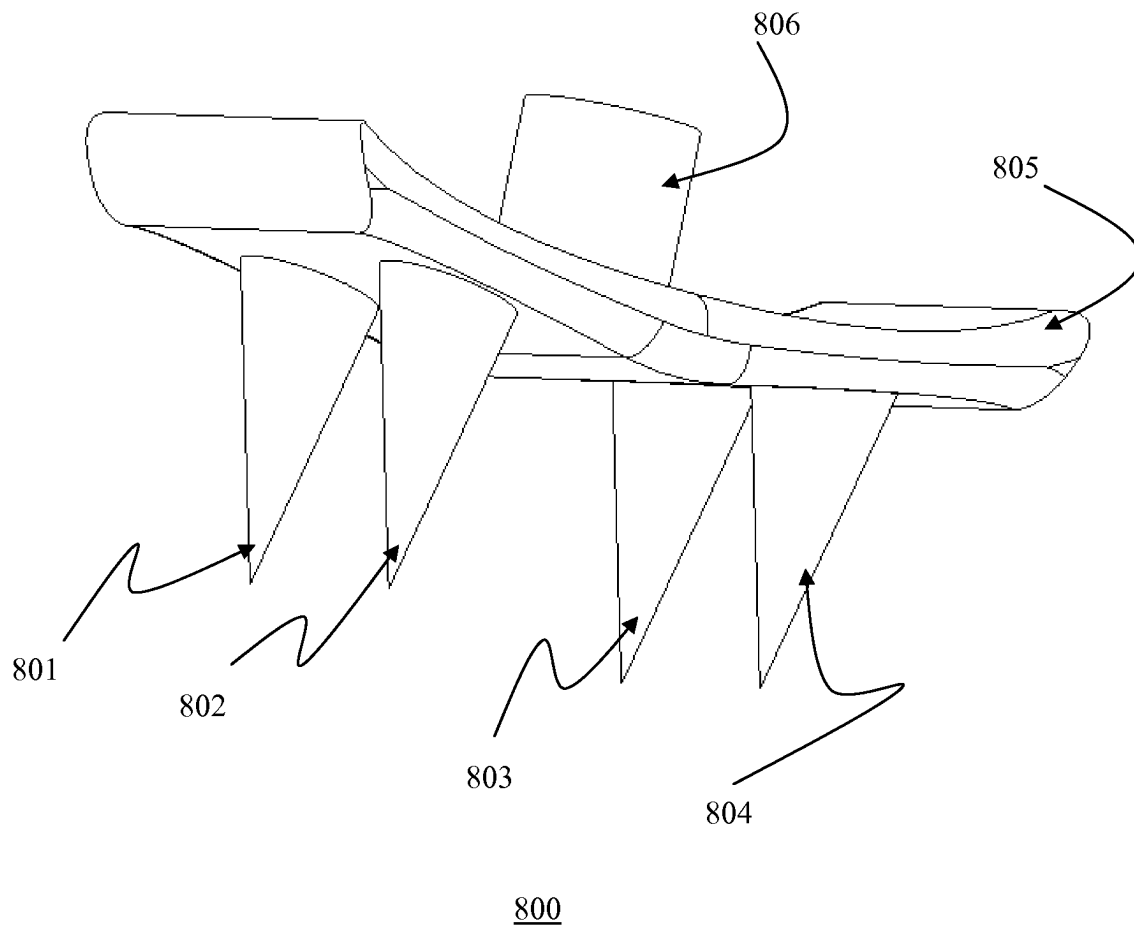


Fig. 8A

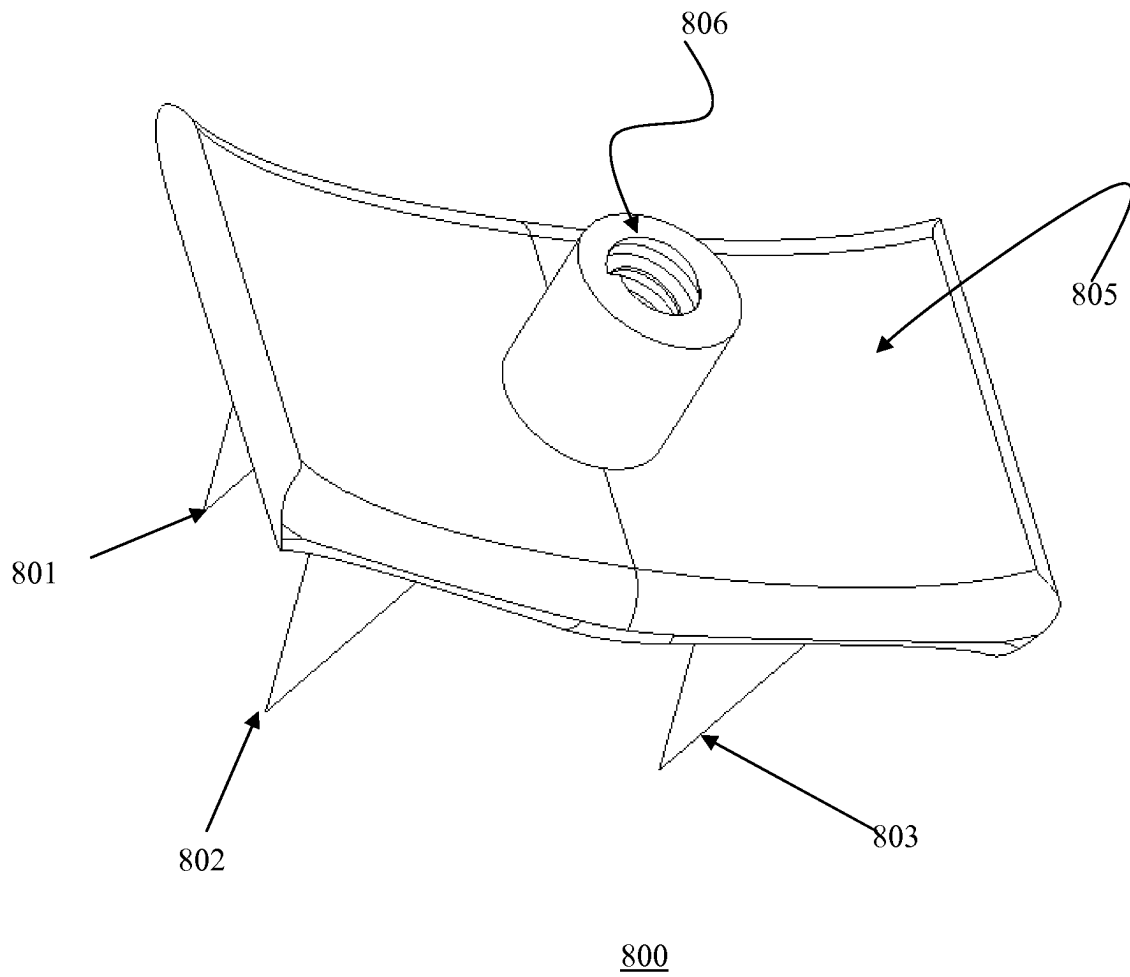


Fig. 8B

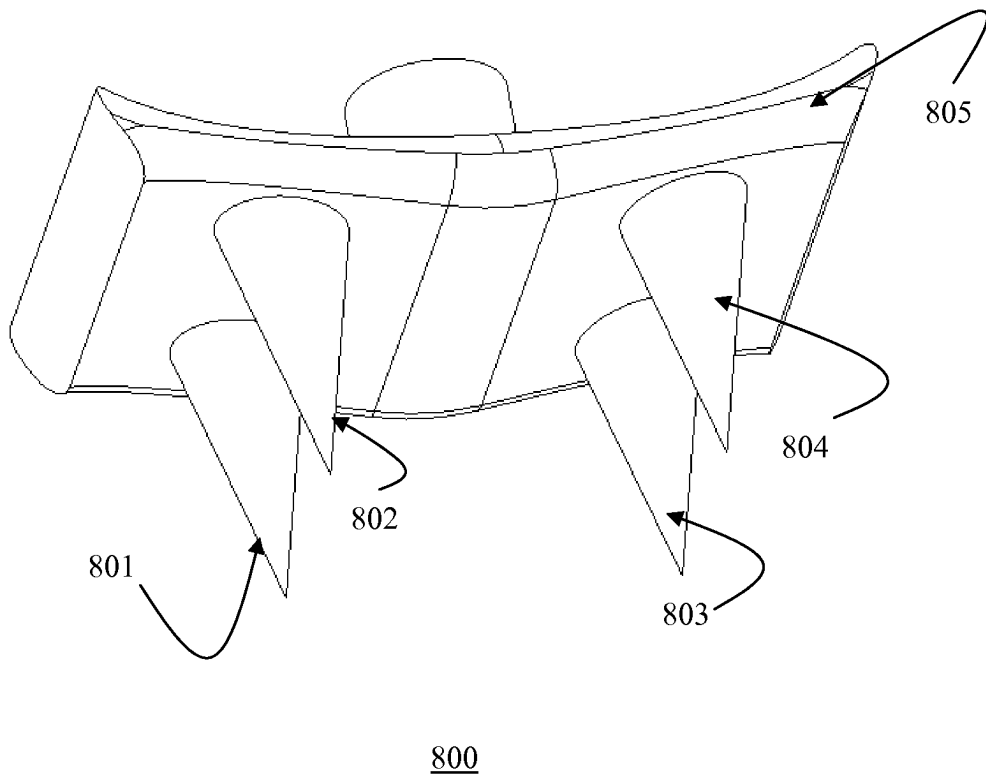


Fig. 8C

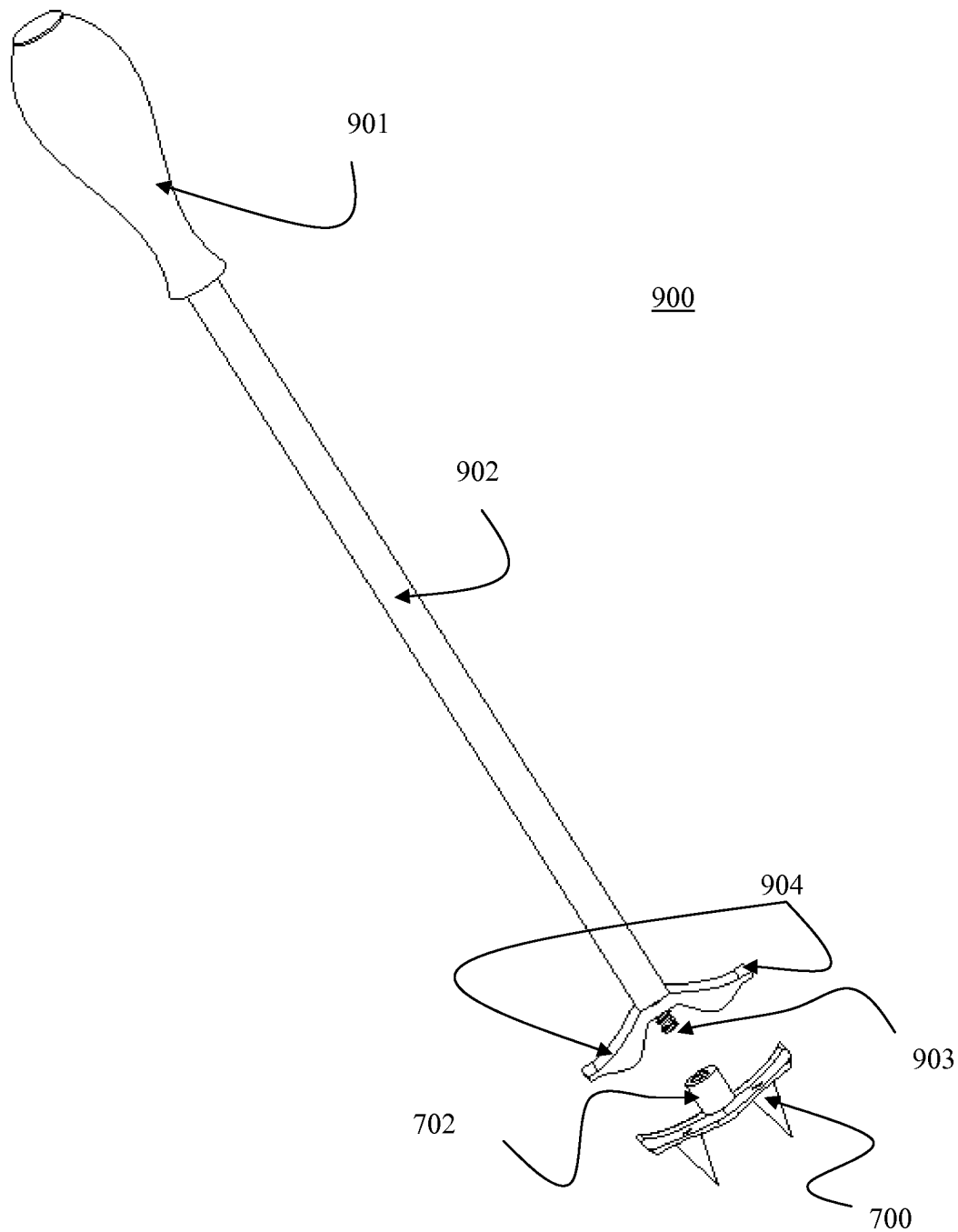


Fig. 9A

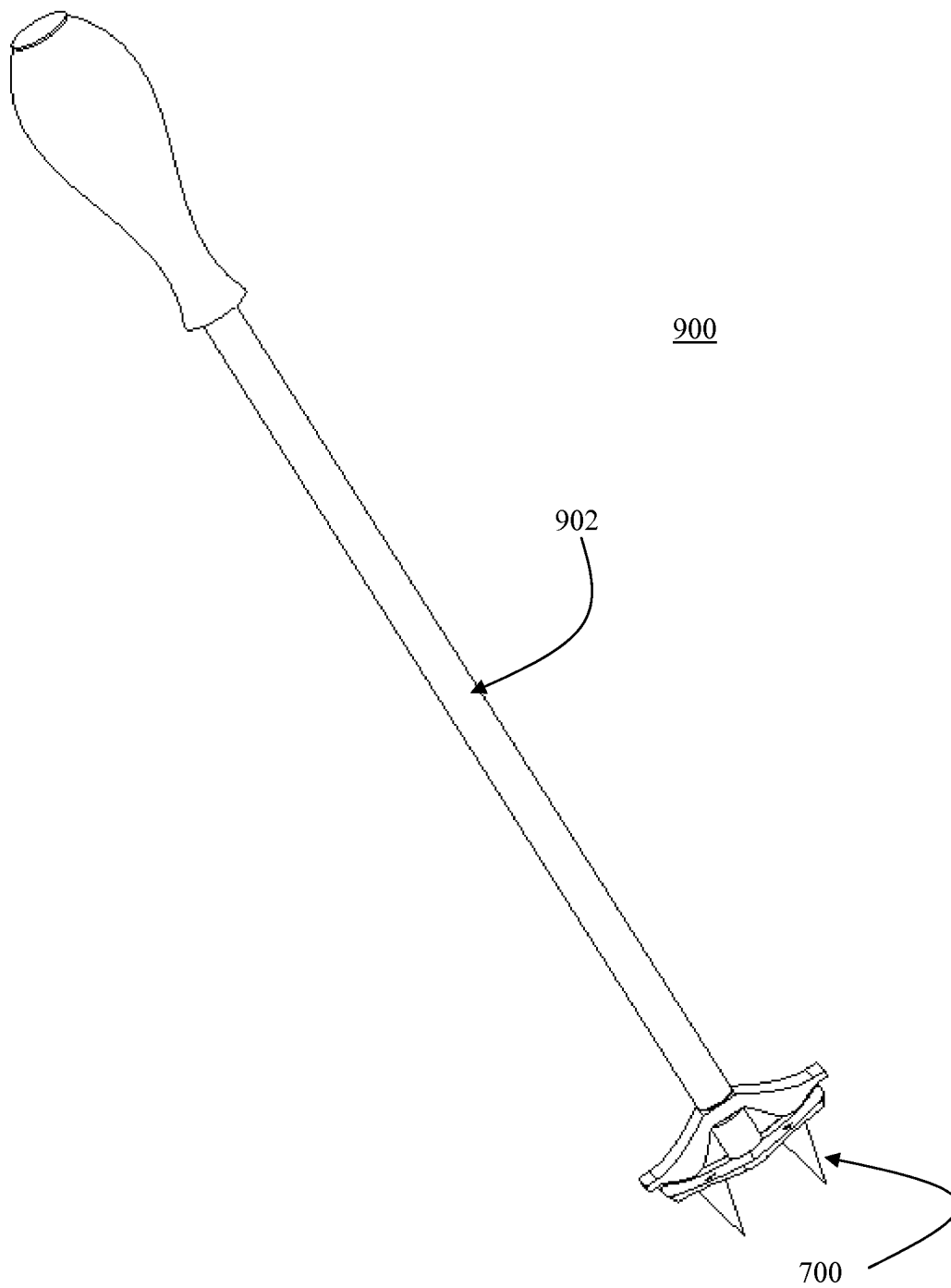


Fig. 9B

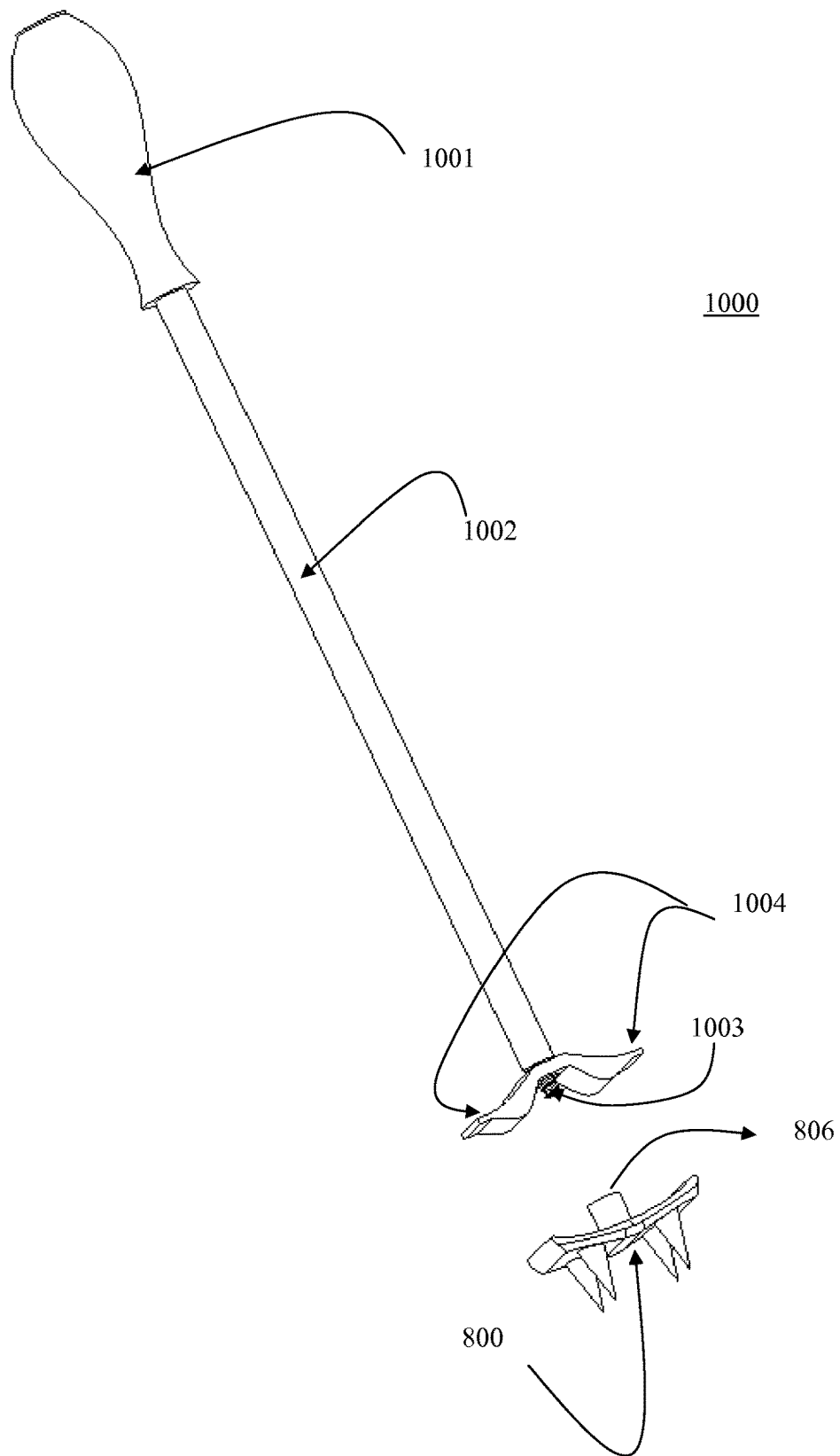


Fig. 10A

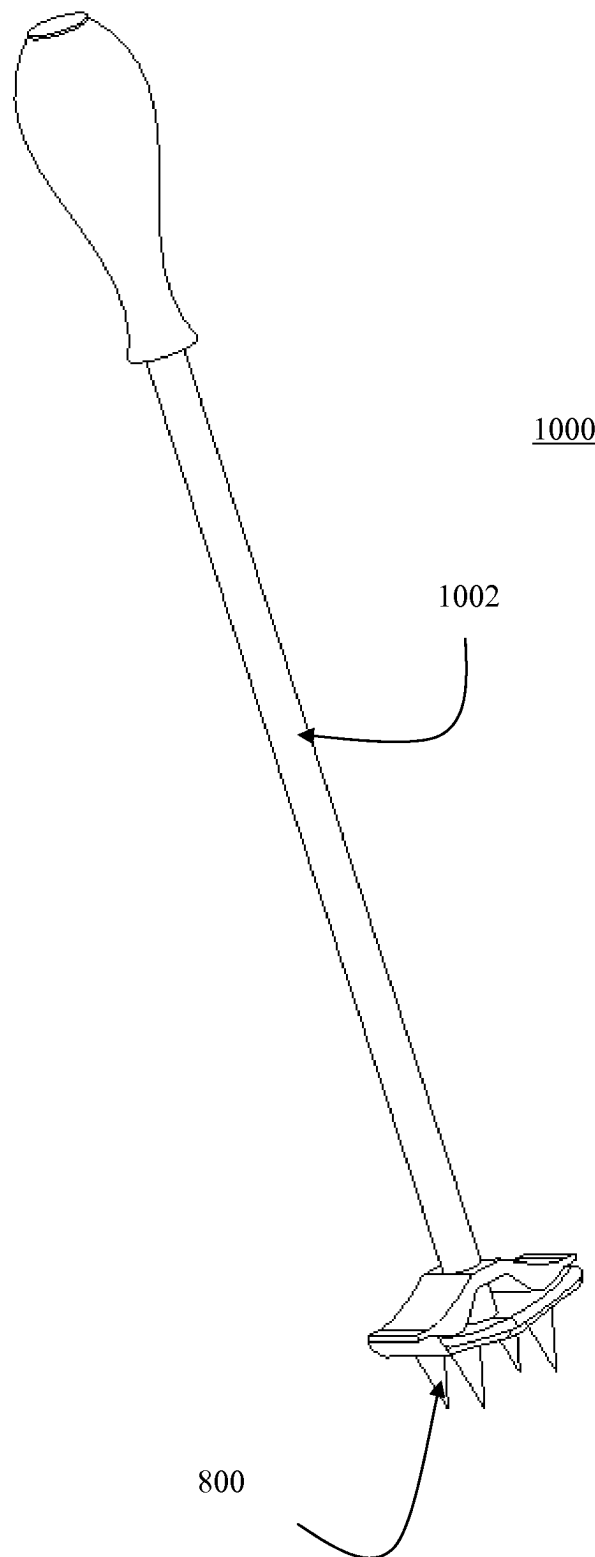


Fig. 10B

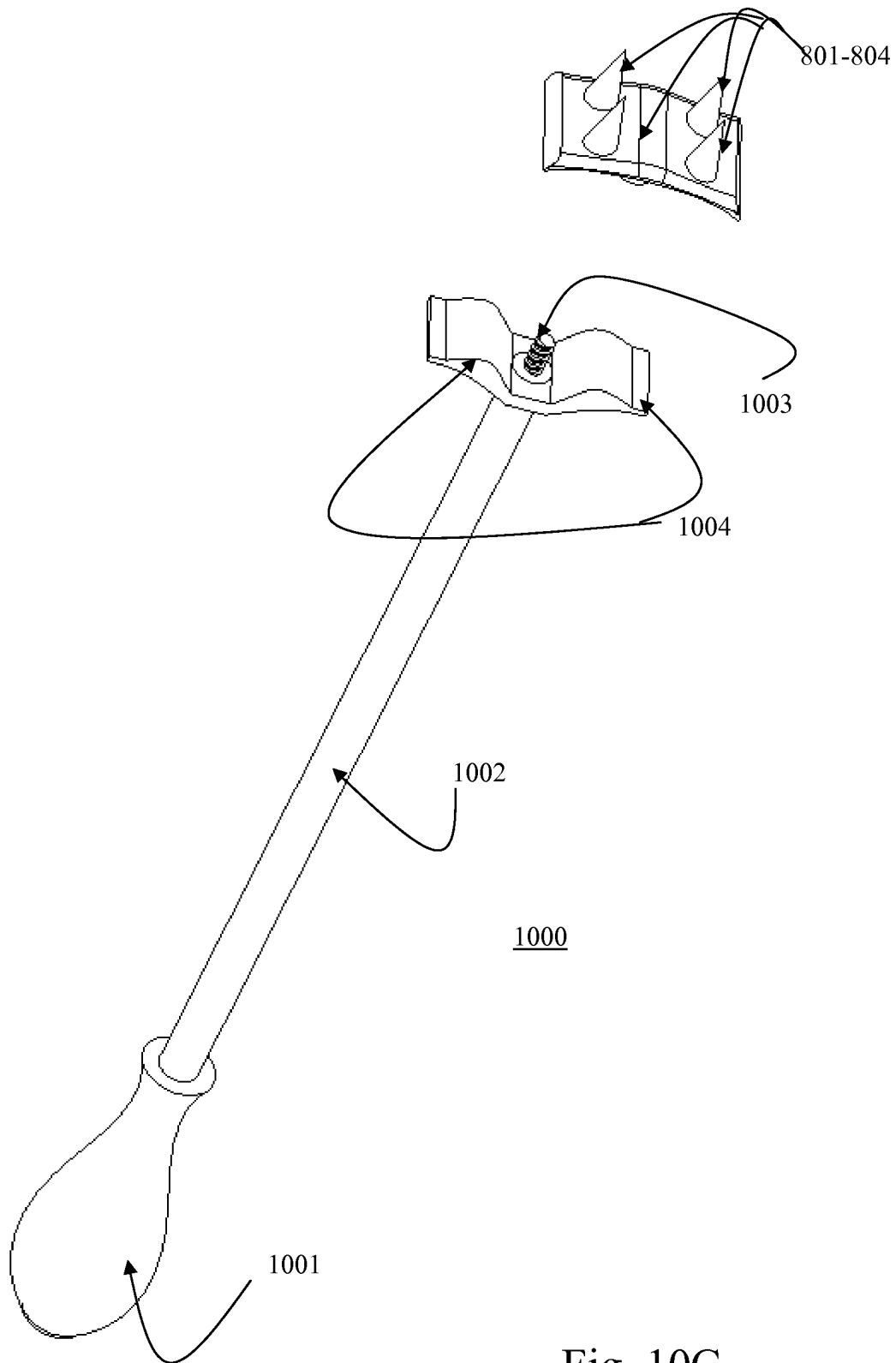


Fig. 10C

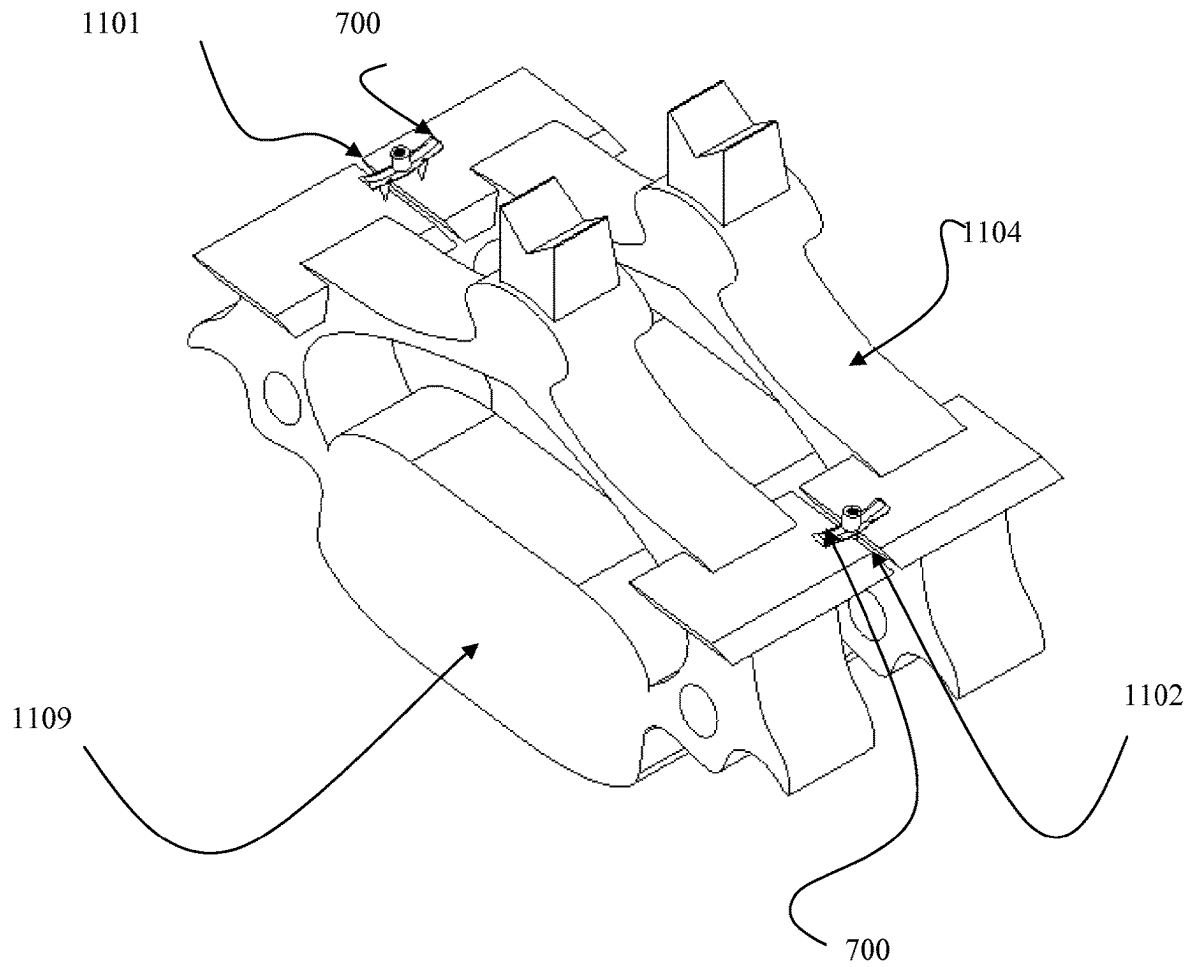


Fig. 11A

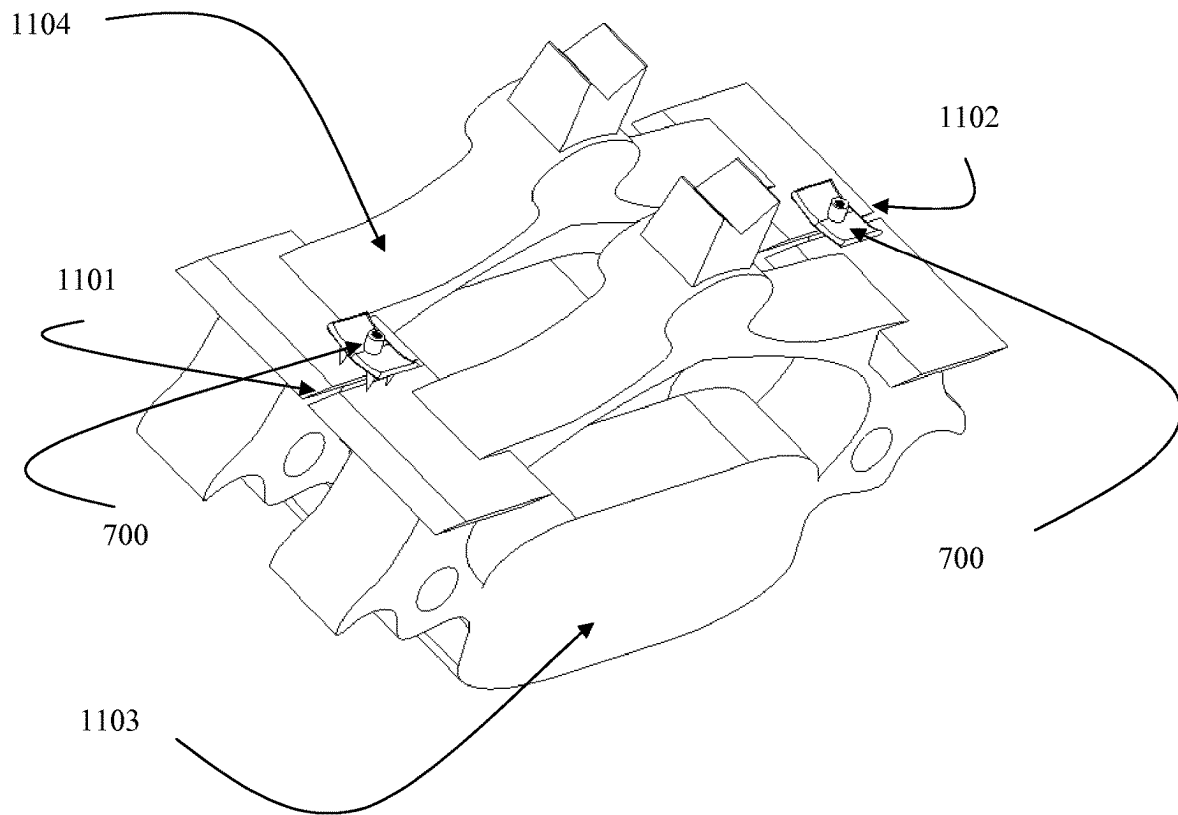


Fig. 11B

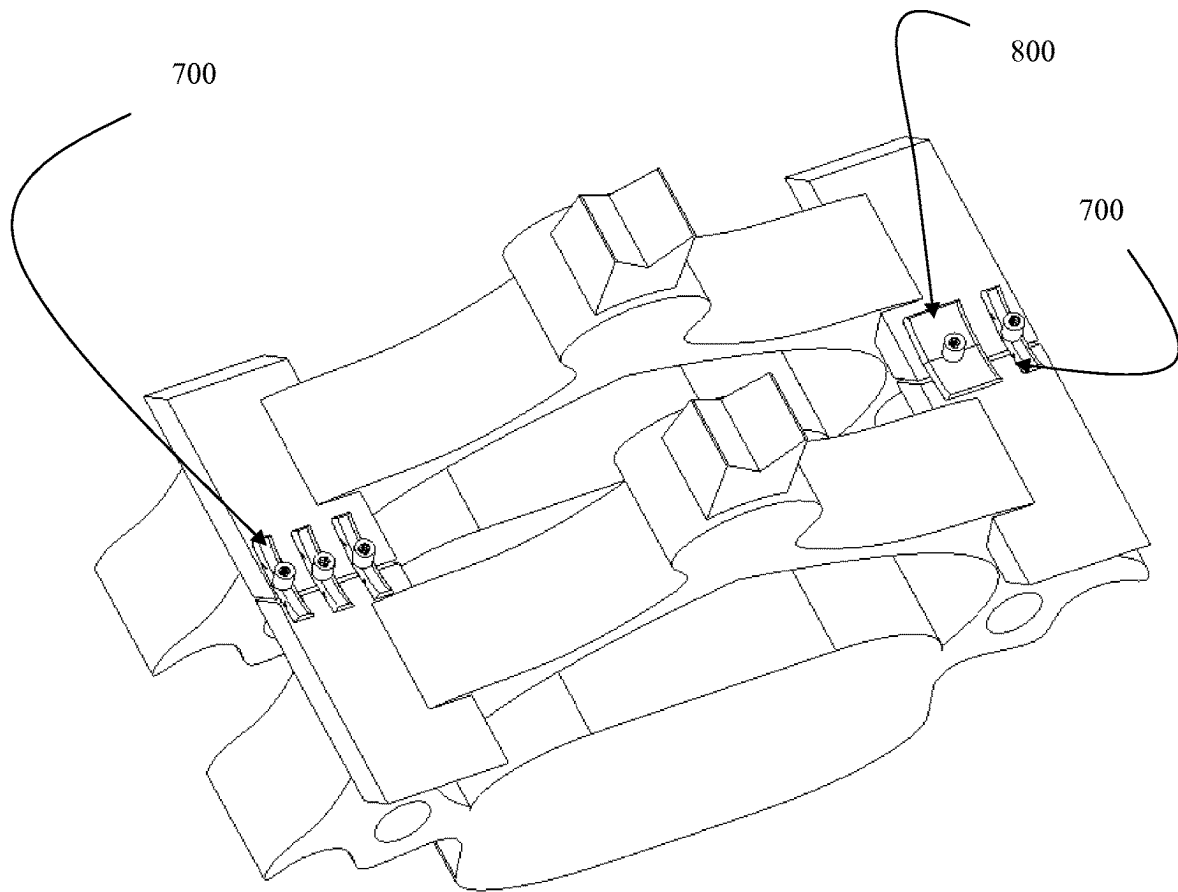


Fig. 11C

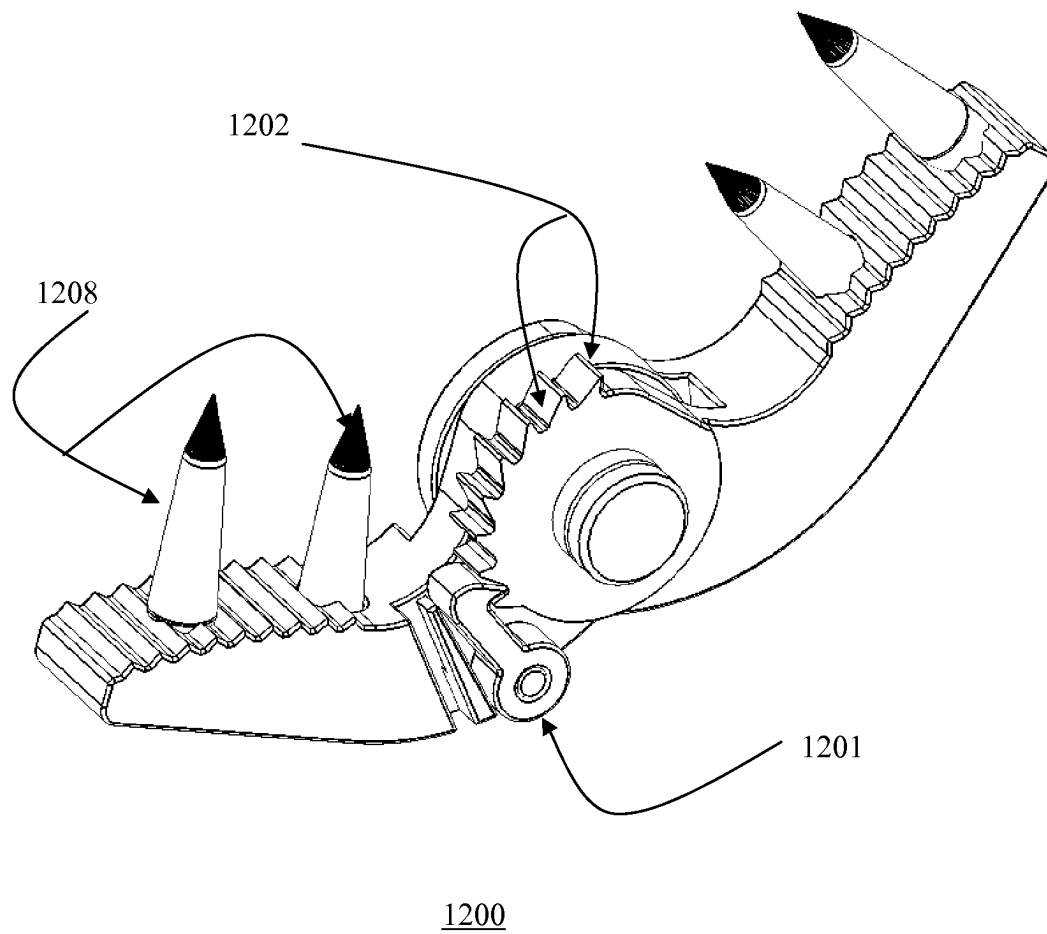


Fig. 12A

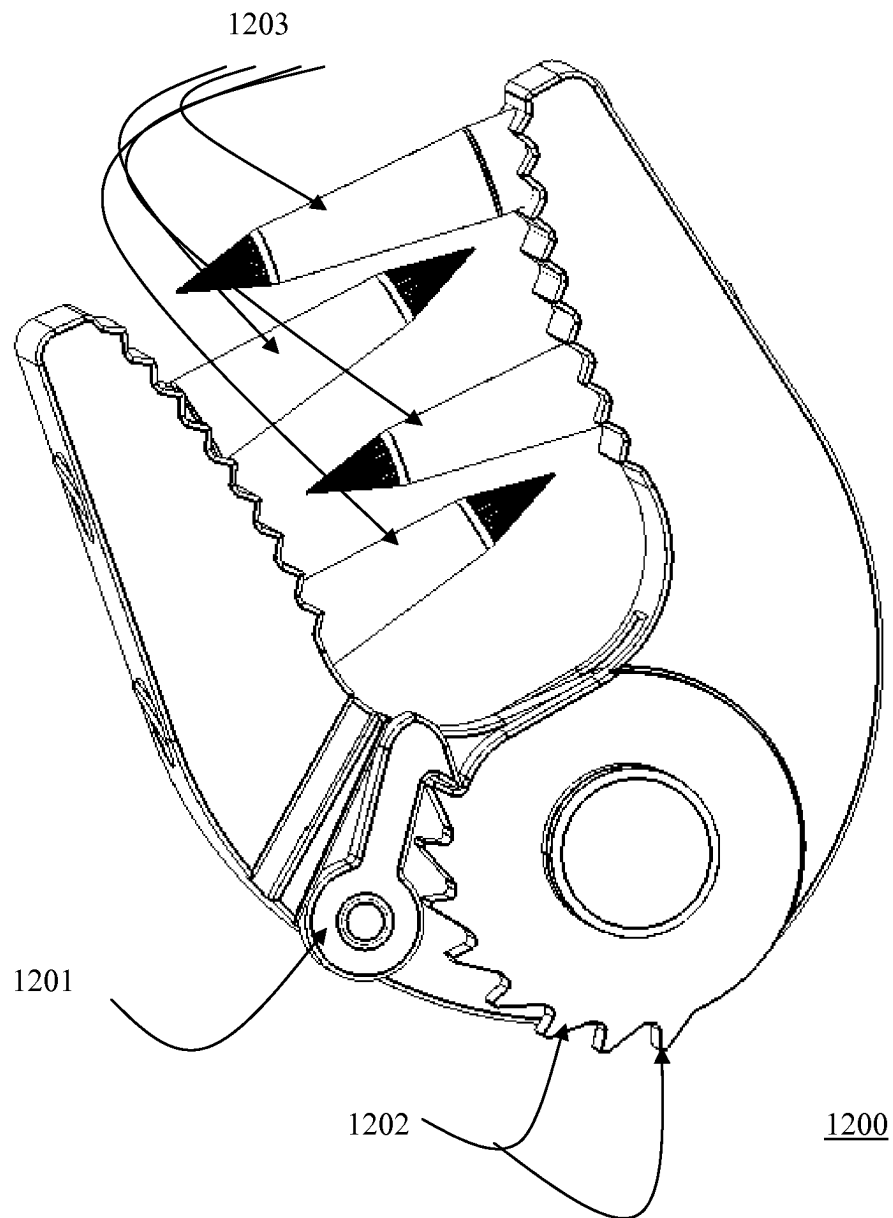


Fig. 12B

1

EXPANDABLE SPINAL IMPLANT AND TOOL SYSTEM

This application is a Continuation Application of U.S. application Ser. No. 15/944,117, filed Apr. 3, 2018 (now U.S. Pat. No. 10,537,442), which is a Continuation Application of U.S. application Ser. No. 15/894,471, filed Feb. 12, 2018 (now U.S. Pat. No. 10,390,969), which is a Continuation of U.S. application Ser. No. 13/210,157, filed Aug. 15, 2011 (now U.S. Pat. No. 9,889,022), which is a Continuation of U.S. Application Ser. No. 13/084,543, filed Apr. 11, 2011 (now U.S. Pat. No. 8,353,913) and Ser. No. 13/108,982, filed May 16, 2011 (now U.S. Pat. No. 9,005,293).

U.S. application Ser. No. 13/084,543 is a Continuation of Ser. No. 11/842,855, filed Aug. 21, 2007 (now U.S. Pat. No. 7,942,903). U.S. application Ser. No. 13/108,982 is a Continuation of Ser. No. 11/842,855, filed Aug. 21, 2007 (now U.S. Pat. No. 7,942,903), which is a Continuation-in-Part of U.S. application Ser. No. 11/536,815, filed Sep. 29, 2006 (now U.S. Pat. No. 7,846,188), which is a Continuation-in-Part of U.S. application Ser. No. 11/208,644, filed Aug. 23, 2005 (now U.S. Pat. No. 7,704,279), which claims priority of U.S. Provisional Application Ser. No. 60/670,231, filed Apr. 12, 2005; the entire contents of all the above identified patent applications are hereby incorporated by reference.

FIELD OF INVENTION

The present invention relates to a unique universal bidirectional screw (BDS) system, and in particular its application to the spine, also referred to as bi-directional fixating transvertebral (BDFT) screws which can be used as a stand-alone intervertebral device which combines the dual functions of an intervertebral spacer which can be filled with bone fusion material(s), as well as a transvertebral bone fusion screw apparatus. In the posterior lumbosacral and thoracic spine, BDFT screw/box constructs can be used independently or supplemented with a novel horizontal mini-plate which prevents upward bone graft intrusion into the thecal sac and nerves. In the anterior lumbosacral spine BDFT screw box constructs can be inserted into and supplemented by a circumferential cage. These posteriorly and anteriorly placed stand-alone intervertebral body fusion constructs may obviate the need for supplemental pedicle screw fixation.

The present invention also relates to stand-alone or supplemental posterior cervical and lumbar calibrated interarticular joint stapling devices which may obviate and/or lessen the need for supplemental pedicle screw fixation.

DESCRIPTION OF THE RELEVANT ART

The history and evolution of instrumented spinal fusion in the entire human spine has been reviewed in our two prior copending application Ser. No. 14/536,815, filed on Sep. 29, 2006, and Ser. No. 11/208,644, filed on Aug. 23, 2005, the related contents of which are hereby incorporated by reference. Currently the majority of posterior cervical and almost all anterior and posterior lumbosacral and thoracic fusion techniques are typically supplemented with pedicle screw placement. Complications of pedicle screw placement in cervical, thoracic and lumbar spine include duration of procedure, significant tissue dissection and muscle retraction, misplaced screws with neural and/or vascular injury, excessive blood loss, need for transfusions, prolonged recovery, incomplete return to work, and excess rigidity leading to adjacent segmental disease requiring further

2

fusions and re-operations. Recent advances in pedicle screw fixation including minimally invasive and image-guided technology, and the development of flexible rods, imperfectly address some but not all of these issues.

Complications of all current spinal interbody fusion devices is their lack of coverage of the majority of the cross-sectional area of the vertebral endplates, and their lack of adequate, if any capacity to penetrate bone, and hence the heightened risk of implant extrusion. Furthermore the bone and biological bone fusion agents which are packed into the intervertebral space can easily blossom and grow upward into the thecal sac causing neural compression, in the absence of a physical barrier between the fusing growing bone, and the thecal sac.

SUMMARY

Herein we describe multiple device embodiments which combine in a single construct the dual functions of an intervertebral spacer maintaining disc space height, and transvertebral body fusion screws.

We also introduce an entirely novel horizontal mini-plate capping off the intervertebral space capable of functioning as a physical barrier preventing upward bone intrusion and/or compression of the ventral thecal sac, and traversing and exciting nerve roots.

Furthermore, we present an advanced mechanism in calibrated posterior facet joint stapling compared to our previous designs illustrated in our co-pending patents. We also introduce the entirely novel concept of posterior cervical facet staples to obviate and/or diminish the need for posterior cervical pedicle screw instrumented fusion. Using combinations and permutations of different embodiments of cervical facet staples in a modular manner advances the concept of flexible fusion in the cervical spine.

To achieve safe, effective and minimally invasive segmental spinal fusion, applicants propose the use of novel bi-directional fixating transvertebral (BDFT) screws which can be strategically inserted via anterior or posterior surgical spinal approaches into the anterior and middle columns of the intervertebral disc space. In our previous applications these bi-directional screws employed turning a wormed driving screw which turns a spur gear which in turn simultaneously turns a rostral oriented screw into the cephalad vertebral body, and a caudal directed screw into the caudal vertebral body. The vertebral bodies above and below the disc space by virtue of their engagement and penetration by the BDFT screws are thus linked, interlocked, and eventually biologically fused with placement of intervertebral bone agents.

In this current application one or more of the described embodiments may eliminate the intervening wormed driving screws and gears required by previous designs, e.g., a gearless screw box is achieved. We have designed a screw box to be placed inter-vertebrally, either unilaterally or bilaterally, in particular, posteriorly between vertebral bodies. The housing screw box incorporates built-in screw and/or drill guides which allow the direct placement and insertion of two self drilling screws which are driven in two opposing directions into superior and inferior vertebral bodies, respectively. One screw within the screw box is angled superiorly, and the other screw in the screw box is angled inferiorly.

In yet another embodiment, in addition to these features we designed an expanding screw box with sliding triangular bases to house two screws driven in two opposing directions which can be expanded in two simultaneous directions,

3

height and depth, by turning a built-in screw adjuster. This is accomplished by a combined positioning tool/screw guide/cage expander to further enhance trajectory precision and to simultaneously expand the screw box in height and depth to custom-fit the individual disc space height. This embodiment has two sub-embodiments; one has two laterally oriented BDFT screws, and the other has a lateral and a medial oriented BDFT screw. These innovations represent a continued evolution of our concept of expandable fusion cages described in our previous co-pending patents.

In yet another embodiment we designed a screw box which houses only one, instead of two screws. Each box allows the placement of one superior or inferior directed screw on one side (left or right), and the contra lateral screw box device allows placement of an inferior or superior oriented screw which goes in the opposite direction of the contra lateral device. In totality these two separate single screw boxes fuse the superior and inferior vertebrae. The potential advantage of this embodiment is that it diminishes the width of the screw box in cases where it might be favorable to have less nerve root retraction with a smaller width device.

In all screw-box embodiments, a rostral-directed screw is passed through one built-in screw guide of the device which then is inserted and screwed into the superior vertebral body. Then a caudally directed screw is passed through an adjacent built-in screw guide which then is inserted and screwed into the inferior vertebral body. The novelty of this design is the built-in prescribed angles of the integral screw guides which allow the posterior transvertebral penetration into the vertebral bodies. This is a truly amazing feat accomplished in the posterior lumbar spine considering the small anatomically restricted work zone within which to work, which is very narrowly prescribed by obtuse angulations between screw and intervertebral bone surfaces, and by nerve root, facet joint and pedicle. We have also designed a positioning tool for the placement of the non-expandable screw boxes which has a screwdriver with a flexible shaft specifically designed to fit these devices if a straight screw driver impedes screw placement. Hence these external tools provide the means in any circumstance to accomplish precision screw trajectory. The embodiments described herein compared to our previous co-pending patent designs, streamline and ease production of bi-directionally oriented transvertebral screws, and allows placement of longer and wider screws with greater bone penetration to provide yet a sturdier fusion construct. The designs are also easily modifiable for anterior placement into the cervical spine. The expandable embodiment of the screw box can also be enlarged and modified to be suitable for cervical, thoracic and lumbar vertebral body replacements.

The box casings have multiple perforations to allow both screw traversal and horizontal bone packing preventing upward vertical migration of bone. The boxes prevent subsidence. Both the inside of the denuded intervertebral space, and the screw boxes can be packed with autologous or allograft bone, BMP, DBX or similar osteoconductive material. Posteriorly or anteriorly in the lumbar spine, these screws can be capped with a horizontal mini-plate which will prevent bony growth into the thecal sac and nerves. We refer to this as a two-in-one device, i.e. two screw boxes/BDFT screws combined with one horizontal mini-plate. This is an entirely novel concept in posterior lumbar spinal surgery. In yet another embodiment two BDFT screw boxes can be combined with a circumferential cage (also 2 in 1) to be placed anteriorly into the lumbar spine.

4

It is believed that BDFT-screw constructs provide as strong or stronger segmental fusion as pedicle screws without the complications arising from pedicle screw placement which include screw misplacement with potential nerve and/or vascular injury, violation of healthy facets, possible pedicle destruction, blood loss, and overly rigid fusions. By placing screws across the intervertebral space from vertebral body to vertebral body, engaging anterior and middle spinal columns, and not the vertebral bodies via the transpedicular route, the healthy facet joints, if they exist, are preserved. Because this technique accomplishes both anterior and middle column fusion, without rigidly fixating the posterior column, it in essence creates a flexible fusion. This device therefore is a flexible fusion device because the preserved posterior facet joints retain their function achieving at least a modicum of mobility and hence a less rigid (i.e. a flexible) fusion.

The very advantage of transpedicular screws which facilitate a strong solid fusion by rigidly engaging all three spinal columns is the same mechanical mechanism whereby complete inflexibility of all columns is incurred thereby leading to increasing rostral and caudal segmental stress which leads to an increased rate of re-operation.

Transvertebral fusion also leads to far less muscle retraction, blood loss, and significant reduction in O.R. time. Thus the complication of pedicular screw pull-out and hence high re-operation rate associated with the current embodiment of flexible fusion pedicle screws/rods is obviated. The lumbosacral screw box embodiments and BDFT screws can be introduced via posterior lateral, transforaminal or anterior interbody fusion approaches/techniques. Although one can opt to supplement these screws with transpedicular screws there would be no absolute need for supplemental pedicle screw fixation with these operative techniques.

BDFT screw constructs outlined here can also be combined with novel zero-profile horizontal cervical and, lumbar/thoracic mini-plates. Likewise one or two of these devices can be inserted anteriorly with or without circumferential cage supplementation.

Because the BDFT screws engage a small percentage of the rostral and caudal vertebral body surface area, multi-level fusions can be performed with these devices.

Previous improvements included a novel calibrated lumbar/thoracic facet stapling device which staples the inferior articulating facet of the superior segment to the superior articulating facet of the caudal vertebral segment unilaterally or bilaterally, which may minimize motion until interbody fusion occurs. In the present patent application we introduce a new design of the staple enhancing its calibrating capability.

In this patent application we also introduce a novel posterior cervical facet stapling device which staples the inferior articulating facet of the superior cervical segment with the superior articulating facet of the caudal vertebral segment unilaterally or bilaterally.

The advantage of cervical facet staples is speed and safety. The risks of cervical facet pedicle screw fixation which include nerve root and vertebral artery injuries are completely obviated. Thus they thereby achieve the same function of pedicle screws without the risks.

Placement of different embodiments of the cervical facet staples along unilateral and/or bilateral facet joints in a modular manner, lead to differing degrees of calibrated motion joint motion hence introducing for the first time the concept of calibrated cervical fusion.

Currently failed anterior lumbar arthroplasties are salvaged by combined anterior and posterior fusions. BDFT

5

screw constructs could be utilized as a one-step salvage operation for failed/extruded anteriorly placed lumbar artificial discs obviating the above salvage procedure which has far greater morbidity.

For example, in one general aspect, a self-drilling bone fusion screw apparatus includes a first sliding box, a second sliding box, positioned relative to the first sliding box, a first screw member having a tapered end and a threaded body disposed within the first sliding box, a second screw member having a tapered end and a threaded body disposed within the second sliding box, and an adjuster for adjusting the height of the sliding boxes.

Implementations of this aspect may include one or more of the following features. For example, the first and second screw members may be medially aligned. At least one of the first and second screw members may be laterally aligned. The first and second screw members are laterally aligned. One of the first and second screw members is laterally aligned and the other screw member is laterally aligned. The first and second sliding boxes may be substantially triangularly shaped. The triangularly shaped first and second sliding boxes may include a sliding rail and ridged surfaces. The triangularly shaped first and second sliding boxes may include holes for bone grafts. The adjuster may include a screw.

In another general aspect, a self-drilling bone fusion screw apparatus includes a box, a first screw member having a tapered end and a threaded body disposed at least partially within the box and laterally aligned with the box, a second screw member having a tapered end and a threaded body disposed at least partially within the box and laterally aligned with the box, and a plurality of ridges disposed on along the sides of the box.

Implementations of this aspect may include one or more of the following features. For example, the apparatus may include bone graft holes. The apparatus may be attachable to a second self-drilling fusion screw apparatus via a plate.

In another general aspect, a self-drilling bone fusion screw apparatus may include a first box, a first screw member having a tapered end and a threaded body disposed at least partially within the first box and laterally aligned with the first box, a second box, a second screw member having a tapered end and a threaded body disposed at least partially within the second box and laterally aligned with the second box, and an attachment member for engaging the first and second boxes.

Implementations of this aspect may include one or more of the following features. For example, the self-drilling bone fusion screw apparatus may include bone graft holes. The plate may be directly joined to the first and second boxes by a plurality of screws. The attachment member for engaging the first and second boxes may include a plate or the attachment member may include a circumferential cage defining at least one recess. The first and the second boxes may be positioned within or securely held within the recess of the circumferential cage, e.g., with an interference fit.

In another general aspect, a tool assembly for manipulating a self-drilling bone fusion screw apparatus includes a handle, a gripper cooperating with the handle and having a plurality of prongs, a screw guide, held in place the plurality of prongs, for controlling the direction of self-drilling screws that are screwed into a vertebral body.

Implementations of this aspect may include one or more of the following features. For example, the tool assembly for manipulating a self-drilling bone fusion screw apparatus may include a key for controlling an adjustment device which controls the height of the self-drilling bone fusion

6

screw apparatus. The tool assembly according to claim may include a driver assembly. The driver assembly may include a handle, a drive bit portion, and a flexible drive shaft extending between the handle and the drive bit portion for manipulating a screw of an expandable or non-expandable screw box. The assembly may include one or more of an expandable screw box and/or a non-expandable screw box. The boxes may include one or more screws. The screw boxes may be joined by or include an attachment member, such as a plate and/or a circumferential cage.

In another general aspect, a cervical facet staple includes a curved staple base, at least two prongs attached to the bottom surface of the curved staple base, and an insertion member disposed on the top surface of the curved staple base.

Implementations of this aspect may include one or more of the following features. For example, the staple may include at least four prongs attached to the bottom surface of the curved staple base. The insertion member may include a threaded insert.

In another general aspect, an impaction tool for a cervical facet staple includes a handle, a stem attached to the handle, a plurality of wings for contacting the cervical facet staple, and an insertion member for coupling the cervical facet staple to the impaction tool.

Implementations of this aspect may include one or more of the following features. For example, the handle may include a flattened portion that can be struck by a mallet.

In another general aspect, a lumbar facet staple includes a pair of rotating arms, at least two prongs attached to the inner surfaces of the rotating arms, a plurality of spurs attached to one of the rotating arms, and a ratchet attached to one of the rotating arms. The rotating arms and prongs are rotated to a closed position to staple a lumbar facet joint.

BRIEF DESCRIPTION OF DRAWINGS

FIGS. 1A-D illustrate the Lumbar intervertebral screw box with one lateral oriented BDFT screw and one medially oriented two BDFT screw (Embodiment IA) in sagittal-oblique (FIG. 1A), superior perspective (FIG. 1B), inferior perspective (FIG. 1C) and exploded (FIG. 1D) views.

FIG. 1E illustrates the lumbar intervertebral expandable screw box with two lateral oriented BDFT screws (Embodiment IB; sagittal-oblique view).

FIGS. 2A-C illustrate the Lumbar intervertebral non-expandable screw box with two BDFT screws (Embodiment II) in lateral (FIG. 2A), oblique (FIG. 2B), and superior perspective (FIG. 2C) views.

FIG. 3 illustrates a superior oblique perspective view of left and right lumbar intervertebral non-expandable screw boxes with one BDFT screw (Embodiment III).

FIGS. 4A-B illustrate the horizontal intervertebral zero-profile mini-plate prior to insertion (FIG. 4A), and after insertion (FIG. 4B) into two non-expandable lumbar intervertebral screw boxes with two BDFT screws.

FIG. 4C illustrates two non-expandable lumbar intervertebral screw boxes with two screws within a large circumferential cage for anterior placement into the lumbar spine.

FIGS. 5A-C illustrate the positioning tool/screw guide/box expander in oblique perspective (FIG. 5A), lateral (FIG. 5B), and exploded (FIG. 5C) views.

FIG. 5D illustrates a superior oblique perspective view of the positioning tool/drill guide/box expander component.

FIGS. 5E-G illustrate the sequential steps (I-III) of the positioning tool/screw guide/box expander assembly. Step I (FIG. 5E), step II (FIG. 5F), and step III (FIG. 5G).

FIGS. 5H-I illustrate the positioning tool for impaction and placement of the non-expandable screw box with two transvertebral screws. Embodiment I has a rectangular positioning handle (FIG. 5H), and embodiment II has a circular positioning handle (FIG. 5I).

FIGS. 6A-B illustrate the insertion of expandable Lumbar bi-directional screw box with two BDFT screws into the Lumbar spine in oblique (FIG. 6A) and lateral (FIG. 6B) views.

FIGS. 7A-B illustrate the cervical facet staple (Embodiment I) in lateral (FIG. 7A) and oblique (FIG. 7B) views.

FIG. 8A-C illustrate the cervical facet staple (Embodiment II) in oblique (FIG. 8A), superior perspective (FIG. 8B) and inferior-oblique (FIG. 8C) views.

FIG. 9A illustrates the two-pronged cervical facet staple inserter/impactor (Embodiment I).

FIG. 9B illustrates the two-pronged cervical facet staple inserter/impactor inserted into the staple (Embodiment I).

FIG. 10A illustrates the four pronged cervical facet staple impactor (Embodiment II).

FIG. 10B illustrates the four pronged cervical facet staple impactor inserted into the cervical facet staple (Embodiment II).

FIG. 10C illustrates an inferior-oblique perspective view of the four-pronged cervical facet staple impactor (Embodiment II).

FIG. 11A illustrates placement of two-pronged cervical facet staples in a three-dimensional cervical spine.

FIG. 11B illustrates placement of four-pronged cervical facet staples in a three-dimensional cervical spine.

FIG. 11C illustrates modular placement of two and four pronged cervical facet staples in a three-dimensional cervical spine to achieve differing calibrated degrees of flexibility.

FIGS. 12 A-B illustrate the Lumbar facet joint staple with a calibrated ratcheting mechanism in opened (Figure A) and closed (Figure B) positions.

DETAILED DESCRIPTION OF THE INVENTION

1. The Medical Device

Referring to FIGS. 1-6, the above described problem can be solved in the thoracic and lumbar spine by insertion into the denuded intervertebral disc space multiple embodiments of screw box constructs with BDFT screws.

FIGS. 1A-D illustrate three-dimensional views of the Lumbar intervertebral expandable screw box 100 with two BDFT screws 101, 102; one lateral and one medially oriented (Embodiment IA). FIG. 1E illustrates a sagittal-oblique view of the lumbar intervertebral expandable screw box 120 with two lateral oriented BDFT screws 121, 122 (Embodiment IB).

The expandable box 100 consists of top and bottom triangular sliding bases 103, 104 (FIG. 1-D). The superior and inferior segments of the height/depth adjusting screw 105 are integrated and connected to the two separate top and bottom triangular bases 103, 104, respectively. By turning this adjusting screw 105 back and forth i.e. clock-wise, and counter clockwise, the sliding rails 106 of the top triangular base 103 (FIG. 1D) slide up and down the rail inserts 107 on the bottom triangular base 104 (FIG. 1D). This action will simultaneously alter the intervertebral height and depth of the screw box 100 allowing individualized custom fitting of the screw box 100 conforming to the dimensions of the disc space.

Transvertebral screw 101 penetrates the top base 103, and transvertebral screw 102 traverses the bottom base 104 of the screw box 100. The two screws 101, 102 traverse the screw box 100 in opposing directions, bi-directionally (whether they are lateral or medially oriented). The external edges of the triangular bases 103, 104 in contact with vertebral body surfaces include ridges 107. This facilitates the screw box's 100 incorporation into and fusion with the superior and inferior vertebral bodies (FIGS. 1A-E). Both top and bottom screw box bases 103, 104 are perforated with holes 108 to allow bone placement for fusion. The entire construct, furthermore, is hollow to allow bone filling. Hence this device functions as both an intervertebral bone fusion spacer and bi-directional transvertebral screw fusion device.

FIGS. 2A-C illustrate three-dimensional views of the Lumbar intervertebral non-expandable screw box 200 with two BDFT screws 201, 202 (Embodiment II). Screws 201 and 202 perforate and orient in opposing, superior and inferior directions. There are holes 208 and hollow spaces allowing packaging with bone. There are also holes which allow the traversal of screws. The superior and inferior edges include ridges 207 to facilitate integration and fusion with superior and inferior vertebral bodies. The expandable screw box 200 may include a screw insert 209 to attach a horizontal mini-plate (not shown). The self-contained internalized drill guides are at a 25 degree angle. The screw boxes can be designed with the internalized drill guides with different angles and/or different positions within the box.

FIG. 3 illustrates a three-dimensional view of left and right lumbar intervertebral non-expandable screw boxes 300a, 300b with one BDFT screw 301 or 302 (Embodiment III). It is roughly half the width of Embodiments I and II. Screw 301 is inserted into screw box 300a (left) and screw 302 is inserted into screw box 300b (right). There are holes 308 and hollow spaces allowing packing of bone to achieve biological fusion. The combined effect of one superior oriented and one inferior oriented screw fuses the superior and inferior vertebral bodies with small constructs. This also enables placement of larger dimension screws compared to embodiments I and II.

FIGS. 4A and B illustrate three-dimensional views of the horizontal intervertebral zero profile mini-plate 400 with two non-expandable lumbar intervertebral screw boxes 300a, 300b housing two BDFT screws 301, 302. FIG. 4A illustrates the perforations 401 within the plate 400 through which small plate securing screws 310 will be inserted to connect it to the built-in screw holes of the screw box 300a, 300b (FIG. 4B). The horizontal mini-plate 400 together with the top surfaces of left and right screw boxes 300a, 300b provide a physical barrier between the underlying bone placed beneath it (not illustrated), and the thecal sac and nerve roots above it (not illustrated).

FIG. 4C illustrates two screw boxes 300c, 300d within a circumferential cage 420 (2 in 1) construct which is designed for anterior placement into the lumbar spine. There are slots 308a, 308b for bone graft placement, both outside and inside the boxes. The circumferential cage 420 has perforations 401a for the placement of transvertebral screws (not shown).

FIGS. 5A-C illustrate three-dimensional views of the external drill/screw guide-box expander 500 which assists in screw trajectory and box expansion (embodiments IA-B). For embodiments II and III, the same instrument is utilized; however, an expanding Allen key component is not used.

The key components of this device include an Allen key 501, a spring 502, a handle 503, a gripper 504 and a screw

guide **505**. The Allen key **501** when inserted in the insertion **514** and turned, turns the screw adjuster (FIG. **5C**) which in turn regulates top and bottom triangular screw box base sliding, and hence box **200** width and depth. The griper **504** has griper prongs **506** which insert into grooves of the screw guide **505** and the screw box **200** (FIGS. **5A-D**) thus perfectly aligning them.

FIG. **5D** illustrates a superior oblique view of the screw guide **505** demonstrating insertions **509** for griper prong **506**, built-in trajectory guides **511**, **512** for insertions of screws **101** and **102**, and the Allen key **501**.

FIGS. **5E-G** illustrate three-dimensional views of the sequential steps necessary for the external guide assembly. FIG. **5E** illustrates the insertion of the Allen key **501** into the handle **503**. FIG. **5F** illustrates the insertion of the handle **503** through the spring **502** and griper **504**. FIG. **5G** illustrates insertion of the griper **504** into the screw guide **505**.

FIGS. **5H-1** illustrate three-dimensional views of a positioning tool **500a** for impaction and placement of two transvertebral screws **201**, **202** in the non-expandable screw box **200**. The driver assembly **550** consists of a screw driver **551**, a flexible shaft **552** and a square recess bit **553**. This facilitates turning the screws **201**, **202** into the bone. The flexible shaft **552** facilitates the avoidance of spinous processes which might hinder the screw driving if the shaft **552** were straight. The positioning tool **500a** can have a rectangular handle, Embodiment I (FIG. **5H**), or a circular handle, Embodiment II (FIG. **5I**). This serves to position the screw box within the intervertebral space, and screws **201**, **202** within the screw box. Once positioned, the screw box can be impacted by tapping the handle with a mallet (not shown). The positioning tool's **500a** griper handle inserts into the screw guide and the box, which maintains alignment.

FIG. **6A** illustrates a three-dimensional view of insertion of the construct (Embodiment I) into the lumbar intervertebral disc space.

FIG. **6B** illustrates a three dimensional lateral view of insertion of the construct (Embodiment I) into the disc space with short screws. Placement with longer screws would capture more bone.

FIGS. **7A** and **B** illustrate three-dimensional views of the two-pronged cervical facet staple **700** (Embodiment I). There is a staple base **701** which is contoured to align with the curved surface of the cervical facet joints. There is a superior impactor threaded insert **702**. An impactor can be screwed into this insert **702** and then impacted with a mallet. The two spikes **703**, **704** perforate the inferior and superior facets of the superior and inferior vertebral bodies hence leading to cervical facet joint fusion. The spikes can be designed with ridges and/or fishhooks to facilitate irreversible extraction.

FIGS. **8A-C** illustrate three-dimensional views of the four-pronged cervical facet staple **800** (Embodiment II). Likewise it has a staple base **805** contoured specifically for the surface of the facet joint. It also has an impactor insert **806**. The insertion of a device with four prongs **801-804** instead of two prongs further limits the degrees of motion of the joint hence making the fusion more rigid.

FIGS. **9 A-B** illustrate a three-dimensional view of the two-pronged cervical staple impactor **900**. It has a handle **901**, a stem **902**, and a screw insert **903** which can be screwed into the threaded staple insert. The impactor has two wings **904** which keep the staple base edges in place facilitating staple impaction. The handle **901** of the impactor **900** is broad in order to allow impaction by a mallet.

FIGS. **10A-C** illustrate three-dimensional views of the four-pronged cervical staple impactor **1000** (Embodiment

II). It has the same features as the two-pronged impactor **900**, except its wings **1004** are broader accommodating the broader staple base. The impactor **1000** also includes a handle **1001**, a stem **1002**, and an impact screw **1003**.

FIG. **11A** illustrates a three-dimensional view of placement of the two pronged cervical facet staple **700** into a cervical spine model having vertebral body **1103** and lamina **1104**. One staple **700** is perched on the joint **1101** prior to impaction. The other staple **700** is impacted.

FIG. **11B** illustrates a three-dimensional view of placement of the four pronged cervical facet staple **800** into a cervical spine pre and post impaction.

FIG. **11C** illustrates the concept of modularity and incremental diminution of movement of the joint by the modular placement of different combinations and permutations of varying numbers of two and four pronged cervical facet staples **700**, **800**. If one wishes to have the most flexible (least rigid) fusion, one would place a unilateral two pronged staple **700**. One can increase i.e. calibrate increasing degrees of rigidity by increasing the number of prongs penetrating the facet joints bilaterally. In FIG. **11C** each facet joint is fused using a total number of six prongs. One side this is accomplished by using three two pronged staples **700**, and on the other side using one four pronged staple **800** and one two pronged staple **700**. These two embodiments can be mixed and matched unilaterally or bilaterally to vary the degree of rigidity and conversely flexibility of fusion. The most flexible fusion at one level would be accomplished by one staple **700** (2 prongs). The highest level of rigidity would be achieved by placing two four pronged staples **800** on both sides totaling sixteen prongs. Intermediate degrees of relative joint motion can be modulated by insertion into the cervical facet joints staples in two-four prong increments from 2-16. Each additional prong further limits the degree of facet joint motion hence increasing rigidity, and conversely decreasing flexibility. Thus the novel modular use of these embodiments heralds an era of flexible cervical spine fusion.

FIGS. **12 A-B** illustrate a lumbar facet joint staple **1200** in open and closed positions and having staple prongs **1203**. This lumbar facet staple has been thoroughly described in our previous co-pending patent application Ser. No. 14/536,815, filed on Sep. 29, 2006, and Ser. No. 11/208,644, filed on Aug. 23, 2005, the relevant portion of each of which is hereby incorporated by reference hereinafter. The new improvement of this device includes a ratchet **1201**. The staple **1200** can be incrementally closed with increased ratcheting over increasing number of spurs **1202**. This achieves increasing calibrated levels of lumbar facet joint fusion, and conversely diminishing joint flexibility. This new designs further enhances the capacity to achieve flexible fusions in the lumbar spine.

2. The Surgical Method

Exemplary surgical steps for practicing one or more of the foregoing embodiments will now be described.

The posterior lumbar spine implantation of all the screw box **100**, **200**, **300** embodiments, with BDFT screws, and horizontal mini-plate **400** can be implanted via previously described posterior lumbar interbody fusion (PLIF) or posterior transforaminal lumbar interbody fusion (TLIF) procedures. The procedures can be performed open, microscopic, closed tubular or endoscopic. Fluoroscopic guidance can be used with any of these procedures.

After adequate induction of anesthesia, the patient is placed in the prone position. A midline incision is made for a PLIF procedure, and one or two parallel paramedian incisions or a midline incision is made for the TLIF procedure. For the PLIF, a unilateral or bilateral facet sparing

11

hemi-laminotomy is created to introduce screw box **100**, **200**, **300** embodiments I-III into the disc space, after it is adequately prepared.

For the TLIF procedure, after unilateral or bilateral dissection and drilling of the inferior articulating surface and the medial superior articulating facet the far lateral disc space is entered and a circumferential discectomy is performed. The disc space is prepared and the endplates exposed.

Then one screw box **100**, **200**, **300** of either embodiments I-III is placed on either right, left or both sides. Then another screw box of embodiments **100**, **200**, **300** I-III is placed on the contralateral side. For embodiment I the external screw guide **505**/box expander is attached to the screw box (FIGS. **5A-H**). First the Allen key **501** is screwed until the box conforms perfectly to the height and depth of the space. Then a pilot hole can be drilled or an awl can start a pilot hole in the vertebral bodies. Then a transvertebral screw is screwed into the vertebral body via the built-in box screw guides **505**. For difficult angles, an angled screw driver can be employed.

For embodiments II-III the same method is used for placing screws, except the Allen key **501** is not utilized in the absence of plate expansion.

If bilateral constructs have been inserted, bone is packed into the intervertebral space, as well as within the device. Then the horizontal intervertebral zero profile mini-plate **400** is slid beneath the thecal sac and is secured to both left and right screw boxes with small mini-plate screws **210** (FIGS. **4A-B**). This prevents bone intrusion into the thecal sac and hence possible nerve root compression.

FIGS. **6A** and **B** illustrate the process of insertion and final placement of the construct into the lumbar spine. The mini-plates **400** can come in different horizontal lengths and widths to accommodate different intra and inter-patient disc space diameters. The BDFT screws can come in different widths, lengths and thread designs.

The anterior thoracic and lumbar spine implantation of one, two or three screw box constructs **100**, **200**, **300** and BDFT screws can be performed in a similar manner to the posterior application. Likewise, a horizontal mini-plate **400** can be used to cap two or three screw box constructs **100**, **200**, **300** (one placed midline deeply, one placed left and one placed right, forming a triangulation). Alternatively two screw box constructs may be placed into a circumferential ring for anterior placement. Anterior placement of these devices can be performed into the L4/5 and L5/S1 spaces on the supine anesthetized patient via previously described open microscopic or endoscopic techniques. Once the disc space is exposed and discectomy and space preparation are performed, placement of one, two or three screw box embodiments **100**, **200**, **300** (I-III) or a 2 in I construct can be placed. The screw placement is facilitated by the internal screw guides, and different positioning tools ((FIG. **5**). A right angled screw driver and/or ratchet could alternatively be employed. A capping mini-plate **400** may be applied if desirable. The mechanism of screw placement and mini-plate **400** attachment are identical to what was described above.

The posterior placement of screw box constructs **100**, **200**, **300** alone or combined with horizontal mini-plates **400** into the thoracic spine can be performed via previously described transpedicular approaches; open or endoscopic. The anterior placement into the thoracic spine can be accomplished via a trans-thoracic approach. Once the disc space is exposed via either approach, any combination of the

12

above mention Embodiments (I-III) can be inserted. Engagement of the devices is identical to what was mentioned above.

For posterior placement of cervical facet staple **700**, **800** embodiments, after adequate induction of anesthesia the patient is flipped prone and his head and neck secured. A single midline or two para-median incisions are made for unilateral or bilateral or multilevel placement of staples. Ultimately the facet joint is exposed. Alternatively and preferably this can be performed percutaneously under fluoroscopic guidance with intravenous sedation. The staple **700**, **800** (Embodiments I or II) is loaded into the impactor **900**, **1000**. The staple **700**, **800** is placed on the two articulating cervical facets, and then impacted into the joint. To achieve modular calibrated fusion different combinations and permutations of cervical facet staples can be inserted ranging from a single unilateral two pronged staple providing a high degree of flexibility to a total of four bilaterally placed four pronged staples **800** (**16** prongs) leading to the highest degree of rigidity. Additional bone may or may not be placed in its vicinity to facilitate permanent and solid fusion. This procedure can be performed open, closed, percutaneously, tubular, endoscopically or microscopically. FIGS. **11 A-C** illustrates placement of the staples **700**, **800** in the cervical spine.

We have previously described surgical placement of the lumbar facet joint staple in our two co-pending patents. The surgical procedure for this device is identical to that which has been previously mentioned.

The present inventions may provide effective and safe techniques that overcome the problems associated with current transpedicular based cervical, thoracic and lumbar fusion technology, and for many degenerative stable and unstable spine disease. These inventions could replace much pedicle screw-based instrumentation in many but not all degenerative spine conditions.

The speed and simplicity of placement of cervical and lumbar facet staples, and placement of Lumbar screw box—BDFT constructs far exceeds that of current pedicle screw technology. Furthermore, these devices have markedly significantly decreased risk of misguided screw placement, and hence decreased risk of neural and vascular injury, and blood loss. In the lumbar spine BDFT screw constructs and facet staples could be applied modularly in different combinations to achieve different degrees of rigidity (flexibility). Patients having these devices would have decreased recovery and back to work time. These devices most likely lead to similar if not equal fusion with significantly less morbidity, and hence overall make them a major advance in the evolution of spinal instrumented technology leading to advances in the care of the spinal patient.

Another major novelty and advance is the introduction of simple and safe modular calibrated cervical flexible fusion. To our knowledge neither a similar device nor a similar mathematical concept of modular joint flexibility/fusion calibration has been postulated for the cervical spine or for any other articulating joint.

To our knowledge there have not been any previously described similar posterior lumbar and thoracic combined spacer and screw constructs. These devices can similarly be modified to stabilize bone fractures throughout the entire body. To our knowledge the description of zero to subzero profile anterior or posterior horizontal spinal plates which traverse the diameter of the disc space has not been previously described.

13

We claim:

1. A system comprising:

a tool assembly which comprises:

a first tool having a first proximal end and a first distal end with a first handle and a holder portion, the holder portion being positioned at the first distal end opposite of the first handle which is positioned at the first proximal end, and the holder portion having first and second engagement prongs positioned at the first distal end, wherein the first tool defines an adjusting tool passage through the first tool; and

a second adjusting tool having a second proximal end and a second distal end with a second handle positioned at the second proximal end, a screw engagement portion positioned at the second distal end, and a shaft extending from the second handle to the screw engagement portion, wherein the shaft of the second adjusting tool is sized with a smaller diameter than that of the adjusting tool passage such that the second adjusting tool can extend through the adjusting tool passage of the first tool; and

an expandable spinal implant sized and configured to be implanted in a human spine, the expandable spinal implant comprising a first expandable spinal implant structure, a second expandable spinal implant structure, and an adjusting screw having a screw head and a threaded portion, wherein the expandable spinal implant is configured to expand the first expandable spinal implant structure with respect to the second expandable spinal implant structure in response to turning of the adjusting screw, wherein the expandable spinal implant defines first and second tool engagement portions each defining a space that is sized, shaped, and configured for receiving the first and second engagement prongs of the first tool, wherein the first tool engagement portion is formed at a proximal end of a first side surface of the expandable spinal implant and the second tool engagement portion is formed at a proximal end of a second side surface of the expandable spinal implant, wherein the adjusting screw is positioned within the expandable spinal implant in a screw location such that the second adjusting tool can extend through the adjusting tool passage of the first tool to engage the screw head of the adjusting screw while the first and second engagement prongs of the first tool are engaged with the first and second tool engagement portions of the expandable spinal implant.

2. The system of claim 1, wherein the first expandable spinal implant structure is a first single integral structure and the second expandable spinal implant structure is a second single integral structure.

3. The system of claim 1, wherein the expandable spinal implant defines a longitudinal axis, wherein the first and second expandable spinal implant structures have first and second angled wedge surfaces that engage one another, wherein the adjusting screw is connected to the second expandable spinal implant structure so as to move the second expandable spinal implant structure along the longitudinal axis and slide the first angled wedge surface with respect to the second angled wedge surface to push the first expandable spinal implant structure in a direction that is substantially away from the longitudinal axis of the expandable spinal implant.

4. The system of claim 1, wherein the first expandable spinal implant structure defines a first angled wedge portion that comprises a first inwardly-facing rail and a second inwardly-facing rail, wherein a first inwardly-facing slot is

14

defined at a location adjacent the first inwardly-facing rail, wherein a second inwardly-facing slot is defined at a location adjacent the second inwardly-facing rail, wherein the second expandable spinal implant structure defines a second angled wedge portion that comprises a first outwardly-facing rail and a second outwardly-facing rail that faces outwardly in a direction opposite that of the first outwardly-facing rail, wherein a first outwardly-facing slot is defined at a location adjacent the first outwardly-facing rail, wherein a second outwardly-facing slot is defined at a location adjacent the second outwardly-facing rail, wherein the first expandable spinal implant structure is slidably-engaged with the second expandable spinal implant structure such that the first angled wedge portion engages the second angled wedge portion with the first inwardly-facing rail of the first expandable spinal implant structure positioned in the first outwardly-facing slot of the second expandable spinal implant structure, the second inwardly-facing rail of the first expandable spinal implant structure positioned in the second outwardly-facing slot of the second expandable spinal implant structure, the first outwardly-facing rail of the second expandable spinal implant structure positioned in the first inwardly-facing slot of the first expandable spinal implant structure, and the second outwardly-facing rail of the second expandable spinal implant structure positioned in the second inwardly-facing slot of the first expandable spinal implant structure.

5. The system of claim 1, and further comprising first and second anchors, wherein the expandable spinal implant comprises first and second anchor guides angled to guide the first and second anchors bidirectionally into first and second vertebral bodies;

wherein the first tool defines third and fourth anchor guides configured to align with the first and second anchor guides of the expandable spinal implant when the first and second engagement prongs are engaged with the first and second tool engagement portions so as to guide the first and second anchors through the third and fourth anchor guides into the first and second anchor guides.

6. A method of using the system of claim 1, the method comprising:

connecting the first tool to the expandable spinal implant with the first and second engagement prongs engaged with the first and second tool engagement portions;

implanting the expandable spinal implant into a disc space in the human spine via the first tool;

extending the second adjusting tool through the first tool to engage the adjusting screw of the expandable spinal implant; and

expanding the expandable spinal implant by turning the adjusting screw of the expandable spinal implant.

7. The system of claim 1, and further comprising bone graft material configured to be placed inside and outside of the expandable spinal implant.

8. The system of claim 1, the expandable spinal implant further comprising:

an implant proximal end and an implant distal end, the first and second tool engagement portions positioned at or near the implant proximal end, and the screw head of the adjusting screw is accessible at the implant proximal end from a proximal direction;

a plurality of ridges extending from a first vertebral body engagement surface, wherein at least some of the ridges are positioned on the first vertebral body engagement surface at or near the implant distal end;

15

first and second angled wedge surfaces, wherein rotation of the adjusting screw by the second adjusting tool drives relative motion of the first angled wedge surface with respect to the second angled wedge surface to expand the expandable spinal implant; and

first and second openings extending through the first vertebral body engagement surface and a second vertebral body engagement surface to a cavity within the expandable spinal implant, the cavity sized to receive bone material; and

wherein outer sides of the first and second engagement prongs are substantially straight when viewed from an angle perpendicular to the first vertebral body engagement surface when the first and second engagement prongs are engaged with the first and second tool engagement portions on the first and second side surfaces of the expandable spinal implant, and the second adjusting tool is engaged with the screw head of the adjusting screw.

9. A system comprising:

a tool assembly comprising:

a first tool having a first proximal end, a first distal end, and a first elongate body between the first proximal end and the first distal end, wherein the first tool defines a first tool axis from the first proximal end to the first distal end, wherein the first tool includes first and second engagement prongs positioned at the first distal end on opposite sides of the first tool axis, wherein the first tool defines an adjusting tool passage through the first tool; and

a second adjusting tool having a second proximal end and a second distal end, wherein the second adjusting tool includes a second handle positioned at the second proximal end, a screw engagement portion positioned at the second distal end, and a shaft extending from the second handle to the screw engagement portion, wherein the shaft of the second adjusting tool is sized with a smaller diameter than that of the adjusting tool passage such that the second adjusting tool can extend through the adjusting tool passage of the first tool; and

an expandable spinal implant sized and configured to be implanted in a human spine, the expandable spinal implant comprising a first expandable spinal implant structure defining a first vertebral body engagement surface sized and configured to engage a first vertebral body, a second expandable spinal implant structure defining a second vertebral body engagement surface sized and configured to engage a second vertebral body, and an adjusting screw having a screw head and a threaded shaft, wherein the expandable spinal implant is configured to expand the first expandable spinal implant structure with respect to the second expandable spinal implant structure in response to turning of the adjusting screw, wherein the expandable spinal implant defines first and second tool engagement portions sized, shaped, and configured for receiving the first and second engagement prongs of the first tool, wherein the first tool engagement portion is formed in first side surface of the expandable spinal implant and the second tool engagement portion is formed in a second side surface of the expandable spinal implant, wherein the adjusting screw is positioned within the expandable spinal implant in a screw location such that the second adjusting tool can extend through the adjusting tool passage of the first tool to engage the screw head of the adjusting screw while the first and second engagement

16

prongs of the first tool are engaged with the first and second tool engagement portions of the expandable spinal implant.

10. The system of claim 9, wherein the expandable spinal implant comprises an implant proximal end and an implant distal end, wherein the first and second tool engagement portions are formed as recessed surfaces and positioned at or near the implant proximal end, and wherein the screw head of the adjusting screw is accessible at the implant proximal end from a proximal direction.

11. The system of claim 9, wherein the expandable spinal implant comprises first and second angled wedge surfaces, wherein rotation of the adjusting screw by the second adjusting tool drives relative motion of the first angled wedge surface with respect to the second angled wedge surface to expand the expandable spinal implant.

12. The system of claim 9, wherein the first vertebral body engagement surface comprises a plurality of ridges extending from the first vertebral body engagement surface, wherein some of the ridges are positioned on the first vertebral body engagement surface at a distal end of the first vertebral body engagement surface.

13. The system of claim 9, wherein the first expandable spinal implant structure defines an end gap between the first and second side surfaces at a proximal end of the first vertebral body engagement surface and of the first expandable spinal implant structure such that first vertebral body engagement surface is open at a proximal end of the first expandable spinal implant structure, wherein the first vertebral body engagement surface comprises a plurality of ridges extending from the first vertebral body engagement surface, wherein some of the ridges are positioned on the first vertebral body engagement surface on a first side of the end gap and some of the ridges are positioned on the first vertebral body engagement surface on a second side of the end gap; and wherein the end gap causes the first vertebral body engagement surface to appear to be substantially U-shaped when viewed from an angle perpendicular to the first vertebral body engagement surface.

14. The system of claim 9, wherein the first and second expandable spinal implant structures each include a through-hole sized to allow for placement of bone material into the expandable spinal implant for fusion.

15. The system of claim 9, wherein the first expandable spinal implant structure is a first single integral structure and the second expandable spinal implant structure is a second single integral structure.

16. The system of claim 9, wherein outer sides of the first and second engagement prongs are substantially straight when viewed from an angle perpendicular to the first vertebral body engagement surface when the first and second engagement prongs are engaged with the first and second tool engagement portions on the first and second side surfaces of the expandable spinal implant.

17. A method of using the system of claim 9, the method comprising:

connecting the first tool to the expandable spinal implant with the first and second engagement prongs engaged with the first and second tool engagement portions;

implanting the expandable spinal implant into a disc space in the human spine via the first tool;

extending the second adjusting tool through the first tool to engage the adjusting screw of the expandable spinal implant; and

expanding the expandable spinal implant by turning the adjusting screw of the expandable spinal implant.

17

18. A system comprising:

a tool assembly comprising:

a first tool having a first proximal end, a first distal end, and a first elongate body between the first proximal end and the first distal end, wherein the first tool defines a first tool axis from the first proximal end to the first distal end, wherein the first tool includes a gripper having one or more engagement extensions positioned at the first distal end axially offset from the first tool axis, wherein the first tool defines an adjusting tool passage through the first tool; and

a second adjusting tool having a second proximal end and a second distal end, wherein the second adjusting tool includes a screw engagement portion positioned at the second distal end and a shaft extending from the second proximal end to the screw engagement portion, wherein the shaft of the second adjusting tool is sized with a smaller diameter than that of the adjusting tool passage such that the second adjusting tool can extend through and turn within the adjusting tool passage of the first tool; and

an expandable spinal implant sized and configured to be implanted in a human spine, the expandable spinal implant comprising a first expandable spinal implant structure defining a first engagement surface sized and configured to engage a first vertebral body, a second expandable spinal implant structure defining a second engagement surface sized and configured to engage a second vertebral body, and an adjusting screw having a tool engagement feature and a threaded portion, wherein the expandable spinal implant is configured to expand the first expandable spinal implant structure with respect to the second expandable spinal implant structure in response to turning of the adjusting screw, wherein the expandable spinal implant defines one or more tool engagement portions sized, shaped, and configured for engaging with the gripper of the first tool, wherein the adjusting screw is positioned within the expandable spinal implant in a screw location such that the second adjusting tool can extend through the adjusting tool passage of the first tool to engage the tool engagement feature of the adjusting screw while one or more engagement extensions of the first tool are engaged with the one or more tool engagement portions of the expandable spinal implant, wherein at least one of the one or more tool engagement portions of the expandable spinal implant is indented into one or more side surfaces of the expandable spinal implant such that the one or more engagement extensions of the gripper is positioned in the one or more tool engagement portions on the one or more side surfaces of the expandable spinal implant when the first tool is engaged with the expandable spinal implant.

18

19. The system of claim 18, wherein the expandable spinal implant comprises one or more substantially cylindrical side holes extending through one or more sides of the expandable spinal implant into an interior cavity of the expandable spinal implant and is sized and configured to allow for bone placement through the one or more substantially cylindrical side holes into the interior cavity, wherein the expandable spinal implant comprises an angled wedge portion having rails and slots configured to allow for relative movement and expansion of the expandable spinal implant during expansion of the expandable spinal implant, wherein the expandable spinal implant comprises an implant proximal end and an implant distal end, and wherein the tool engagement feature of the adjusting screw extends at least partially out of the implant proximal end in a proximal direction.

20. The system of claim 18, the expandable spinal implant further comprising:

an implant proximal end and an implant distal end, the one or more tool engagement portions positioned at or near the implant proximal end, and the tool engagement feature of the adjusting screw is accessible at the implant proximal end from a proximal direction, such that the second adjusting tool engages with the tool engagement feature of the adjusting screw at the implant proximal end;

a plurality of ridges extending from the first engagement surface, wherein at least some of the ridges are positioned on the first engagement surface at or near the implant distal end, said ridges configured to contact the first vertebral body;

first and second angled wedge surfaces, wherein rotation of the adjusting screw by the second adjusting tool drives relative motion of the first angled wedge surface with respect to the second angled wedge surface to expand the expandable spinal implant; and

first and second openings extending through the first and second engagement surfaces to a cavity within the expandable spinal implant, the cavity sized to receive bone material;

wherein the first expandable spinal implant structure is a first single integral structure and the second expandable spinal implant structure is a second single integral structure; and

wherein outer sides of the one or more engagement extensions are substantially straight when viewed from an angle perpendicular to the first engagement surface when the one or more engagement extensions are engaged with the one or more tool engagement portions on the one or more side surfaces of the expandable spinal implant, and the second adjusting tool is engaged with the tool engagement feature of the adjusting screw.

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